



CHAPTER II

ON HYPERGEODESIC DIFFERENTIAL EQUATIONS

Notations :

2.1 ψ is an n -vector valued function of a real variable t
 $\psi^1(t), \psi^2(t), \dots, \psi^n(t)$ denoted by $\vec{\psi}(t) = (\psi^1(t), \dots, \psi^n(t))$.

$$2.2 \quad \frac{d\psi^i}{dt} = \dot{\psi}^i, \quad \frac{d^2\psi^i}{dt^2} = \ddot{\psi}^i, \quad \frac{d^3\psi^i}{dt^3} = \overset{\cdot\cdot\cdot}{\psi}^i, \quad i = 1, 2, \dots, n$$

$$2.3 \quad G_{j_1 \dots j_k}^i(\psi) \dot{\psi}^{j_1} \dots \dot{\psi}^{j_k} = \sum_{j_1=1}^n \dots \sum_{j_k=1}^n G_{j_1 \dots j_k}^i(\psi) \dot{\psi}^{j_1} \dots \dot{\psi}^{j_k} \quad \text{where}$$

$i = 1, \dots, n$ and $k = 1, 2, \dots$

$$2.4 \quad J_{k_1 \dots k_m}^i(\psi) \psi^{k_1} \dots \psi^{k_m} = \sum_{k_1=1}^n \dots \sum_{k_m=1}^n J_{k_1 \dots k_m}^i(\psi) \psi^{k_1} \dots \psi^{k_m} \quad \text{where}$$

$i = 1, 2, \dots, n$ and $m = 1, 2, 3, \dots$

$$2.5 \quad L_\ell^i(\psi) t^\ell = \sum_{\ell=1}^{\infty} L_\ell^i(\psi) t^\ell \quad \text{where } i = 1, 2, \dots, n$$

$$2.6 \quad K_{k_1 \dots k_m}^i(\psi) \psi^{k_1} \dots \psi^{k_m} \dot{\psi}^{j_1} \dots \dot{\psi}^{j_k} = \sum_{k_1=1}^n \dots \sum_{k_m=1}^n \sum_{j_1=1}^n \dots$$

$$\sum_{j_k=1}^n K_{k_1 \dots k_m}^i(\psi) \psi^{k_1} \dots \psi^{k_m} \dot{\psi}^{j_1} \dots \dot{\psi}^{j_k}$$

where $i = 1, 2, \dots, n$, $m = 1, 2, \dots$, $k = 1, 2, \dots$

$$2.7 \quad M_{j_1 \dots j_k}^i (\psi) \dot{\psi}^{j_1} \dots \dot{\psi}^{j_k t^\ell} = \sum_{j_1=1}^n \dots \sum_{j_k=1}^n \sum_{\ell=1}^{\infty} M_{j_1 \dots j_k}^i (\psi) \dot{\psi}^{j_1} \dots \dot{\psi}^{j_k t^\ell}$$

where $i = 1, \dots, n$ and $k = 1, 2, \dots$

$$2.8 \quad N_{k_1 \dots k_m}^i (\psi) \dot{\psi}^{..k_1} \dots \dot{\psi}^{..k_m t^\ell} = \sum_{k_1=1}^n \dots \sum_{k_m=1}^n \sum_{\ell=1}^{\infty} N_{k_1 \dots k_m}^i (\psi) \dot{\psi}^{..k_1} \dots \dot{\psi}^{..k_m t^\ell}$$

where $i = 1, \dots, n$ and $m = 1, 2, \dots$

$$2.9 \quad R_{k_1 \dots k_m}^i (\psi) \dot{\psi}^{..k_1} \dots \dot{\psi}^{..k_m} \dot{\psi}^{j_1} \dots \dot{\psi}^{j_k t^\ell} = \sum_{k_1=1}^n \dots \sum_{k_m=1}^n \sum_{j_1=1}^n \dots$$

$$\dots \sum_{j_k=1}^n \sum_{\ell=1}^{\infty} R_{k_1 \dots k_m}^i (\psi) \dot{\psi}^{..k_1} \dots \dot{\psi}^{..k_m} \dot{\psi}^{j_1} \dots \dot{\psi}^{j_k t^\ell}$$

where $i = 1, \dots, n$ and $m = 1, 2, \dots$ and $k = 1, 2, \dots$

$$2.10 \quad u^{p_1} u^{p_2} \dots u^{p_k} v^{q_1} \dots v^{q_\ell} \frac{\partial^{k+\ell} \psi^i (p, \alpha u, \alpha v, t)}{\partial u^{p_1} \dots \partial u^{p_k} \partial v^{q_1} \dots \partial v^{q_\ell}}$$

$$= \sum_{p_1=1}^n \dots \sum_{p_k=1}^n \sum_{q_1=1}^n \dots \sum_{q_\ell=1}^n u^{p_1} \dots u^{p_k} v^{q_1} \dots v^{q_\ell} \frac{\partial^{k+\ell} \psi^i (p, \alpha u, \alpha v, t)}{\partial u^{p_1} \dots \partial u^{p_k} \partial v^{q_1} \dots \partial v^{q_\ell}}$$

where $k = 1, 2, \dots$ and $\ell = 1, 2, \dots$

Notations in 2.3 to 2.10 are called Einstein Summation convention.



Introduction to Theorem

$$\Pi_1(x^1, \dots, x^n, x^{n+1}, \dots, x^{2n}, x^{2n+1}, \dots, x^{3n}, x^{3n+1}) = (x^1, \dots, x^n)$$

$$\Pi_2(x^1, \dots, x^n, x^{n+1}, \dots, x^{2n}, x^{2n+1}, \dots, x^{3n}, x^{3n+1}) = (x^{n+1}, \dots, x^{2n})$$

$$\Pi_3(x^1, \dots, x^n, x^{n+1}, \dots, x^{2n}, x^{2n+1}, \dots, x^{3n}, x^{3n+1}) = (x^{2n+1}, \dots, x^{3n})$$

$$\Pi_4(x^1, \dots, x^n, x^{n+1}, \dots, x^{2n}, x^{2n+1}, \dots, x^{3n}, x^{3n+1}) = x^{3n+1}$$

Let Ω be a connected open set of \mathbb{R}^{3n+1} such that

$$\forall \vec{p} \in \Pi_1(\Omega) \quad (\vec{p}, \vec{u}, \vec{v}, 0) \in \Omega \quad \forall \vec{u}, \vec{v} \in \mathbb{R}^n.$$

Let $H : \Omega \rightarrow \mathbb{R}^n$ be analytic. H determines a third order differential equation $\psi^{i\prime\prime\prime} = H^i(\vec{\psi}, \dot{\vec{\psi}}, \ddot{\vec{\psi}}, t)$ where $\vec{\psi} = (\psi^1, \dots, \psi^n)$, $\dot{\vec{\psi}} = (\dot{\psi}^1, \dots, \dot{\psi}^n)$, and $\ddot{\vec{\psi}} = (\ddot{\psi}^1, \dots, \ddot{\psi}^n)$.

Given $\vec{p} \in \Pi_1(\Omega)$, $\vec{u}, \vec{v} \in \mathbb{R}^n$ we take the initial conditions to be

$$\vec{\psi}(0) = \vec{p} = (p^1, \dots, p^n) \in \Pi_1(\Omega)$$

$$\dot{\vec{\psi}}(0) = \vec{u} = (u^1, \dots, u^n) \in \mathbb{R}^n$$

$$\ddot{\vec{\psi}}(0) = \vec{v} = (v^1, \dots, v^n) \in \mathbb{R}^n.$$

By the Fundamental Theorem of Ordinary Differential Equations, there exists an open subset U of Ω in $\Pi_4(\Omega)$ and a unique function

$\Phi_{\vec{p}, \vec{u}, \vec{v}} : U \rightarrow \Pi_1(\Omega)$ which is a solution to the differential equation $\psi^{i\prime\prime\prime} = H^i(\vec{\psi}, \dot{\vec{\psi}}, \ddot{\vec{\psi}}, t)$ with the above given initial conditions.

Write $\phi_{\vec{p}, \vec{u}, \vec{v}}^i(t) = \psi(\vec{p}, \vec{u}, \vec{v}, t)$ for all $t \in U$.

Let $\alpha \in \mathbb{R}$, define $\vec{\alpha u} = (\alpha u^1, \dots, \alpha u^n)$ and $\vec{\alpha v} = (\alpha^2 v^1, \dots, \alpha^2 v^n)$ as was done in chapter I.

Theorem 2.11 Suppose we have an analytic third order differential equation $\psi^{i\prime\prime\prime} = H^i(\vec{\psi}, \dot{\vec{\psi}}, \ddot{\vec{\psi}}, t)$ for $i = 1, \dots, n$ with initial conditions $\psi^i(\vec{p}, \vec{u}, \vec{v}, 0) = p^i$, $\dot{\psi}^i(\vec{p}, \vec{u}, \vec{v}, 0) = u^i$, $\ddot{\psi}^i(\vec{p}, \vec{u}, \vec{v}, 0) = v^i$ whose solution $\psi^i(\vec{p}, \vec{u}, \vec{v}, t)$ satisfies the functional equation

$$\psi^i(\vec{p}, \vec{\alpha u}, \vec{\alpha v}, t) = \psi^i(\vec{p}, \vec{u}, \vec{v}, f(\alpha, t))$$

where $f: W \rightarrow \mathbb{R}$ is an analytic function on W a neighbourhood of $(0, 0)$ in \mathbb{R}^2 , $(\vec{p}, \vec{\alpha u}, \vec{\alpha v}, t) \in \Omega \subseteq \mathbb{R}^{3n+1}$, $(\alpha, t) \in W$.

Furthermore, assume that $f(\alpha, 0) = f(0, t) = 0 \quad \forall (\alpha, t) \in W$. Then the differential equation must be of the form

$$\psi^{i\prime\prime\prime} = G_{j_1 j_2 j_3}^i(\vec{\psi}) \psi^{j_1} \psi^{j_2} \psi^{j_3} + K_{k_1 j_1}^i(\vec{\psi}) \psi^{k_1} \psi^{j_1} \quad \text{and } f(\alpha, t)$$

must equal αt .

