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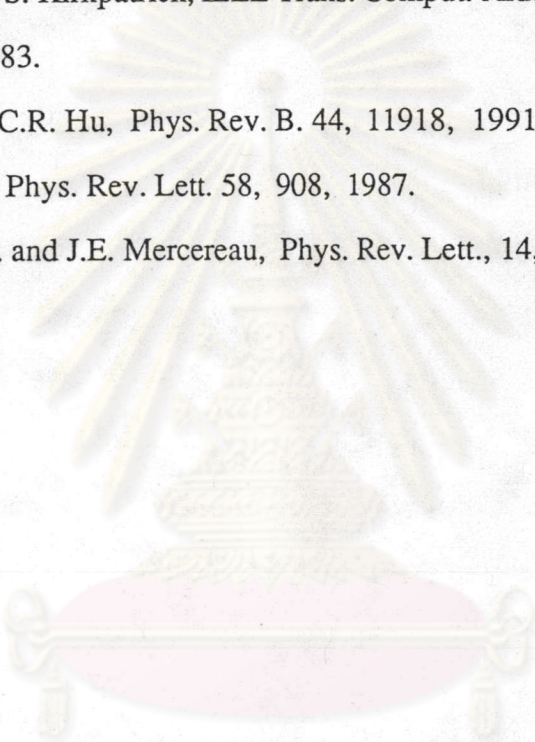
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## APPENDIX A

```

C .....
C  ## PROGRAM NAME:  GLIDI.FOR
C  ## Author:       Tanin Nutaro
C  ## Advisors:    Dr. Julian Poulter, Dr. David Ruffulo,
C                  Prof. Virulh Sa-yakanit.
C  ## Last update:  July/19/1992
C  ## Purpose:     minimizing the Gibbs free energy
C
C       $g = -|\psi|^2 + 0.5|\psi|^4 + \text{grad}(\psi)^2 + q^2\psi^2 + k^2(\text{curl}(q) - H)^2.$ 
C
C  ## Output file 1> GLIDI.out  :: psi, q, Hint data file.
C                      2> Est.out  :: initial input data and the best
C                                  free energy estimation.
C  Method of integration :: Trapezoid rule.
C .....
C  A1,A2 are the location points of the sample in coherence length unit
C  PSI   is the orderparameter
C  Q     is the supervelocity :(Q <- A+grad(phi))
C  HEXT  is the external magnetic field
C  Hint  is the internal magnetic field
C  N     is the number of strip for integration
C  KAPPA is the Ginzburg-Landau parameter(k)
C  TOL   is the tolerance
C
C      REAL *8 F,A1,A2,X,SUM,H,est,tol,z,psi,psi0,Q,Q0,HINT,HEXT,KAPPA
C      DIMENSION PSI(5009),psi0(5009),A(5009)
C      DIMENSION Q(5009),Q0(5009),HINT(5009)
C
C      INTEGER N,np
C  make a decision to start program from the real initial condition
C  or to read the previous data files(GLIDI.out & EST.out).
C
C      logical start
C      DATA N/100/
C      PRINT *, 'Input A1,A2'
C      READ *, A1,A2
C      print*, 'Input hext, kappa'
C      read*, hext,kappa
C      print*, 'Type 'T' if you want to start program'
C      print*, 'Type 'F' if you want to read data files'
C      read*, start
C      np=n+1
C
C  generate the coefficient of trapezoid rule for integration
C
C      do 1 i=2,np
1      a(i)=2.d0
C      a(1)=1.d0
C      a(np)=1.d0
C      h=(a2-a1)/dfloat(n)