Proof Since $\psi^{i\prime\prime\prime} = H^i(\vec{\psi}, \dot{\vec{\psi}}, \ddot{\vec{\psi}}, t)$ is analytic, by hypothesis we can write $H^i(\vec{\psi}, \dot{\vec{\psi}}, \ddot{\vec{\psi}}, t)$ as a power series.

$$\begin{aligned} H^i(\vec{\psi}, \dot{\vec{\psi}}, \ddot{\vec{\psi}}, t) &= G^i(\vec{\psi}) + G_{j_1}^i(\vec{\psi}) \psi^{j_1} + G_{j_1 j_2}^i(\vec{\psi}) \psi^{j_1} \psi^{j_2} + \dots \\ &+ J_{k_1}^i(\vec{\psi}) \psi^{k_1} + J_{k_1 k_2}^i(\vec{\psi}) \psi^{k_1} \psi^{k_2} + \dots + L_{\ell}^i(\vec{\psi}) t^{\ell} \\ &+ K_{k_1 j_1}^i(\vec{\psi}) \psi^{k_1} \psi^{j_1} + K_{k_1 j_1 j_2}^i(\vec{\psi}) \psi^{k_1} \psi^{j_1} \psi^{j_2} + \dots \end{aligned}$$

$$\begin{aligned}
 &+ K_{k_1 k_2 j_1}^i (\vec{\psi}) \psi_1^{k_1} \psi_2^{k_2} \psi_1^{j_1} + K_{k_1 k_2 j_1 j_2}^i (\vec{\psi}) \psi_1^{k_1} \psi_2^{k_2} \psi_1^{j_1} \psi_2^{j_2} + \dots \\
 &+ M_{j_1 \ell}^i (\vec{\psi}) \psi_1^{j_1} t^\ell + M_{j_1 j_2 \ell}^i (\vec{\psi}) \psi_1^{j_1} \psi_2^{j_2} t^\ell + \dots \\
 &+ N_{k_1 \ell}^i (\vec{\psi}) \psi_1^{k_1} t^\ell + N_{k_1 k_2 \ell}^i (\vec{\psi}) \psi_1^{k_1} \psi_2^{k_2} t^\ell + \dots \\
 &+ R_{k_1 j_1 \ell}^i (\vec{\psi}) \psi_1^{k_1} \psi_1^{j_1} t^\ell + R_{k_1 j_1 j_2 \ell}^i (\vec{\psi}) \psi_1^{k_1} \psi_1^{j_1} \psi_2^{j_2} t^\ell \\
 &+ \dots \\
 &+ R_{k_1 k_2 j_1 \ell}^i (\vec{\psi}) \psi_1^{k_1} \psi_2^{k_2} \psi_1^{j_1} t^\ell + R_{k_1 k_2 j_1 j_2 \ell}^i (\vec{\psi}) \psi_1^{k_1} \psi_2^{k_2} \psi_1^{j_1} \psi_2^{j_2} t^\ell \\
 &+ \dots
 \end{aligned}$$

For convenience, we will replace \vec{p} by p , \vec{u} by u , and \vec{v} by v and $f(\alpha, t)$ by f .

Since $\psi^i(p, \alpha u, \alpha v, t) = \psi^i(p, u, v, f)$ $i = 1, \dots, n \forall p \in \Pi_1(\Omega)$
 $u, v \in \mathbb{R}^n, \alpha, t \in \mathbb{R}$ differentiate this equation with respect to t , we get

$$(2.11-1) \quad \dot{\psi}^i(p, \alpha u, \alpha v, t) = \dot{\psi}^i(p, u, v, f) f_t \quad \text{where } f_t = \frac{\partial f}{\partial t}.$$

let $t = 0$ then (2.11-1) becomes

$$\alpha u^i = u^i f_t(\alpha, 0) \quad \text{implying that } f_t(\alpha, 0) = \alpha$$

differentiate (2.11-1) with respect to t , we get

$$(2.11-2) \quad \ddot{\psi}^i(p, \alpha u, \alpha v, t) = \ddot{\psi}^i(p, u, v, f) f_t^2 + \dot{\psi}^i(p, u, v, f) f_{tt}$$

let t in (2.11-2) be zero,

$$\alpha^2 v^i = v^i \alpha^2 + u^i f_{tt}(\alpha, 0) \text{ implying that } f_{tt}(\alpha, 0) = 0.$$

Again, differentiate (2.11-2) with respect to t .

$$(2.11-3) \quad \ddot{\psi}^i(p, \alpha u, \alpha v, t) = \ddot{\psi}^i(p, u, v, f) f_t^3 + \dot{\psi}^i(p, u, v, f) f_{ttt} \\ + 3f_t f_{tt} \ddot{\psi}^i(p, u, v, f)$$

Substitute (2.11-3) by the power series expansion, this gives

$$G^i(\psi(p, \alpha u, \alpha v, t)) + G_{j_1}^i(\psi(p, \alpha u, \alpha v, t)) \dot{\psi}^{j_1}(p, \alpha u, \alpha v, t) \\ + G_{j_1 j_2}^i(\psi(p, \alpha u, \alpha v, t)) (\dot{\psi}^{j_1} \dot{\psi}^{j_2})(p, \alpha u, \alpha v, t) + \dots \\ + J_{k_1}^i(\psi(p, \alpha u, \alpha v, t)) \ddot{\psi}^{k_1}(p, \alpha u, \alpha v, t) \\ + J_{k_1 k_2}^i(\psi(p, \alpha u, \alpha v, t)) (\ddot{\psi}^{k_1} \ddot{\psi}^{k_2})(p, \alpha u, \alpha v, t) + \dots \\ + L_{\ell}^i(\psi(p, \alpha u, \alpha v, t)) t^{\ell} + K_{k_1 j_1}^i(\psi(p, \alpha u, \alpha v, t)) (\ddot{\psi}^{k_1} \dot{\psi}^{j_1})(p, \alpha u, \alpha v, t) \\ + K_{k_1 j_1 j_2}^i(\psi(p, \alpha u, \alpha v, t)) (\ddot{\psi}^{k_1} \dot{\psi}^{j_1} \dot{\psi}^{j_2})(p, \alpha u, \alpha v, t) + \dots \\ + K_{k_1 k_2 j_1}^i(\psi(p, \alpha u, \alpha v, t)) (\ddot{\psi}^{k_1} \ddot{\psi}^{k_2} \dot{\psi}^{j_1})(p, \alpha u, \alpha v, t) \\ + K_{k_1 k_2 j_1 j_2}^i(\psi(p, \alpha u, \alpha v, t)) (\ddot{\psi}^{k_1} \ddot{\psi}^{k_2} \dot{\psi}^{j_1} \dot{\psi}^{j_2})(p, \alpha u, \alpha v, t) + \dots \\ + M_{j_1 \ell}^i(\psi(p, \alpha u, \alpha v, t)) \dot{\psi}^{j_1}(p, \alpha u, \alpha v, t) t^{\ell} \\ + M_{j_1 j_2 \ell}^i(\psi(p, \alpha u, \alpha v, t)) (\dot{\psi}^{j_1} \dot{\psi}^{j_2})(p, \alpha u, \alpha v, t) t^{\ell} + \dots \\ + N_{k_1 \ell}^i(\psi(p, \alpha u, \alpha v, t)) \ddot{\psi}^{k_1}(p, \alpha u, \alpha v, t) t^{\ell}$$

$$\begin{aligned}
& + N_{k_1 k_2}^i (\psi(p, \alpha u, \alpha v, t)) (\psi_{\psi^1 \psi^2}^{\dots k_1 \dots k_2})(p, \alpha u, \alpha v, t) t^\ell + \dots \\
& + R_{k_1 j_1}^i (\psi(p, \alpha u, \alpha v, t)) (\psi_{\psi^1 \psi^{j_1}}^{\dots k_1 \dots j_1})(p, \alpha u, \alpha v, t) t^\ell \\
& + R_{k_1 j_1 j_2}^i (\psi(p, \alpha u, \alpha v, t)) (\psi_{\psi^1 \psi^{j_1} \psi^{j_2}}^{\dots k_1 \dots j_1 \dots j_2})(p, \alpha u, \alpha v, t) t^\ell + \dots \\
& + R_{k_1 k_2 j_1}^i (\psi(p, \alpha u, \alpha v, t)) (\psi_{\psi^1 \psi^2 \psi^{j_1}}^{\dots k_1 \dots k_2 \dots j_1})(p, \alpha u, \alpha v, t) t^\ell \\
& + R_{k_1 k_2 j_1 j_2}^i (\psi(p, \alpha u, \alpha v, t)) (\psi_{\psi^1 \psi^2 \psi^{j_1} \psi^{j_2}}^{\dots k_1 \dots k_2 \dots j_1 \dots j_2})(p, \alpha u, \alpha v, t) t^\ell + \dots \\
= & f_t^3 G^i (\psi(p, u, v, f)) + f_t^3 G_{j_1}^i (\psi(p, u, v, f)) \psi^{j_1} (p, u, v, f) \\
& + f_t^3 G_{j_1 j_2}^i (\psi(p, u, v, f)) (\psi_{\psi^{j_1} \psi^{j_2}}^{\dots j_1 \dots j_2})(p, u, v, f) + \dots \\
& + f_t^3 J_{k_1}^i (\psi(p, u, v, f)) \psi^{i_1} (p, u, v, f) \\
& + f_t^3 J_{k_1 k_2}^i (\psi(p, u, v, f)) (\psi_{\psi^1 \psi^2}^{\dots k_1 \dots k_2})(p, u, v, f) + \dots \\
& + L_\ell^i (\psi(p, u, v, f)) f_t^3 t^\ell + f_t^3 K_{k_1 j_1}^i (\psi(p, u, v, f)) (\psi_{\psi^1 \psi^{j_1}}^{\dots k_1 \dots j_1})(p, u, v, f) \\
& + f_t^3 K_{k_1 j_1 j_2}^i (\psi(p, u, v, f)) (\psi_{\psi^1 \psi^{j_1} \psi^{j_2}}^{\dots k_1 \dots j_1 \dots j_2})(p, u, v, f) + \dots \\
& + f_t^3 K_{k_1 k_2 j_1}^i (\psi(p, u, v, f)) (\psi_{\psi^1 \psi^2 \psi^{j_1}}^{\dots k_1 \dots k_2 \dots j_1})(p, u, v, f) \\
& + f_t^3 K_{k_1 k_2 j_1 j_2}^i (\psi(p, u, v, f)) (\psi_{\psi^1 \psi^2 \psi^{j_1} \psi^{j_2}}^{\dots k_1 \dots k_2 \dots j_1 \dots j_2})(p, u, v, f) \\
& + \dots + f_t^3 M_{j_1}^i (\psi(p, u, v, f)) \psi^{j_1} (p, u, v, f) t^\ell
\end{aligned}$$

$$\begin{aligned}
& + f_t^3 M_{j_1 j_2}^i (\psi(p, u, v, f)) (\psi^{j_1} \psi^{j_2}) (p, u, v, f) t^\ell + \dots \\
& + f_t^3 N_{k_1}^i (\psi(p, u, v, f)) \psi^{k_1} (p, u, v, f) t^\ell \\
& + f_t^3 N_{k_1 k_2}^i (\psi(p, u, v, f)) (\psi^{k_1} \psi^{k_2}) (p, u, v, f) t^\ell + \dots \\
& + f_t^3 R_{k_1 j_1}^i (\psi(p, u, v, f)) (\psi^{k_1} \psi^{j_1}) (p, u, v, f) t^\ell \\
& + f_t^3 R_{k_1 j_1 j_2}^i (\psi(p, u, v, f)) (\psi^{k_1} \psi^{j_1} \psi^{j_2}) (p, u, v, f) t^\ell + \dots \\
& + f_t^3 R_{k_1 k_2 j_1}^i (\psi(p, u, v, f)) (\psi^{k_1} \psi^{k_2} \psi^{j_1}) (p, u, v, f) t^\ell \\
& + f_t^3 R_{k_1 k_2 j_1 j_2}^i (\psi(p, u, v, f)) (\psi^{k_1} \psi^{k_2} \psi^{j_1} \psi^{j_2}) (p, u, v, f) t^\ell \\
& + \dots + \psi^i(p, u, v, f) f_{ttt} + 3f_t f_{tt} \psi^i(p, u, v, f).
\end{aligned}$$



let $t = 0$, then

$$\begin{aligned}
& G^i(p) + G_{j_1}^i(p) \alpha u^{j_1} + G_{j_1 j_2}^i(p) \alpha^2 u^{j_1 j_2} + \dots + J_{k_1}^i(p) \alpha^2 v^{k_1} \\
& + J_{k_1 k_2}^i(p) \alpha^4 v^{k_1 k_2} + \dots + K_{k_1 j_1}^i(p) \alpha^3 v^{k_1} u^{j_1} + K_{k_1 j_1 j_2}^i(p) \alpha^4 v^{k_1} u^{j_1 j_2} + \dots \\
& + K_{k_1 k_2 j_1}^i(p) \alpha^5 v^{k_1 k_2} u^{j_1} + K_{k_1 k_2 j_1 j_2}^i(p) \alpha^6 v^{k_1 k_2} u^{j_1 j_2} + \dots \\
& = \alpha^3 G^i(p) + \alpha^3 G_{j_1}^i(p) u^{j_1} + \alpha^3 G_{j_1 j_2}^i(p) u^{j_1 j_2} + \dots + \alpha^3 J_{k_1}^i(p) v^{k_1} \\
& + \alpha^3 J_{k_1 k_2}^i(p) v^{k_1 k_2} + \dots + \alpha^3 K_{k_1 j_1}^i(p) v^{k_1} u^{j_1} + \alpha^3 K_{k_1 j_1 j_2}^i(p) v^{k_1} u^{j_1 j_2} + \dots \\
& + \alpha^3 K_{k_1 k_2 j_1}^i(p) v^{k_1 k_2} u^{j_1} + \alpha^3 K_{k_1 k_2 j_1 j_2}^i(p) v^{k_1 k_2} u^{j_1 j_2} + \dots + u^i f_{ttt}
\end{aligned}$$

we get

$$\begin{aligned}
 & (1-\alpha^3)G^i(p) + (\alpha-\alpha^3)G_{j_1}^i(p)u^{j_1} + (\alpha^2-\alpha^3)G_{j_1 j_2}^i(p)u^{j_1 j_2} \\
 & + (\alpha^3-\alpha^3)G_{j_1 j_2 j_3}^i(p)u^{j_1 j_2 j_3} + \dots + (\alpha^2-\alpha^3)J_{k_1}^i(p)v^{k_1} \\
 & + (\alpha^4-\alpha^3)J_{k_1 k_2}^i(p)v^{k_1 k_2} + \dots + (\alpha^3-\alpha^3)K_{k_1 j_1}^i(p)v^{k_1 j_1} \\
 & + (\alpha^4-\alpha^3)K_{k_1 j_1 j_2}^i(p)v^{k_1 j_1 j_2} + (\alpha^5-\alpha^3)K_{k_1 k_2 j_1}^i(p)v^{k_1 k_2 j_1} \\
 & + (\alpha^6-\alpha^3)K_{k_1 k_2 j_1 j_2}^i(p)v^{k_1 k_2 j_1 j_2} + \dots \\
 & = u^i f_{ttt}(\alpha, 0)
 \end{aligned}$$

Choose $\alpha = \alpha_0$, $\alpha_0 \neq \pm 1, 0$ then

$$G^i(p) = 0, \quad G_{j_1}^i(p) = \frac{f_{ttt}(\alpha_0, 0)\delta_{j_1}^i}{\alpha_0 - \alpha_0^3} = c \text{ constant independent of } \alpha_0$$

$$\text{where } \delta_{j_1}^i = \begin{cases} 0, & i \neq j_1 \\ 1, & i = j_1 \end{cases}$$

$$G_{j_1 j_2 j_3}^i(p) \text{ arbitrary } G_{j_1 \dots j_n}^i(p) = 0 \quad \forall n \geq 2, \text{ all } J\text{'s} = 0$$

$$K_{k_1 j_1}^i(p) \text{ arbitrary other } K\text{'s} = 0.$$

So now we have

$$\begin{aligned}
 (2.11-4) \quad \psi^i &= c\psi^i + G_{j_1 j_2 j_3}^i(\psi)\psi^{j_1 j_2 j_3} + L_{\ell}^i(\psi)t^{\ell} + K_{k_1 j_1}^i(\psi)\psi^{k_1 j_1} \\
 &+ M_{j_1 \ell}^i(\psi)\psi^{j_1 t^{\ell}} + M_{j_1 j_2 \ell}^i(\psi)\psi^{j_1 j_2 t^{\ell}} + \dots + N_{k_1 \ell}^i(\psi)\psi^{k_1 t^{\ell}}
 \end{aligned}$$

$$\begin{aligned}
& + N_{k_1 k_2}^i(\psi) \psi^{..k_1..k_2} t^\ell + \dots + R_{k_1 j_1}^i(\psi) \psi^{..k_1..j_1} t^\ell \\
& + R_{k_1 j_1 j_2}^i(\psi) \psi^{..k_1..j_1..j_2} t^\ell + \dots + R_{k_1 k_2 j_1}^i(\psi) \psi^{..k_1..k_2..j_1} t^\ell \\
& + R_{k_1 k_2 j_1 j_2}^i(\psi) \psi^{..k_1..k_2..j_1..j_2} t^\ell + \dots
\end{aligned}$$

Next we want to consider the L's, M's, N's, and R's and prove that they are zero.

Now $\psi^i(p, \alpha u, \alpha v, t) = \psi^i(p, u, v, f) \quad \forall p \in \Pi_1(\Omega), \forall u, \forall v \in \mathbb{R}^n, \alpha, t \in \mathbb{R}$

so we can differentiate this equation with respect to α . This gives

$$(2.11-5) \quad u^{p_1} \frac{\partial \psi^i}{\partial u^{p_1}}(p, \alpha u, \alpha v, t) + 2\alpha v^{q_1} \frac{\partial \psi^i}{\partial v^{q_1}}(p, \alpha u, \alpha v, t) = \psi^i(p, u, v, f) f_\alpha$$

$$\begin{aligned}
\text{where } f_\alpha &= \frac{\partial f}{\partial \alpha}, \quad p_1 = 1, \dots, n \\
q_1 &= 1, \dots, n.
\end{aligned}$$

Let $\alpha = 0$ we get

$$u^{p_1} \frac{\partial \psi^i}{\partial u^{p_1}}(p, 0, 0, t) = u^i f_\alpha(0, t) \text{ implying that } \frac{\partial \psi^i}{\partial u^{p_1}}(p, 0, 0, t) = f_\alpha(0, t) \delta_{p_1}^i$$

$$\text{where } \delta_{p_1}^i = \begin{cases} 0, & i \neq p_1 \\ 1, & i = p_1 \end{cases}.$$

Differentiate (2.11-5) with respect to α

$$\begin{aligned}
(2.11-6) \quad & u^{p_1 p_2} \frac{\partial^2 \psi^i}{\partial u^{p_1} \partial u^{p_2}}(p, \alpha u, \alpha v, t) + 2\alpha u^{p_1} v^{q_2} \frac{\partial^2 \psi^i}{\partial u^{p_1} \partial v^{q_2}}(p, \alpha u, \alpha v, t) \\
& + 2v^{q_1} \frac{\partial \psi^i}{\partial v^{q_1}}(p, \alpha u, \alpha v, t) + 2\alpha u^{p_2} v^{q_1} \frac{\partial^2 \psi^i}{\partial u^{p_2} \partial v^{q_1}}(p, \alpha u, \alpha v, t) \\
& + 4\alpha^2 v^{q_1} v^{q_2} \frac{\partial^2 \psi^i}{\partial v^{q_1} \partial v^{q_2}}(p, \alpha u, \alpha v, t) \\
& = \dot{\psi}^i(p, u, v, f) f_{\alpha\alpha} + f_{\alpha}^2 \ddot{\psi}^i(p, u, v, f) \quad \text{where } p_2, q_2 = 1, 2, \dots, n.
\end{aligned}$$

Let $\alpha = 0$ we get

$$u^{p_1 p_2} \frac{\partial^2 \psi^i}{\partial u^{p_1} \partial u^{p_2}}(p, 0, 0, t) + 2v^{q_1} \frac{\partial \psi^i}{\partial v^{q_1}}(p, 0, 0, t) = u^i f_{\alpha\alpha}(0, t) + f_{\alpha}^2(0, t) v^i$$

implying that $f_{\alpha\alpha}(0, t) = 0$, $\frac{\partial^2 \psi^i(p, 0, 0, t)}{\partial u^{p_1} \partial u^{p_2}} = 0$ and

$$\frac{\partial \psi^i}{\partial v^{q_1}}(p, 0, 0, t) = \frac{f_{\alpha}^2(0, t)}{2} \delta_{q_1}^i \quad \text{where } \delta_{q_1}^i = \begin{cases} 0, & i \neq q_1 \\ 1, & i = q_1 \end{cases}$$