```

```

C
    tol=1.d-1
    IF(start)then
C
C generate initial values for psi=1.0 ans q=0.0 everywhere.
C
    est=1.d50
    DO 5 i=1,np
        psi(i)=1.d0
        psi0(i)=psi(i)
        q(i)=0.d0
        q0(i)=q(i)
5    continue
    ELSE
C
C the second condition to read the previous data files
C
        open(7,file= 'est.out')
        read(7,*)est
        close(7)
        open(8,file= 'glldi.out')
        DO 12 j=1,np
            read(8,123)i,psi(j),q(j),hint(j)
            psi0(j)=psi(j)
12            q0(j)=q(j)
        close(8)
C
    ENDIF
C
C start counting
C
    kount=0
    kx=0
500    call func(psi,Q,np,tol)
C
    hint(1)=(q(2)-q(1))/h
    do 796 i=2,(np-1)
796    hint(i)=.5d0*(q(i+1)-q(i-1))/h
    hint(np)=(q(np)-q(np-1))/h
C
C SUM is the result of integration
    SUM=0.DO
    DO 2 I=1,NP
2    SUM=SUM+F(Psi,Q,NP,I,H,HEXT,KAPPA,hint(i))*a(i)
C
    SUM=H*SUM/2.d0
C
C if SUM is less than the previous one set kx to kx+1
    if(sum.lt.est)then
        kx=kx+1
        print *, 'better estimate ',sum,TOL
        kount=0
        est=sum
    DO 550 i=1,np
550    psi0(i)=psi(i)
        q0(i)=q(i)
        if(kx.eq.100)then
            kx=0

```

```

        open(7,file='est.out')
        write(7,*)est,A1,A2,n,kappa,hext,tol
        close(7)
        open(8,file='glldi.out')
        DO 600 i=1,np
600      write(8,123)i,psi(i),Q(I),HINT(I)
        close(8)
        endif
        else
C      set Kount to Kount+1
        kount=kount+1
        DO 700 i=1,np
        psi(i)=psi0(i)
700      q(i)=q0(i)
        endif
C
C      if more than 250 tries but can't get the better result,
C      change tolurence

        if(kount.gt.250)then
            TOL=0.5D0*TOL
            write(6,*)tol
            kount=0
        endif
C
C      until the TOL < 1.0e-6 :save the final result and the stop program
C
        IF (TOL .LT.1.D-6) then
            open(7,file='est.out')
            write(7,*)est,a1,a2,n,kappa,hext,tol
            close(7)
            open(8,file='glldi.out')
            DO 450 i=1,np
            write(8,123)i,psi(i),Q(i),HINT(I)
450          Format (I4,2x,3(f15.7,2x))
123          close(8)
            STOP
            ENDIF
            goto 500
            STOP
            END
        IF (TOL .LT.1.D-6) then
            open(7,file='est.out')
            write(7,*)est,a1,a2,n,kappa,hext,tol
            close(7)
            open(8,file='glldi.out')
            DO 450 i=1,np
            write(8,123)i,psi(i),Q(i),HINT(I)
450          Format (I4,2x,3(f15.7,2x))
123          close(8)
            STOP
            ENDIF
            goto 500
            STOP
            END
C      @@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@
        SUBROUTINE FUNC(PSI,Q,NP,TOL)
C      @@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@@
C      The main purpose of this subroutine is to adjust the value
C      of psi, q randomly
C
        REAL*8 A,B,tol,psi,Q,y,z
        REAL*4 URAND
        INTEGER SEED
        DIMENSION PSI(NP),Q(NP)
            save seed
        DATA SEED/0/
        rand=urand(seed)
        DO 3 I=1,NP
            if(rand.le..1)then
                y=psi(i+1)-2.0*psi(i)+psi(i-1)

```



```

      a=.25d0*y
      else
      A=2.D0*(URAND(SEED)-.5)*TOL
      endif
      PSI(I)=PSI(I)+A
      psi(1)=0.d0
      psi(np)=0.d0
3     IF(PSI(I).LT.0.D0)PSI(I)=0.D0
      DO 2 I=1,np
      if(rand.le..1.and.i.ne.1.and.i.ne.np) then
      z=q(i+1)-2.0*q(i)+q(i-1)
      a=.25d0*z
      else
      A=2.D0*(URAND(SEED)-.5)*TOL
      endif
2     Q(I)=Q(I)+A
      RETURN
      END

```

C

C

```
-----
      FUNCTION F(PSI,Q,NP,INDEX,H,HEXT,KAPPA, hint)