Differentiate (2.11-6) with respect to α

$$\begin{aligned}
(2.11-7) \quad & u^{p_1 p_2 p_3} \frac{\partial^3 \psi^i}{\partial u^{p_1} \partial u^{p_2} \partial u^{p_3}}(p, \alpha u, \alpha v, t) + 6\alpha u^{r_1} v^{r_2} v^{r_3} \frac{\partial^3 \psi^i}{\partial u^{r_1} \partial u^{r_2} \partial v^{r_3}}(p, \alpha u, \alpha v, t) \\
& + 6u^{r_4} v^{r_5} \frac{\partial^2 \psi^i}{\partial u^{r_4} \partial v^{r_5}}(p, \alpha u, \alpha v, t) + 12\alpha^2 u^{r_6} v^{r_7} v^{r_8} \frac{\partial^3 \psi^i}{\partial u^{r_6} \partial v^{r_7} \partial v^{r_8}}(p, \alpha u, \alpha v, t) \\
& + 12\alpha v^{r_9} v^{r_{10}} \frac{\partial^2 \psi^i}{\partial v^{r_9} \partial v^{r_{10}}}(p, \alpha u, \alpha v, t) + 8\alpha^3 v^{q_1} v^{q_2} v^{q_3} \frac{\partial^3 \psi^i}{\partial v^{q_1} \partial v^{q_2} \partial v^{q_3}}(p, \alpha u, \alpha v, t)
\end{aligned}$$

$$= \dot{\psi}^i(p,u,v,f) f_{\alpha\alpha\alpha} + 3f_{\alpha} f_{\alpha\alpha} \ddot{\psi}^i(p,u,v,f) + f_{\alpha}^3 \psi^{\dots i}(p,u,v,f)$$

where $p_1, p_2, p_3, r_1, r_2, r_3, r_4, r_5, r_6, r_7, r_8, r_9, r_{10}, q_1, q_2,$

$$q_3 = 1, 2, \dots, n$$

Replace $\psi^{\dots i}(p,u,v,f)$ in (2.11-7) by the power series expansion, this gives

$$\begin{aligned} & p_1 p_2 p_3 \frac{\partial^3 \psi^i}{\partial u^1 \partial u^2 \partial u^3}(p, \alpha u, \alpha v, t) + 6 \alpha u^1 u^2 v^3 \frac{\partial^3 \psi^i}{\partial u^1 \partial u^2 \partial u^3}(p, \alpha u, \alpha v, t) \\ & + 6 u^4 v^5 \frac{\partial^2 \psi^i}{\partial u^4 \partial v^5}(p, \alpha u, \alpha v, t) + 12 \alpha^2 u^6 v^7 v^8 \frac{\partial^3 \psi^i}{\partial u^6 \partial v^7 \partial v^8}(p, \alpha u, \alpha v, t) \\ & + 12 \alpha v^9 v^{10} \frac{\partial^2 \psi^i}{\partial v^9 \partial v^{10}}(p, \alpha u, \alpha v, t) + 8 \alpha^3 v^1 v^2 v^3 \frac{\partial^3 \psi^i}{\partial v^1 \partial v^2 \partial v^3}(p, \alpha u, \alpha v, t) \end{aligned}$$

$$\begin{aligned} & = \dot{\psi}^i(p,u,v,f) f_{\alpha\alpha\alpha} + 3f_{\alpha} f_{\alpha\alpha} \ddot{\psi}^i(p,u,v,f) + f_{\alpha}^3 \psi^{\dots i}(p,u,v,f) \\ & + f_{\alpha}^3 G_{j_1 j_2 j_3}^i(\psi(p,u,v,f)) (\dot{\psi}^{j_1} \dot{\psi}^{j_2} \dot{\psi}^{j_3})(p,u,v,f) \\ & + f_{\alpha}^3 L_{\ell}^i(\psi(p,u,v,f)) t^{\ell} + f_{\alpha}^3 K_{k_1 j_1}^i(\psi(p,u,v,f)) (\dot{\psi}^{k_1} \dot{\psi}^{j_1})(p,u,v,f) \\ & + f_{\alpha}^3 M_{j_1 \ell}^i(\psi(p,u,v,f)) \dot{\psi}^{j_1}(p,u,v,f) t^{\ell} \\ & + f_{\alpha}^3 M_{j_1 j_2 \ell}^i(\psi(p,u,v,f)) (\dot{\psi}^{j_1} \dot{\psi}^{j_2})(p,u,v,f) t^{\ell} + \dots \\ & + f_{\alpha}^3 N_{k_1 \ell}^i(\psi(p,u,v,f)) \dot{\psi}^{k_1}(p,u,v,f) t^{\ell} \end{aligned}$$

$$\begin{aligned}
& + f_{\alpha}^3 N_{k_1 k_2 \ell}^i(\psi(p, u, v, f)) (\psi^{..k_1..k_2}) (p, u, v, f) t^{\ell} + \dots \\
& + f_{\alpha}^3 R_{k_1 j_1 \ell}^i(\psi(p, u, v, f)) (\psi^{..k_1..j_1}) (p, u, v, f) t^{\ell} \\
& + f_{\alpha}^3 R_{k_1 j_1 j_2 \ell}^i(\psi(p, u, v, f)) (\psi^{..k_1..j_1..j_2}) (p, u, v, f) t^{\ell} + \dots \\
& + f_{\alpha}^3 R_{k_1 k_2 j_1 \ell}^i(\psi(p, u, v, f)) (\psi^{..k_1..k_2..j_1}) (p, u, v, f) t^{\ell} \\
& + f_{\alpha}^3 R_{k_1 k_2 j_1 j_2 \ell}^i(\psi(p, u, v, f)) (\psi^{..k_1..k_2..j_1..j_2}) (p, u, v, f) t^{\ell} \\
& + \dots
\end{aligned}$$

Let $\alpha = 0$, we have

$$\begin{aligned}
& u^{\frac{p_1}{u}} u^{\frac{p_2}{u}} u^{\frac{p_3}{u}} \frac{\partial^3 \psi^i}{\partial u^1 \partial u^2 \partial u^3} (p, 0, 0, t) + 6u^{\frac{r_4}{u}} v^{\frac{r_5}{v}} \frac{\partial^2 \psi^i}{\partial u^{\frac{r_4}{u}} \partial v^{\frac{r_5}{v}}} (p, 0, 0, t) = u^i f_{\alpha \alpha \alpha}^i(0, t) \\
& + cu^i f_{\alpha}^3(0, t) + f_{\alpha}^3(0, t) G_{j_1 j_2 j_3}^i(p) u^{j_1} u^{j_2} u^{j_3} + f_{\alpha}^3(0, t) L_{\ell}^i(p) t^{\ell} \\
& + f_{\alpha}^3(0, t) K_{k_1 j_1}^i(p) v^{k_1} u^{j_1} + f_{\alpha}^3(0, t) M_{j_1 \ell}^i(p) u^{j_1} t^{\ell} \\
& + f_{\alpha}^3(0, t) M_{j_1 j_2 \ell}^i(p) u^{j_1} u^{j_2} t^{\ell} + \dots + f_{\alpha}^3(0, t) N_{k_1 \ell}^i(p) v^{k_1} t^{\ell} \\
& + f_{\alpha}^3(0, t) N_{k_1 k_2 \ell}^i(p) v^{k_1} v^{k_2} t^{\ell} + \dots + f_{\alpha}^3(0, t) R_{k_1 j_1 \ell}^i(p) v^{k_1} u^{j_1} t^{\ell} \\
& + f_{\alpha}^3(0, t) R_{k_1 j_1 j_2 \ell}^i(p) v^{k_1} u^{j_1} u^{j_2} t^{\ell} + \dots + f_{\alpha}^3(0, t) R_{k_1 k_2 j_1 \ell}^i(p) v^{k_1} v^{k_2} u^{j_1} t^{\ell} \\
& + f_{\alpha}^3(0, t) R_{k_1 k_2 j_1 j_2 \ell}^i(p) v^{k_1} v^{k_2} u^{j_1} u^{j_2} t^{\ell} + \dots
\end{aligned}$$

$$\begin{aligned}
(2.11-8) \quad & u^{p_1}_{j_1} u^{p_2}_{j_2} u^{p_3}_{j_3} \frac{\partial^3 \psi^i}{\partial u^{p_1} \partial u^{p_2} \partial u^{p_3}}(p, 0, 0, t) + 6u^{r_4}_{j_4} u^{r_5}_{j_5} \frac{\partial^2 \psi^i}{\partial v^{r_4} \partial v^{r_5}}(p, 0, 0, t) \\
& = (f_{\alpha}^3(0, t) G_{j_1 j_2 j_3}^i(p) + f_{\alpha}^3(0, t) M_{j_1 j_2 j_3}^i(p) t^{\ell}) u^{j_1}_{j_1} u^{j_2}_{j_2} u^{j_3}_{j_3} \\
& + (f_{\alpha}^3(0, t) K_{j_1 k_1}^i(p) + f_{\alpha}^3(0, t) t^{\ell} R_{k_1 j_1}^i(p)) u^{j_1}_{j_1} u^{k_1}_{j_1} \\
& + (f_{\alpha\alpha\alpha}(0, t) + c f_{\alpha}^3(0, t) + f_{\alpha}^3(0, t) M_{j_1}^i(p) t^{\ell} \delta_i^{j_1}) u^i \\
& + (f_{\alpha}^3(0, t) L_{\ell}^i(p) t^{\ell}) + (f_{\alpha}^3(0, t) M_{j_1 j_2}^i(p) t^{\ell}) u^{j_1}_{j_1} u^{j_2}_{j_2} \\
& + (f_{\alpha}^3(0, t) M_{j_1 j_2 j_3 j_4}^i(p) t^{\ell}) u^{j_1}_{j_1} u^{j_2}_{j_2} u^{j_3}_{j_3} u^{j_4}_{j_4} \\
& + (f_{\alpha}^3(0, t) M_{j_1 j_2 j_3 j_4 j_5}^i(p) t^{\ell}) u^{j_1}_{j_1} u^{j_2}_{j_2} u^{j_3}_{j_3} u^{j_4}_{j_4} u^{j_5}_{j_5} + \dots \\
& + f_{\alpha}^3(0, t) N_{k_1}^i(p) t^{\ell} u^{k_1}_{j_1} + f_{\alpha}^3(0, t) N_{k_1 k_2}^i(p) t^{\ell} u^{k_1}_{j_1} u^{k_2}_{j_1} + \dots \\
& + f_{\alpha}^3(0, t) R_{k_1 j_1 j_2}^i(p) t^{\ell} u^{j_1}_{j_1} u^{k_1}_{j_2} + \dots \\
& + f_{\alpha}^3(0, t) R_{k_1 k_2 j_1}^i(p) t^{\ell} u^{j_1}_{j_1} u^{k_1}_{j_2} u^{k_2}_{j_2} + f_{\alpha}^3(0, t) R_{k_1 k_2 j_1 j_2}^i(p) t^{\ell} u^{k_1}_{j_2} u^{k_2}_{j_2} u^{j_1}_{j_1} u^{j_2}_{j_2} \\
& + \dots
\end{aligned}$$



We want to show that

$$i) \quad \frac{\partial^3 \psi^i}{\partial u^{j_1} \partial u^{j_2} \partial u^{j_3}}(p, 0, 0, t) = f_{\alpha}^3(0, t) G_{j_1 j_2 j_3}^i(p)$$

$$ii) \quad \frac{\partial^2 \psi^i}{\partial u^{j_1} \partial v^{k_1}}(p, 0, 0, t) = f_{\alpha}^3(0, t) K_{j_1 k_1}^i(p)$$

$$\text{iii) } f_{\alpha\alpha\alpha}(0,t) + cf_{\alpha}^3(0,t) = 0$$

iv) there exists $t_0 \neq 0$ in W s.t. $f_{\alpha}(0,t_0) \neq 0$

let $\alpha = 0$ then (2.11-7) becomes

$$\begin{aligned} (2.11-9) \quad & u^{p_1}_{p_1} u^{p_2}_{p_2} u^{p_3}_{p_3} \frac{\partial^3 \psi^i}{\partial u^{p_1} \partial u^{p_2} \partial u^{p_3}}(p,0,0,t) + 6u^{r_4}_{r_4} v^{r_5}_{r_5} \frac{\partial^2 \psi^i}{\partial u^{r_4} \partial v^{r_5}}(p,0,0,t) \\ & = u^i f_{\alpha\alpha\alpha}(0,t) + f_{\alpha}^3(0,t) \psi^i(p,u,v,0) \end{aligned}$$

From (2.11-4) let $t = 0$, we get

$$\psi^i(p,u,v,0) = cu^i + G^i_{j_1 j_2 j_3}(p) u^{j_1} u^{j_2} u^{j_3} + K^i_{k_1 j_1}(p) v^{k_1} u^{j_1}$$

substitute this equation into (2.11-9)

$$\begin{aligned} & u^{p_1}_{p_1} u^{p_2}_{p_2} u^{p_3}_{p_3} \frac{\partial^3 \psi^i}{\partial u^{p_1} \partial u^{p_2} \partial u^{p_3}}(p,0,0,t) + 6u^{r_4}_{r_4} v^{r_5}_{r_5} \frac{\partial^2 \psi^i}{\partial u^{r_4} \partial v^{r_5}}(p,0,0,t) \\ & = u^i f_{\alpha\alpha\alpha}(0,t) + f_{\alpha}^3(0,t) cu^i + f_{\alpha}^3(0,t) G^i_{j_1 j_2 j_3}(p) u^{j_1} u^{j_2} u^{j_3} + f_{\alpha}^3(0,t) K^i_{k_1 j_1}(p) v^{k_1} u^{j_1} \end{aligned}$$

this equation implies that

$$f_{\alpha\alpha\alpha}(0,t) + f_{\alpha}^3(0,t)c = 0 \quad \text{so iii) is proved}$$

$$\frac{\partial^3 \psi^i}{\partial u^{j_1} \partial u^{j_2} \partial u^{j_3}}(p,0,0,t) = f_{\alpha}^3(0,t) G^i_{j_1 j_2 j_3}(p) \quad \text{so i) is proved}$$

$$6 \frac{\partial^2 \psi^i}{\partial u^{j_1} \partial v^{k_1}}(p,0,0,t) = f_{\alpha}^3(0,t) K^i_{j_1 k_1}(p) \quad \text{so ii) is proved.}$$

To prove iv), suppose $f_\alpha(0,t) = 0$ in W , we claim that

$$\frac{\partial^n}{\partial \alpha^n} f(0,t) = 0 \quad \forall n = 2, 3, \dots$$

We shall use induction on n to prove this.

But first, we shall prove the following equation by induction.

$$\begin{aligned} (2.11-10) \quad \frac{\partial^k}{\partial \alpha^k} \psi^i(p, \alpha u, \alpha v, t) &= f_\alpha \frac{\partial^{k-1}}{\partial \alpha^{k-1}} \dot{\psi}^i(p, u, v, v, f) \\ &+ \binom{k-1}{1} \frac{\partial^{k-2}}{\partial \alpha^{k-2}} \dot{\psi}^i(p, u, v, f) \frac{\partial f_\alpha}{\partial \alpha} + \binom{k-1}{2} \frac{\partial^{k-3}}{\partial \alpha^{k-3}} \dot{\psi}^i(p, u, v, f) \frac{\partial^2 f_\alpha}{\partial \alpha^2} \\ &+ \binom{k-1}{3} \frac{\partial^{k-4}}{\partial \alpha^{k-4}} \dot{\psi}^i(p, u, v, f) \frac{\partial^3 f_\alpha}{\partial \alpha^3} + \dots + \binom{k-1}{k-1} \dot{\psi}^i(p, u, v, f) \frac{\partial^{k-1} f_\alpha}{\partial \alpha^{k-1}} \end{aligned}$$

$$\forall k = 2, 3, \dots$$

The proof goes as follows :

$$\text{for } k = 2, \quad \frac{\partial^2 \psi^i}{\partial \alpha^2}(p, \alpha u, \alpha v, t) = f_\alpha \frac{\partial \dot{\psi}^i}{\partial \alpha}(p, u, v, f) + \binom{1}{1} \dot{\psi}^i(p, u, v, f) f_{\alpha\alpha}$$

Assume (2.11-10) is true for all $k = 2, 3, \dots, n$

$$\begin{aligned} \text{for } k = n+1, \quad \frac{\partial^{n+1}}{\partial \alpha^{n+1}} \psi^i(p, \alpha u, \alpha v, t) &= \frac{\partial}{\partial \alpha} \left(\frac{\partial^n}{\partial \alpha^n} \psi^i(p, \alpha u, \alpha v, t) \right) \\ &= \frac{\partial}{\partial \alpha} \left(f_\alpha \frac{\partial^{n-1}}{\partial \alpha^{n-1}} \dot{\psi}^i(p, u, v, f) \right. \\ &\quad + \binom{n-1}{1} \frac{\partial^{n-2}}{\partial \alpha^{n-2}} \dot{\psi}^i(p, u, v, f) \frac{\partial f_\alpha}{\partial \alpha} \\ &\quad + \binom{n-1}{2} \frac{\partial^{n-3}}{\partial \alpha^{n-3}} \dot{\psi}^i(p, u, v, f) \frac{\partial^2 f_\alpha}{\partial \alpha^2} \\ &\quad + \binom{n-1}{3} \frac{\partial^{n-4}}{\partial \alpha^{n-4}} \dot{\psi}^i(p, u, v, f) \frac{\partial^3 f_\alpha}{\partial \alpha^3} \\ &\quad \left. + \dots + \binom{n-1}{n-1} \dot{\psi}^i(p, u, v, f) \frac{\partial^{n-1} f_\alpha}{\partial \alpha^{n-1}} \right) \end{aligned}$$

$$\begin{aligned}
\text{so } \frac{\partial^{n+1}}{\partial \alpha^{n+1}} \psi^i(p, \alpha u, \alpha v, t) &= f_\alpha \frac{\partial^n}{\partial \alpha^n} \dot{\psi}^i(p, u, v, f) \\
&+ \left[\binom{n-1}{0} \frac{\partial^{n-1}}{\partial \alpha^{n-1}} \dot{\psi}^i(p, u, v, f) \frac{\partial f_\alpha}{\partial \alpha} + \binom{n-1}{1} \frac{\partial^{n-1}}{\partial \alpha^{n-1}} \dot{\psi}^i(p, u, v, f) \frac{\partial f_\alpha}{\partial \alpha} \right] \\
&+ \left[\binom{n-1}{1} \frac{\partial^{n-2}}{\partial \alpha^{n-2}} \dot{\psi}^i(p, u, v, f) \frac{\partial^2 f_\alpha}{\partial \alpha^2} \right. \\
&+ \left. \binom{n-1}{2} \frac{\partial^{n-2}}{\partial \alpha^{n-2}} \dot{\psi}^i(p, u, v, f) \frac{\partial^2 f_\alpha}{\partial \alpha^2} \right] \\
&+ \left[\binom{n-1}{2} \frac{\partial^{n-3}}{\partial \alpha^{n-3}} \dot{\psi}^i(p, u, v, f) \frac{\partial^3 f_\alpha}{\partial \alpha^3} \right. \\
&+ \left. \binom{n-1}{3} \frac{\partial^{n-3}}{\partial \alpha^{n-3}} \dot{\psi}^i(p, u, v, f) \frac{\partial^3 f_\alpha}{\partial \alpha^3} \right] + \dots \\
&+ \left[\binom{n-1}{n-2} \frac{\partial \dot{\psi}^i}{\partial \alpha}(p, u, v, f) \frac{\partial^{n-1} f_\alpha}{\partial \alpha^{n-1}} \right. \\
&+ \left. \binom{n-1}{n-1} \frac{\partial \dot{\psi}^i}{\partial \alpha}(p, u, v, f) \frac{\partial^{n-1} f_\alpha}{\partial \alpha^{n-1}} \right] \\
&+ \binom{n-1}{n-1} \dot{\psi}^i(p, u, v, f) \frac{\partial^n f_\alpha}{\partial \alpha^n}
\end{aligned}$$

Since $\binom{n}{k-1} + \binom{n}{k} = \binom{n+1}{k}$ so we have

$$\begin{aligned}
(2.11-11) \quad \frac{\partial^{n+1}}{\partial \alpha^{n+1}} \psi^i(p, \alpha u, \alpha v, t) &= f_\alpha \frac{\partial^n}{\partial \alpha^n} \dot{\psi}^i(p, u, v, f) + \binom{n}{1} \frac{\partial^{n-1}}{\partial \alpha^{n-1}} \dot{\psi}^i(p, u, v, f) \frac{\partial f_\alpha}{\partial \alpha} \\
&+ \binom{n}{2} \frac{\partial^{n-2}}{\partial \alpha^{n-2}} \dot{\psi}^i(p, u, v, f) \frac{\partial^2 f_\alpha}{\partial \alpha^2} + \dots \\
&+ \binom{n}{n-1} \frac{\partial \dot{\psi}^i}{\partial \alpha}(p, u, v, f) \frac{\partial^{n-1} f_\alpha}{\partial \alpha^{n-1}} \\
&+ \binom{n}{n} \dot{\psi}^i(p, u, v, f) \frac{\partial^n f_\alpha}{\partial \alpha^n}
\end{aligned}$$

so (2.11-10) is true for all $k = 2, 3, \dots$

Now let us turn back to the proof that if $f_\alpha(0, t) \equiv 0$, then

$$\frac{\partial^n f(0, t)}{\partial \alpha^n} \equiv 0 \quad \forall n = 2, 3, \dots$$

For $n = 2$ we proved that $f_{\alpha\alpha}(0, t) = 0$.

$$\text{Assume} \quad \frac{\partial^k f(0, t)}{\partial \alpha^k} \equiv 0 \quad k = 2, 3, \dots, n$$

Before we continue our proof let us prove the following lemma.

Lemma 2.12 For $n > 2$, $\frac{\partial^n}{\partial \alpha^n} \psi^i(p, \alpha u, \alpha v, t) = u^{p_1} \dots u^{p_n} \frac{\partial^n}{\partial u^{p_1} \dots \partial u^{p_n}} \psi^i(p, \alpha u, \alpha v, t)$

$$+ \sum_{r=0}^{n-1} \sum_{s=1}^n X_{p_1 \dots p_r q_1 \dots q_s}^i(\alpha, u, v, p, t) u^{p_1} \dots u^{p_r} v^{q_1} \dots v^{q_s}$$

where $2 \leq r + s \leq n$, where $X_{p_1 \dots p_r q_1 \dots q_s}^i(\alpha, u, v, p, t)$ is a function of α, p, u, v, t .