```

C

```
-----
C The main function for free energy calculation

```

```

      REAL*8 F,A,B,C,D,E,h,psi,Q,HEXT,KAPPA, curl, hint
      DIMENSION PSI(NP),Q(NP)
      A=PSI(INDEX)
      B=PSI(INDEX+1)
      D=Q(INDEX)
      E=Q(INDEX+1)
      if(index.eq.np)b=0.d0
      if(index.eq.np)e=d
      F=A*A
      C=(B-A)/H
      CURL=hint-HEXT
      F=-F+.5D0*F*F+C*C+D*D*F+KAPPA*KAPPA*CURL*CURL
      RETURN
      END

```

C

C

```
-----
      FUNCTION URAND(IY)

```

C

C

C

C

C

C

C

```

      REAL*8 HALFM
      SAVE IA,IC,M2,S
      DATA M2/0/,ITWO/2/
      IF(M2.NE.0)GOTO 20

```

C

C

C

```
      IF FIRST ENTRY, COMPUTE MACHINE INTEGER WORD LENGTH.

```

```
      M=1

```

```
10 M2=M

```

```
      M=ITWO*M2

```



```

IF(M.GT.M2)GOTO 10
HALFM=M2

```

```

C
C
C
C

```

```

      COMPUTE MULTIPLIER AND INCREMENT FOR LINEAR CONGRUENTIAL
      METHOD.

```

```

IA=8*IDINT(HALFM*DATAN(1.D0)/8.D0)+5
IC=2*IDINT(HALFM*(.5D0-DSQRT(3.D0)/6.D0))+1
MIC=(M2-IC)+M2

```

```

C
C
C

```

```

      S IS THE SCALE FACTOR FOR CONVERTING TO FLOATING POINT.

```

```

S=.5/HALFM

```

```

C
C
C

```

```

      COMPUTE NEXT RANDOM NUMBER

```

```

20 IY=IY*IA

```

```

C
C
C

```

```

      THE FOLLOWING STATEMENT IS FOR COMPUTERS WHICH DO NOT
      ALLOW INTEGER OVERFLOW ON ADDITION.

```

```

IF(IY.GT.MIC)IY=(IY-M2)-M2

```

```

C

```

```

IY=IY+IC

```

```

C
C
C

```

```

      THE FOLLOWING STATEMENT IS FOR COMPUTERS WHERE THE
      WORD LENGTH FOR ADDITION IS GREATER THAN FOR MULTIPLICATION.

```

```

IF(IY/2.GT.M2)IY=(IY-M2)-M2

```

```

C
C
C

```

```

      THE FOLLOWING STATEMENT IS FOR COMPUTERS WHERE INTEGER
      OVERFLOW AFFECTS THE SIGN BIT.

```

```

IF(IY.LT.0)IY=(IY+M2)+M2

```

```

C

```

```

URAND=FLOAT(IY)*S

```

```

RETURN

```

```

END

```

```

C

```

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## APPENDIX B

```

#include <math.h>
#include <stdio.h>
#define NROWS 19
#define NDIM 1121 /* Must be 3*NROWS^2 + 2*NROWS. */
#define FIRST_T 1
#define FRACTION 0.5
#define LAST_T 0.00001
/* Last modified :: 30 SEP 1992
   initial condition : psi[]          = 0.0
                      qx[] , qy[]    = 0.0
                      length          = 20.0
                      kappa           = 3.0
                      hext             = 0.5
   number of change points 300
*/

double hext, kappa, length;
double bests[NDIM+1], s[NDIM+1], ds[NDIM+1];
double ss;
unsigned long ia, ic, iy = 2847, m2 = 0;
long better;
int iff=0;

main()
{
  double dy, newfe, oldfe, qx ;
  int ans, i, j, select;
  long total;
  double update(), f();
  void printout(), previous();
  length=20.0;
  kappa=3.0;
  hext=0.50;