Proof We will prove this by induction on n .

$$\text{For } n = 3; \frac{\partial^3}{\partial \alpha^3} \psi^i(p, \alpha u, \alpha v, t) = u^{p_1} u^{p_2} u^{p_3} \frac{\partial^3 \psi^i(p, \alpha u, \alpha v, t)}{\partial u^{p_1} \partial u^{p_2} \partial u^{p_3}}$$

$$+ 6\alpha u^{p_1} u^{p_2} v^{q_1} \frac{\partial^3 \psi^i(p, \alpha u, \alpha v, t)}{\partial u^{p_1} \partial u^{p_2} \partial v^{q_1}} + 6u^{p_1} v^{q_1} \frac{\partial^2 \psi^i(p, \alpha u, \alpha v, t)}{\partial u^{p_1} \partial v^{q_1}}$$

$$+ 12\alpha^2 u^{p_1} v^{q_1} v^{q_2} \frac{\partial^3 \psi^i(p, \alpha u, \alpha v, t)}{\partial u^{p_1} \partial v^{q_1} \partial v^{q_2}}$$

$$+ 12\alpha v^{q_1} v^{q_2} \frac{\partial^2 \psi^i(p, \alpha u, \alpha v, t)}{\partial v^{q_1} \partial v^{q_2}}$$

$$+ 8\alpha^3 v^{q_1} v^{q_2} v^{q_3} \frac{\partial^3 \psi^i(p, \alpha u, \alpha v, t)}{\partial v^{q_1} \partial v^{q_2} \partial v^{q_3}}$$

Hence Lemma 2.12. is true for $n = 3$.

Assume Lemma 2.12. is true for $n = k$, that is

$$\begin{aligned} \frac{\partial^k}{\partial \alpha^k} \psi^i(p, \alpha u, \alpha v, t) &= u^{p_1} \dots u^{p_k} \frac{\partial^k}{\partial u^1 \dots \partial u^k} \psi^i(p, \alpha u, \alpha v, t) \\ &+ \sum_{r=0}^{k-1} \sum_{s=1}^k X_{p_1 \dots p_r q_1 \dots q_s}(\alpha, u, v, p, t) u^{p_1} \dots u^{p_r} v^{q_1} \dots v^{q_s} \end{aligned}$$

such that $2 \leq r + s \leq k$.

$$\begin{aligned} \frac{\partial^{k+1}}{\partial \alpha^{k+1}} \psi^i(p, \alpha u, \alpha v, t) &= u^{p_1} \dots u^{p_{k+1}} \frac{\partial^{k+1}}{\partial u^1 \dots \partial u^{k+1}} \psi^i(p, \alpha u, \alpha v, t) \\ &+ 2\alpha u^{p_1} \dots u^{p_k} v^{q_1} \frac{\partial^{k+1}}{\partial u^1 \dots \partial u^k \partial v} \psi^i(p, \alpha u, \alpha v, t) \\ &+ \sum_{r=0}^{k-1} \sum_{s=1}^k u^{p_1} \dots u^{p_r} v^{p_{r+1} q_1 \dots q_s} \frac{\partial}{\partial u^{p_{r+1}}} X_{p_1 \dots p_r q_1 \dots q_s} \\ &+ \sum_{r=0}^{k-1} \sum_{s=1}^k 2\alpha u^{p_1} \dots u^{p_r} v^{q_1 \dots q_s} v^{q_{s+1}} \frac{\partial}{\partial v^{q_{s+1}}} X_{p_1 \dots p_r q_1 \dots q_s} \\ &+ \sum_{r=0}^{k-1} \sum_{s=1}^k Y_{p_1 \dots p_r q_1 \dots q_s}(\alpha, u, v, p, t) u^{p_1} \dots u^{p_r} v^{q_1} \dots v^{q_s} \end{aligned}$$

$$\text{so } \frac{\partial^{k+1}}{\partial \alpha^{k+1}} \psi^i(p, \alpha u, \alpha v, t) = u^{p_1} \dots u^{p_{k+1}} \frac{\partial^{k+1}}{\partial u^1 \dots \partial u^{k+1}} \psi^i(p, \alpha u, \alpha v, t)$$

$$+ \sum_{r=0}^k \sum_{s=1}^{k+1} Z(\alpha, u, v, p, t) u^{p_1} \dots u^{p_r} v^{q_1} \dots v^{q_s} .$$

So Lemma 2.12 is proved.

Substitute $\alpha = 0$ into equation (2.11-11) we obtain

$$\begin{aligned}
 & u^{p_1} \dots u^{p_{n+1}} \frac{\partial^{n+1}}{\partial u^{p_1} \dots \partial u^{p_{n+1}}} \psi^i(p, 0, 0, t) + \sum_{r=0}^n \sum_{s=1}^{n+1} X_{p_1 \dots p_r q_1 \dots q_s}^i(0, u, v, p, t) u^{p_1} \dots u^{p_r} v^{q_1} \dots v^{q_s} \\
 &= f_\alpha(0, t) \frac{\partial^n}{\partial \alpha^n} \dot{\psi}^i(p, u, v, 0) + \binom{n}{1} \frac{\partial^{n-1}}{\partial \alpha^{n-1}} \dot{\psi}^i(p, u, v, 0) \frac{\partial}{\partial \alpha} f_\alpha(0, t) \\
 &+ \binom{n}{2} \frac{\partial^{n-2}}{\partial \alpha^{n-2}} \dot{\psi}^i(p, u, v, 0) \frac{\partial^2}{\partial \alpha^2} f_\alpha(0, t) + \dots \\
 &+ \binom{n}{n-1} \frac{\partial}{\partial \alpha} \dot{\psi}^i(p, u, v, 0) \frac{\partial^{n-1}}{\partial \alpha^{n-1}} f_\alpha(0, t) + \binom{n}{n} \dot{\psi}^i(p, u, v, 0) \frac{\partial^n}{\partial \alpha^n} f_\alpha(0, t)
 \end{aligned}$$

where $2 \leq r + s \leq n$.

$$\begin{aligned}
 & u^{p_1} \dots u^{p_{n+1}} \frac{\partial^{n+1}}{\partial u^{p_1} \dots \partial u^{p_{n+1}}} \psi^i(p, 0, 0, t) + \sum_{r=0}^n \sum_{s=1}^{n+1} X_{p_1 \dots p_r q_1 \dots q_s}^i(0, u, v, p, t) u^{p_1} \dots u^{p_r} v^{q_1} \dots v^{q_s} \\
 &= u^i \frac{\partial^n}{\partial \alpha^n} f_\alpha(0, t) = u^i \frac{\partial^{n+1}}{\partial \alpha^{n+1}} f(0, t).
 \end{aligned}$$

So $\frac{\partial^{n+1}}{\partial \alpha^{n+1}} f(0, t) = 0$, that is $\frac{\partial^n}{\partial \alpha^n} f(0, t) \equiv 0$, $\forall n = 2, 3, \dots$

To prove $f_\alpha(0, t) \neq 0$ for some t , all we need to show is the following.

Lemma 2.13 If $f(\alpha, t)$ is analytic in a neighbourhood of $(0, 0)$ and $f(0, t) = 0$, $\frac{\partial^n}{\partial \alpha^n} f(0, t) = 0$ for $n = 1, 2, \dots$, then $f(\alpha, t) \equiv 0$.

Proof Fix t_0 such that $f(\alpha, t_0)$ is defined in a neighbourhood of $\alpha = 0$ denote $f(\alpha, t_0)$ by $F_{t_0}(\alpha)$.

Since $F_{t_0}(\alpha)$ is analytic

$$F_{t_0}(\alpha) = F_{t_0}(0) + F'_{t_0}(0) \frac{\alpha}{1!} + F''_{t_0}(0) \frac{\alpha^2}{2!} + \dots + F_{t_0}^{(n)}(0) \frac{\alpha^n}{n!} + \dots$$

$$f(\alpha, t_0) = f(0, t_0) + \frac{\partial}{\partial \alpha} f(0, t_0) \alpha + \frac{\partial^2}{\partial \alpha^2} f(0, t_0) \frac{\alpha^2}{2!} + \dots + \frac{\partial^n}{\partial \alpha^n} f(0, t_0) \frac{\alpha^n}{n!} + \dots$$

$$= 0.$$

Since t_0 is arbitrary, we must have that $f(\alpha, t) \equiv 0$.

Thus Lemma 2.13 is proved.

So we have that $f(\alpha, t) \equiv 0 \quad \forall \alpha, t \in \mathbb{R}$

$$\begin{aligned} \text{and } \psi^i(p, \alpha u, \alpha v, t) &= \psi^i(p, u, v, f(\alpha, t)) \\ &= \psi^i(p, u, v, 0) \\ &= p^i \end{aligned}$$

$$\text{hence } \dot{\psi}^i(p, \alpha u, \alpha v, t) = 0$$

implying that

$$\dot{\psi}^i(p, \alpha u, \alpha v, 0) = 0$$

$$\text{but } \dot{\psi}^i(p, \alpha u, \alpha v, 0) = \alpha u^i$$

$$\text{so } \alpha u^i = 0 \quad \forall \alpha, \forall u.$$

This is a contradiction, so the supposition on the top of page 42 that $f_\alpha(0, t) = 0$ is false, hence $t_0 \neq 0$ such that $f_\alpha(0, t_0) \neq 0$ so iv) is proved.

From (2.11-8) and by knowing that $\exists t_0 \neq 0$ such that $f_\alpha(0, t_0) \neq 0$ we can conclude, from equation (2.11-8) page 40, that $L_\ell^i(p) = 0, \ell, i$

all N^i 's = 0, all R^i 's = 0, all M^i 's = 0.

Finally we see that from (2.11-4) all we have left is

$$\psi^{\dots i} = c \psi^i + G_{j_1 j_2 j_3}^i (\psi) \psi^{j_1 j_2 j_3} + K_{k_1 j_1}^i (\psi) \psi^{k_1 j_1}$$

Next, we want to show that $c = 0$.