```

```

dy = length/((double)NROWS+1);
printf("\n This is the best program for simulated annealing \n");
printf("\n");
printf("enter 0 to start program from initial condition\n");
printf("    1 to read the previous data files \n");
scanf("%d", &select);
/*  select=1; */
    if(select == 1){ previous();}
    else {
        for (j=1;j<=NROWS*NROWS;j++) {
            s[j] = bests[j] = 0.5 ;
            range[j]=0.01;
        }
        for(i=(NROWS*NROWS)+1,qx= 0.0;i<=2*(NROWS*NROWS)+NROWS;i++) {
            bests[i] = s[i] = qx;
            if (!(i-NROWS*NROWS) % (NROWS+1))) qx = 0.0;
            range[i]=0.01;
        }
        for(i=2*(NROWS*NROWS)+NROWS+1;i<=3*(NROWS*NROWS)+2*
NROWS;i++){
            bests[i] = s[i] = 0.0 ;
            range[i]=0.01;
        }

        t = FIRST_T;
    }

/*  Start here */
    for(i=1; i<=NDIM+1; i++) { range[i] = 0.01 ;}
    better = 0;
    total = 0;
    oldfe = f(s);
    printf("oldfe =====%lf\n",f(s));
    for (t = FIRST_T;t >= LAST_T;) {
        for(better = 0;better <= 10*NDIM;) {

```

```

if (ans=update(&newfe,&oldfe,&t)) {
    printf("b ");
    oldfe = newfe;
    for (i=1;i<=NDIM;i++) bests[i] = s[i];
    better++;
    total++;
    if (!(better % 100)) {
        printf(" better = %d, total = %d, newfe = %lf\n",
            better,total,newfe);
        printout();
        sleep(2);
    }
} else {
    printf("w ");
    total++;
}
}
t*=FRACTION;
}
}

```

```

double update(newfe,oldfe,t)
double *newfe, *oldfe, *t;
{
    double de, random;
    int i, k;
    static long int seed=1278;

    double ran();
    double f();
    for(i=1;i<=300;i++){
        random=NDIM*ran(&seed);
        k=random+1;
        if(random+1-k<0.5){
            s[k]=bests[k]+range[k];
        } else {

```

```

    s[k]=bests[k]-range[k];
        }
if (k <= NROWS*NROWS) s[k] = fabs(s[k]);
    }

    *newfe = f(s);
/* printf("NeW fe of up date==%lf\n",f(s)); */
    de = *newfe - *oldfe;
    return(de < 0.0 || ran(&seed) < exp(-de/ *t));
}

/* RAN --> UNIFORM RANDOM DEVIATE BETWEEN 0 AND 1.

NEGATIVE ARGUMENT REINITIALIZES SEQUENCE.

THIS ROUTINE IS FAST, PORTABLE, AND FREE OF
SEQUENTIAL CORRELATIONS. OUTPUT IS LIMITED
INTEGERS DIVIDED BY 714,025.

from NUMERICAL RECIPES IN C (ran2)
*/

#define M      714025
#define IA     1366
#define IC     150889

double ran(idum)
long *idum;
{
    int j;
    void nrerror();

    if (*idum < 0 || iff == 0) {

        /* INITIALIZE SEQUENCE */

```

```

iff=1;
if ((*idum=(IC-(*idum)) % M) < 0) *idum = -(*idum);
for (j=1;j<=97;j++) {
    *idum=(IA*(*idum)+IC) % M;
    ir[j]=(*idum);
}
*idum=(IA*(*idum)+IC) % M;
iy=(*idum);
}

/* START HERE UNLESS INITIALIZING. */
/* RANDOMLY SELECT NUMBER FROM SEQUENCE. */

j=1 + 97.0*iy/M;
if (j > 97 || j < 1) nrerror("RAN: This cannot happen.");
iy=ir[j];
*idum=(IA*(*idum)+IC) % M;
ir[j]=(*idum);
return (double) iy/M;
}

double f(s)
double *s;
{
    double dq1dy, dq2dx, dsdx, dsdy, dx, dy, fe=0.0, *q1, *q2, feinc;
    double s2, qx2, qy2, sud, slr, qll, qlr, qul, qur, qle, que, qre;
    double curl1, curl2;
    int jx, jy, qxoffset, qyoffset, soffset;

    /* Set the pointer q to point to s+n. Thus the second half of
       the vector s is referred to as q.
    */

    q1 = s + NROWS*NROWS;
    q2 = s + 2*NROWS*NROWS + NROWS;

```

```
dy = dx = length / (double)(NROWS+1);
```

```
/* Contribution from lattice points: inside the boundary */
```

```
for (jy=1;jy<=NROWS;jy++) {
  soffset = (jy-1)*NROWS;
  qxoffset = (jy-1)*(NROWS+1);
  qyoffset = (jy-1)*NROWS;
  for (jx=1;jx<=NROWS;jx++) {
    s2 = s[soffset+jx]*s[soffset+jx];
    qx2 = (q1[qxoffset+jx]+q1[qxoffset+jx+1])
          * (q1[qxoffset+jx]+q1[qxoffset+jx+1]) / 4;
    qy2 = (q2[qyoffset+jx]+q2[qyoffset+jx+NROWS])
          * (q2[qyoffset+jx]+q2[qyoffset+jx+NROWS]) / 4;
    fe += -s2 + 0.5*s2*s2 + s2*qx2 + s2*qy2;
  }
}
```

```
/* Contribution from lattice points: on the boundary
```

```
Boundary conditions: s = 0 at boundary
```

```
*/
```

```
/* No contribution from boundary points! psi(edge) = 0. */
```

```
/* For Grad(psi)^2 : ((Sup-Sdown)/dy)^2 + ((Sright-Sleft)/dx)^2 */
```

```
for (jx=1; jx<=NROWS-1;jx++)
```

```
{
  for(jy=1;jy<=NROWS-1;jy++)
  {
    sud=((s[(jy)*NROWS+jx]-s[(jy-1)*NROWS+jx])/dy); /*sud=s(up-down)/dy*/
    slr=((s[(jy-1)*NROWS+jx+1]-s[(jy-1)*NROWS+jx])/dx);/*slr=sleft-right*/
    fe += (sud*sud) + (slr*slr);
  }
}
```

```
/* at the boundary: only edges */
```



```

        /* Lower edge */
for (jx=1; jx<=NROWS;jx++)
{
    sud=((s[jx]-0) / dy); /*sud=s(up-down)/dy*/
    fe += (sud*sud);
}

        /* Upper edge */

for (jx=1; jx<=NROWS;jx++)
{
    sud=((0-s[(NROWS-1)*NROWS+jx])/dy); /*sud=s(up-down)/dy*/
    fe += (sud*sud);
}

        /* Left edge */

for(jy=1;jy<=NROWS;jy++)
{
    slr=((s[(jy-1)*NROWS+1] - 0) / dx);/*slr=sleft-right*/
    fe += (slr*slr);
}

        /* Left edge */

for(jy=1;jy<=NROWS;jy++)
{
    slr=((0-s[(jy-1)*NROWS+NROWS]) / dx);/*slr=sleft-right*/
    fe += (slr*slr);
}

/* For the term k^2*(curlQ-hext)*/

for (jy=1;jy<=NROWS-1;jy++) {
    soffset = (jy-1)*NROWS;

```

```

qxoffset = (jy-1)*(NROWS+1);
qyoffset = jy*NROWS;
for (jx=1;jx<=NROWS-1;jx++) {
    curl1=(q2[qyoffset+jx+1]-q2[qyoffset+jx]) ;
    curl2= (q1[jy*(NROWS+1)+jx+1]-q1[qxoffset+jx+1]);
    feinc =kappa*kappa*(((curl1-curl2)/dx)-hext)*(((curl1-curl2)/dx)-hext);
    fe += feinc;
}
}
/* For the boundary */

/* Corners, upper edge, lower edge -> all 0 (Qx free to make them zero) */

fe *= dx * dy;
/* printf("f: fe = %12lf\n",fe); */
return(fe);
}

void printout()
{
FILE *fp_s,*fp_q1,*fp_q2,*fp_h,*fp_e;
int i,j,k,l;
double dx, hint, *s, *q1, *q2;

void nrrerror();
dx=length/(double)(NROWS+1);

/* printf(" %lf\n",f(p)); */

fp_s = fopen("psi3.dat","w");
fp_q1 = fopen("qone3.dat","w");
fp_q2 = fopen("qtwo3.dat","w");
fp_h = fopen("hint3.dat","w");

fp_e = fopen("free3.dat","a");
q1 = p + NROWS*NROWS;