Into equation (2.11-3) on page 32 substitute

$$\psi^{..i} = G_{j_1 j_2 j_3}^i (\psi) \dot{\psi}^{j_1} \dot{\psi}^{j_2} \dot{\psi}^{j_3} + K_{j_1 k_1}^i (\psi) \dot{\psi}^{j_1} \dot{\psi}^{..k_1} + c \dot{\psi}^i .$$

This gives

$$\begin{aligned} & c \dot{\psi}^i(p, au, av, t) + G_{j_1 j_2 j_3}^i (\psi(p, au, av, t)) (\dot{\psi}^{j_1} \dot{\psi}^{j_2} \dot{\psi}^{j_3})(p, au, av, t) \\ & + K_{k_1 j_1}^i (\psi(p, au, av, t)) (\dot{\psi}^{..k_1} \dot{\psi}^{j_1})(p, au, av, t) \\ & = G_{j_1 j_2 j_3}^i (\psi(p, u, v, f)) (\dot{\psi}^{j_1} \dot{\psi}^{j_2} \dot{\psi}^{j_3})(p, u, v, f) f_t^3 + c \dot{\psi}^i(p, u, v, f) f_t^3 \\ & + f_t^3 K_{k_1 j_1}^i (\psi(p, u, v, f)) (\dot{\psi}^{..k_1} \dot{\psi}^{j_1})(p, u, v, f) + \dot{\psi}^i(p, u, v, f) f_{ttt} \\ & + 3f_t f_{tt} \ddot{\psi}^i(p, u, v, f). \end{aligned}$$

Using (2.14-1) and (2.14-2) we get

$$\begin{aligned} & G_{j_1 j_2 j_3}^i (\psi(p, u, v, f)) (\dot{\psi}^{j_1} \dot{\psi}^{j_2} \dot{\psi}^{j_3})(p, u, v, f) f_t^3 + c \dot{\psi}^i(p, u, v, f) f_t^3 \\ & + K_{k_1 j_1}^i (\psi(p, u, v, f)) [\dot{\psi}^{..k_1} (p, u, v, f) f_t^2 + \dot{\psi}^{..k_1} (p, u, v, f) f_{tt}] \dot{\psi}^{j_1} (p, u, v, f) f_t \\ & = G_{j_1 j_2 j_3}^i (\psi(p, u, v, f)) (\dot{\psi}^{j_1} \dot{\psi}^{j_2} \dot{\psi}^{j_3})(p, u, v, f) f_t^3 + c \dot{\psi}^i(p, u, v, f) f_t^3 \\ & + f_t^3 K_{k_1 j_1}^i (\psi(p, u, v, f)) (\dot{\psi}^{..k_1} \dot{\psi}^{j_1})(p, u, v, f) + \dot{\psi}^i(p, u, v, f) f_{ttt} \\ & + 3f_t f_{tt} \ddot{\psi}^i(p, u, v, f) \end{aligned}$$

$$\begin{aligned} & \text{so } [K_{j_1 k_1}^i (\psi(p, u, v, f)) (\dot{\psi}^{j_1 k_1}) (p, u, v, f) - 3\ddot{\psi}^i(p, u, v, f)] f_t f_{tt} \\ & = \dot{\psi}^i(p, u, v, f) [f_{ttt} - cf_t + cf_t^3] \quad \forall p \in \Pi_1(\Omega), \forall u \in R^n \end{aligned}$$

$$\forall v \in R^n, \forall \alpha, t \in R.$$

Fix u_0 such that $u_0^i \neq 0$ $i = 1, \dots, n$, choose a small neighbourhood U of u_0 such that $\dot{\psi}^i(p, u, v, t) \neq 0$ $i = 1, \dots, n$ $u \in U$ (we can do this by continuity). Then

$$\begin{aligned} & \frac{1}{\dot{\psi}^i(p, u, v, f)} [K_{j_1 k_1}^i (\psi(p, u, v, f)) (\dot{\psi}^{j_1 k_1}) (p, u, v, f) - 3\ddot{\psi}^i(p, u, v, f)] f_t f_{tt} \\ & = f_{ttt} - cf_t + cf_t^3 \quad \text{for small } t. \end{aligned}$$

case 1 $f_t f_{tt} \neq 0$. Since RHS of the above equation is independent of p, u and v , hence

$$\frac{1}{\dot{\psi}^i(p, u, v, f)} [K_{j_1 k_1}^i (\psi(p, u, v, f)) (\dot{\psi}^{j_1 k_1}) (p, u, v, f) - 3\ddot{\psi}^i(p, u, v, f)]$$

must be independent of p, u and v , so

$$\begin{aligned} & \frac{1}{\dot{\psi}^i(p, u, v, f)} [K_{j_1 k_1}^i (\psi(p, u, v, f)) (\dot{\psi}^{j_1 k_1}) (p, u, v, f) - 3\ddot{\psi}^i(p, u, v, f)] \\ & = k(\alpha, t). \end{aligned}$$

Let $t = 0$, fix α_0 , we get

$$v^i = \frac{1}{3} K_{k_1 j_1}^i(p) u^{j_1} u^{k_1} - \frac{1}{3} k(\alpha_0, 0) u^i$$

But u and v are independent variables, therefore we get a contradiction for the case $f_t f_{tt} \neq 0$. Thus we must have

$$\text{case 2} \quad f_t f_{tt} \equiv 0, \text{ since } f_t(\alpha, 0) = \alpha \neq 0. \text{ And since}$$

f is an analytic function, by Theorem 1.15, we have

$$f_{tt}(\alpha, t) \equiv 0 \text{ for } t \text{ sufficiently small}$$

so $f_{ttt}(\alpha, t) = 0$, and since

$$c = \frac{f_{ttt}(\alpha, 0)}{\alpha - \alpha^3} \delta_j^i \text{ we get } c = 0$$

also we get $f_t(\alpha, t) = g(\alpha)$, for some function g

so $f(\alpha, t) = g(\alpha)t + A(\alpha)$, for some function A

$$f(\alpha, 0) = A(\alpha) \text{ implying } A(\alpha) = 0$$

then $f(\alpha, t) = g(\alpha)t$

but $f_t(\alpha, t) = g(\alpha)$, let $t = 0$, we have

$$f_t(\alpha, 0) = g(\alpha), \text{ but one page 31 we proved that } f_t(\alpha, 0) = \alpha$$

therefore $\alpha = g(\alpha)$,

So $f(\alpha, t) = \alpha t$.

So we get that our differential equation must be of the form

$$(2.11-12) \quad \psi^i = G_{j_1 j_2 j_3}^i(\psi) \psi^{j_1} \psi^{j_2} \psi^{j_3} + K_{j_1 k_1}^i(\psi) \psi^{j_1} \psi^{k_1}.$$

This finished the proof of Theorem 2.11.

To prove the converse we need Lemma 2.14 and Theorem 2.15.

Lemma 2.14 Let $\psi^i(p, u, v, t)$ be the solution to a differential equation of the form

$$\ddot{\psi}^i = G_{j_1 j_2 j_3}^i(\psi) \dot{\psi}^{j_1} \dot{\psi}^{j_2} \dot{\psi}^{j_3} + K_{j_1 k_1}^i(\psi) \dot{\psi}^{j_1} \dot{\psi}^{k_1}, \quad \text{where}$$

$G_{j_1 j_2 j_3}^i$, $K_{j_1 k_1}^i$ are analytic on an open subset D of \mathbb{R}^n , with

initial conditions $\psi^i(p, u, v, 0) = p^i$,

$$\dot{\psi}^i(p, u, v, 0) = u^i, \quad \ddot{\psi}^i(p, u, v, 0) = v^i. \quad \text{Then}$$

$$\begin{aligned} \frac{\partial^n}{\partial t^n} \psi^i(p, u, v, t) &= Y_{j_1 \dots j_n}^i(\psi) \dot{\psi}^{j_1} \dots \dot{\psi}^{j_n} + Y_{j_1 \dots j_{n-2} k_1}^i(\psi) \dot{\psi}^{j_1} \dots \dot{\psi}^{j_{n-2}} \dot{\psi}^{k_1} + \dots \\ &+ \begin{cases} Y_{k_1 \dots k_{\frac{n}{2}}}^i(\psi) \dot{\psi}^{k_1} \dots \dot{\psi}^{k_{\frac{n}{2}}} & \text{if } n \text{ is even} \\ Y_{j_1 k_1 \dots k_{\frac{n-1}{2}}}^i(\psi) \dot{\psi}^{j_1} \dot{\psi}^{k_1} \dots \dot{\psi}^{k_{\frac{n-1}{2}}} & \text{if } n \text{ is odd.} \end{cases} \end{aligned}$$

for all $n \geq 3$. That is,

$$\frac{\partial^n}{\partial t^n} \psi^i(p, u, v, t) = \text{polynomial in } \dot{\psi} \text{ and } \ddot{\psi} \text{ such that each term has exactly } n \text{ dots.}$$

Proof for $n = 3$, Lemma 2.14 is true.

Assume Lemma 2.14 is true for $n = m \geq 3$, that is

$$\frac{\partial^m}{\partial t^m} \psi^i(p, u, v, t) = Y_{j_1 \dots j_m}^i(\psi) \dot{\psi}^{j_1} \dots \dot{\psi}^{j_m} + Y_{k_1 j_1 \dots j_{m-2}}^i(\psi) \dot{\psi}^{j_1} \dots \dot{\psi}^{j_{m-2}} \dot{\psi}^{k_1} + \dots$$

$$+ \begin{cases} Y_{k_1 \dots k_{\frac{m}{2}}}^i(\psi) \dot{\psi}^{k_1} \dots \dot{\psi}^{\frac{m}{2}} & \text{if } m \text{ is even} \\ Y_{j_1 k_1 \dots k_{\frac{m-1}{2}}}^i(\psi) \dot{\psi}^{j_1} \dot{\psi}^{k_1} \dots \dot{\psi}^{\frac{m-1}{2}} & \text{if } m \text{ is odd.} \end{cases}$$

That is, each term has exactly m dots by the induction hypothesis.

For $n = m+1$ we get

$$\frac{\partial^{m+1}}{\partial t^{m+1}} \psi^i(p, u, v, t) = \frac{\partial Y_{j_1 \dots j_m}^i(\psi) \dot{\psi}^{j_1} \dots \dot{\psi}^{j_m} \dot{\psi}^{j_{m+1}}}{\partial x^{j_{m+1}}}$$

$$+ Y_{j_1 \dots j_m}^i(\psi) \dot{\psi}^{j_1} \dot{\psi}^{j_2} \dots \dot{\psi}^{j_m} + \dots + Y_{j_1 \dots j_m}^i(\psi) \dot{\psi}^{j_1} \dots \dot{\psi}^{j_{m-1}} \dot{\psi}^{j_m}$$

$$+ \frac{\partial Y_{j_1 \dots j_{m-2}}^i(\psi) \dot{\psi}^{j_1} \dots \dot{\psi}^{j_{m-1}} \dot{\psi}^{k_1}}{\partial x^{j_{m-1}}}$$

$$+ Y_{j_1 \dots j_{m-2} k_1}^i(\psi) \dot{\psi}^{j_1} \dot{\psi}^{j_2} \dots \dot{\psi}^{j_{m-2}} \dot{\psi}^{k_1} + \dots + Y_{j_1 \dots j_{m-2} k_1}^i(\psi) \dot{\psi}^{j_1} \dots \dot{\psi}^{j_{m-2}} \dot{\psi}^{k_1}$$

$$+ Y_{j_1 \dots j_{m-2} k_1}^i(\psi) \dot{\psi}^{j_1} \dots \dot{\psi}^{j_{m-2}} \dot{\psi}^{k_1} + \dots$$

$$\begin{aligned}
 & \left. \begin{aligned}
 & \frac{\partial Y_{k_1 \dots k_{\frac{m}{2}}}^i}{\partial x} (\psi) \psi^{j_1 \dots k_1 \dots \psi^{\frac{k_m}{2}}} + Y_{k_1 \dots k_{\frac{m}{2}}}^i (\psi) \psi^{j_1 \dots k_2 \dots \psi^{\frac{k_m}{2}}} + \dots \\
 & + Y_{k_1 \dots k_{\frac{m}{2}}}^i (\psi) \psi^{j_1 \dots \psi^{\frac{k_m}{2}}} \quad \text{if } m \text{ is even} \\
 & + \frac{\partial Y_{k_1 \dots k_{\frac{m-1}{2}} j_1}^i}{\partial x} (\psi) \psi^{j_1 \dots \psi^{\frac{k_{m-1}}{2}} \psi^{j_1} \psi^{j_2}} \\
 & + Y_{j_1 k_1 \dots k_{\frac{m-1}{2}}}^i (\psi) \psi^{j_1 \dots k_1 \dots k_2 \dots \psi^{\frac{k_{m-1}}{2}}} + \dots \\
 & + Y_{j_1 k_1 \dots k_{\frac{m-1}{2}}}^i (\psi) \psi^{j_1 \dots k_1 \dots k_2 \dots \psi^{\frac{k_{m-1}}{2}}} + \dots \\
 & + Y_{j_1 k_1 \dots k_{\frac{m-1}{2}}}^i (\psi) \psi^{j_1 \dots k_1 \dots \psi^{\frac{k_{m-1}}{2}}} \quad \text{if } m \text{ is odd.}
 \end{aligned} \right\}
 \end{aligned}$$