```

```

q2 = p + 2*NROWS*NROWS + NROWS;

for (k=1;k<=NROWS;k++) {
    for (l=1;l<=NROWS;l++) {
        fprintf(fp_s," %4d %4d %12lf\n",k,l,bests[(l-1)*NROWS+k]);
    }
}
for (k=1;k<=NROWS+1;k++) {
    for (l=1;l<=NROWS;l++) {
        fprintf(fp_q1," %4d %4d %12lf\n",k,l,q1[(l-1)*(NROWS+1)+k]);
    }
}
for (k=1;k<=NROWS;k++) {
    for (l=1;l<=NROWS+1;l++) {
        fprintf(fp_q2," %4d %4d %12lf\n",k,l,q2[(l-1)*NROWS+k]);
    }
}
for (k=1;k<=NROWS-1;k++) {
    for (l=1;l<=NROWS-1;l++) {
        hint = (q2[l*NROWS+k+1]-q2[l*NROWS+k]
                -q1[l*(NROWS+1)+k+1]+q1[(l-1)*(NROWS+1)+k+1])/dx;
        fprintf(fp_h," %4d %4d %12lf\n",k,l,hint);
    }
}

    fprintf(fp_e,"%6d\t %lf\t %f\n",(better/100),f(p),t);
fclose(fp_s);
fclose(fp_q1);
fclose(fp_q2);
    fclose(fp_h);
    fclose(fp_e);
}

void previous()
{ FILE *fsc_s, *fsc_q1, *fsc_q2;
  int i, j, k, l;
  double *q1, *q2;

```

```

void nerror();


printf("Hello.\n");
printf("hereeeeeeee");
fflush(stdout);

fsc_s = fopen("psi3.dat","r");
fsc_q1 = fopen("qone3.dat","r");
fsc_q2 = fopen("qtwo3.dat","r");

for(k=1;k<=NROWS;k++){
  for(l=1;l<=NROWS;l++){
    for (i=1; i<= NROWS*NROWS; i++) {
      fscanf(fsc_s,"%4d%4d%12lf",&k,&l,&s[i]);
/* printf("s[%d] = %lf\n ", i, s[i]); */
      bests[i] = s[i];
    }
  }
}
for(k=1; k<=NROWS+1;k++){
  for(l=1; l<=NROWS; l++){
    for(i=(NROWS*NROWS)+1; i<=2*(NROWS*NROWS)+NROWS ; i++)
    {
      fscanf(fsc_q1,"%4d%4d%12lf",&k,&l,&s[i]);
/* printf("s[%d] = %lf\n", i,s[i]); */
      bests[i] = s[i];
    }
  }
}
for(k=1;k<=NROWS ; k++){
  for(l=1; l<=NROWS+1; l++){
    for(i=2*(NROWS*NROWS)+NROWS+1 ; i<= 3*(NROWS*NROWS)+(2*
NROWS); i++)
    {
      fscanf(fsc_q2,"%4d%4d%12lf",&k,&l,&s[i]);
      bests[i] = s[i];
    }
  }
}

```

```
/*      printf("s[%d] = %lf\n", i, s[i]); */  
    }  
    }  
    }  
fclose(fsc_s);  
fclose(fsc_q1);  
fclose(fsc_q2);  
printf("What is the last temperature\n");  
scanf("%lf",&t);  
}
```



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## CURRICULUM VITAE

Mr. Tanin Nutaro was born on September 10, 1961 in Surin. He received his B.Ed. degree in Physics from Srinakharinwirot Bangkok University in 1984. During his study for a M.Sc. degree in physics at Chulalongkorn University, he received a scholarship from the University Development Commission of the National Council (U.D.C.) and he worked as a research assistant for the high-temperature superconductivity project, which was supported by the Science and Technology Development Board (STDB).



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