Thus we see that each term has $m+1$ dots, but some terms have $\psi^{\dots i}$ in them so we substitute equation (2.11-12) and get

$$\begin{aligned}
 \frac{\partial^{m+1}}{\partial t^{m+1}} \psi^i(p, u, v, t) &= \frac{\partial Y_{j_1 \dots j_m}^i}{\partial x^{m+1}} (\psi) \psi^{j_1 \dots \psi^{j_{m+1}}} + Y_{j_1 \dots j_m}^i (\psi) \psi^{j_1 \dots j_2 \dots \psi^{j_m}} \\
 &+ \dots + Y_{j_1 \dots j_m}^i (\psi) \psi^{j_1 \dots \psi^{j_{m-1}} \psi^{j_m}} + \frac{\partial Y_{j_1 \dots j_{m-2} k_1}^i}{\partial x^{j_{m-2}}} (\psi) \psi^{j_1 \dots \psi^{j_{m-1}} \psi^{k_1}} \\
 &+ Y_{j_1 \dots j_{m-2} k_1}^i (\psi) \psi^{j_1 \dots \psi^{j_{m-2}} \psi^{k_1}} + \dots + Y_{j_1 \dots j_{m-2} k_1}^i (\psi) \psi^{j_1 \dots \psi^{j_{m-2}} \psi^{k_1}} \\
 &+ G_{j_{m-1} j_m j_{m+1}}^{k_1} (\psi) Y_{j_1 \dots j_{m-2} k_1}^i (\psi) \psi^{j_1 \dots \psi^{j_{m-2}} \psi^{j_{m-1}} \psi^{j_m} \psi^{j_{m+1}}} \\
 &+ K_{j_{m-1} k_2}^{k_1} (\psi) Y_{j_1 \dots j_{m-2} k_1}^i (\psi) \psi^{j_1 \dots \psi^{j_{m-2}} \psi^{j_{m-1}} \psi^{k_2}} + \dots
 \end{aligned}$$

$$\begin{aligned}
& \frac{\partial Y_{k_1 \dots k_{\frac{m}{2}}}^i}{\partial x^{j_1}} (\psi) \dot{\psi}^{j_1 \dots k_1} \dots \dot{\psi}^{\frac{k_{\frac{m}{2}}}{2}} + G_{j_1 j_2 j_3}^{k_1} (\psi) Y_{k_1 \dots k_{\frac{m}{2}}}^i (\psi) \dot{\psi}^{j_1} \dot{\psi}^{j_2} \dot{\psi}^{j_3} \dots \dot{\psi}^{\frac{k_{\frac{m}{2}}}{2}} \\
& + K_{j_1}^{k_1} (\psi) Y_{k_1 \dots k_{\frac{m}{2}}}^i (\psi) \dot{\psi}^{j_1} \dots \dot{\psi}^{\frac{k_{\frac{m}{2}+2}}{2}} \dots \dot{\psi}^{\frac{k_{\frac{m}{2}}}{2}} + \dots \\
& + G_{j_1 j_2 j_3}^{\frac{k_{\frac{m}{2}}}{2}} (\psi) Y_{k_1 \dots k_{\frac{m}{2}}}^i (\psi) \dot{\psi}^{j_1} \dot{\psi}^{j_2} \dot{\psi}^{j_3} \dots \dot{\psi}^{\frac{k_{\frac{m}{2}-2}}{2}} \\
& + K_{j_1}^{\frac{k_{\frac{m}{2}}}{2}} (\psi) Y_{k_1 \dots k_{\frac{m}{2}}}^i (\psi) \dot{\psi}^{j_1} \dots \dot{\psi}^{\frac{k_{\frac{m}{2}-2}}{2}} \dot{\psi}^{\ell} \quad \text{if } m \text{ is even} \\
& + \frac{\partial Y_{k_1 \dots k_{\frac{m-1}{2}}}^i}{\partial x^{j_2}} (\psi) \dot{\psi}^{j_1} \dot{\psi}^{j_2} \dots \dot{\psi}^{\frac{k_{\frac{m-1}{2}}}{2}} + \dots \\
& + G_{j_2 j_3 j_4}^{k_1} (\psi) Y_{j_1 k_2 \dots k_{\frac{m-1}{2}}}^i (\psi) \dot{\psi}^{j_1} \dot{\psi}^{j_2} \dot{\psi}^{j_3} \dot{\psi}^{j_4} \dots \dot{\psi}^{\frac{k_{\frac{m-1}{2}}}{2}} \\
& + K_{j_2}^{k_1} (\psi) Y_{j_1 k_1 \dots k_{\frac{m-1}{2}}}^i (\psi) \dot{\psi}^{j_1} \dot{\psi}^{j_2} \dots \dot{\psi}^{\frac{k_{\frac{m-1}{2}}}{2}} + \dots \\
& + G_{j_2 j_3 j_4}^{\frac{k_{\frac{m-1}{2}}}{2}} (\psi) Y_{j_1 k_1 \dots k_{\frac{m-1}{2}}}^i (\psi) \dot{\psi}^{j_1} \dot{\psi}^{j_2} \dot{\psi}^{j_3} \dot{\psi}^{j_4} \dots \dot{\psi}^{\frac{k_{\frac{m-3}{2}}}{2}} \\
& + K_{j_2}^{\frac{k_{\frac{m-1}{2}}}{2}} (\psi) Y_{j_1 k_1 \dots k_{\frac{m-1}{2}}}^i (\psi) \dot{\psi}^{j_1} \dot{\psi}^{j_2} \dots \dot{\psi}^{\frac{k_{\frac{m-3}{2}}}{2}} \dot{\psi}^k \quad \text{if } m \text{ is odd.}
\end{aligned}$$

So we see that when we replace $\dot{\psi}^i$ by the RHS of equation (2.11-12) we are replacing $\dot{\psi}^i$ by terms which have three dots so the result is the same, that is each term of $\frac{\partial^{m+1}}{\partial t^{m+1}} \dot{\psi}^i$ has $m+1$ dots.

Lemma 2.14 is proved. Now for the converse.

Theorem 2.15 Let $\psi^i(p,u,v,t)$ be the solution to the differential equation

$$\ddot{\psi}^i = G_{j_1 j_2 j_3}^i(\psi) \dot{\psi}^{j_1} \dot{\psi}^{j_2} \dot{\psi}^{j_3} + K_{j_1 k_1}^i(\psi) \dot{\psi}^{j_1} \dot{\psi}^{k_1} \quad \text{where}$$

$G_{j_1 j_2 j_3}^i$, $K_{j_1 k_1}^i$ are analytic on open subset D of \mathbb{R}^n satisfying

the initial conditions $\psi^i(p,u,v,0) = p^i$, $\dot{\psi}^i(p,u,v,0) = u^i$,

$\ddot{\psi}^i(p,u,v,0) = v^i$. Then $\psi^i(p,\alpha u, \alpha v, t)$ exists if and only if

$\psi^i(p,u,v,\alpha t)$ exists, and

$$\psi^i(p,\alpha u, \alpha v, t) = \psi^i(p,u,v,\alpha t)$$

Proof Since ψ^i is the solution of $\ddot{\psi}^i = G_{j_1 j_2 j_3}^i(\psi) \dot{\psi}^{j_1} \dot{\psi}^{j_2} \dot{\psi}^{j_3} + K_{j_1 k_1}^i(\psi) \dot{\psi}^{j_1} \dot{\psi}^{k_1}$ where $G_{j_1 j_2 j_3}^i$ and $K_{j_1 k_1}^i$ are analytic on D we must have that $G_{j_1 j_2 j_3}^i(\psi) \dot{\psi}^{j_1} \dot{\psi}^{j_2} \dot{\psi}^{j_3} + K_{j_1 k_1}^i(\psi) \dot{\psi}^{j_1} \dot{\psi}^{k_1}$ is

analytic on $D \times \mathbb{R}^n \times \mathbb{R}^n \times \mathbb{R}$.

Fix $p_0 \in D$, $u_0, v_0 \in \mathbb{R}^n$, $\alpha_0 \in \mathbb{R}$.

Since $(p_0, \alpha_0 u_0, \alpha_0 v_0, 0) \in D \times \mathbb{R}^n \times \mathbb{R}^n \times \mathbb{R}$, then the Fundamental Theorem says that there exists an interval I of zero in \mathbb{R} such that $\psi^i(p_0, \alpha_0 u_0, \alpha_0 v_0, t)$ exists on I and satisfies initial conditions

$$\psi^i(p_0, \alpha_0 u_0, \alpha_0 v_0, 0) = p_0^i$$

$$\dot{\psi}^i(p_0, \alpha_0 u_0, \alpha_0 v_0, 0) = \alpha_0 u_0^i$$

$$\ddot{\psi}^i(p_0, \alpha_0 u_0, \alpha_0 v_0, 0) = \alpha_0^2 v_0^i$$

and also ψ^i is an analytic function in all variables p, u, v, t .

Since $\psi^i(p, u, v, t)$ is analytic, then on I we can write

$$\begin{aligned} \psi^i(p, u, v, t) &= p^i + \dot{\psi}^i(p, u, v, 0)t + \ddot{\psi}^i(p, u, v, 0) \frac{t^2}{2!} \\ &\quad + \dddot{\psi}^i(p, u, v, 0) \frac{t^3}{3!} + \dots \\ &\quad + \psi^{(n)i}(p, u, v, 0) \frac{t^n}{n!} + \dots \end{aligned}$$

$$\text{therefore } \psi^i(p, u, v, t) = p^i + u^i t + v^i \frac{t^2}{2!}$$

$$+ (G_{j_1 j_2 j_3}^i(p) u^{j_1} u^{j_2} u^{j_3} + K_{j_1 k_1}^i(p) u^{j_1} v^{k_1}) \frac{t^3}{3!} + \dots$$

$$+ [Y_{j_1 \dots j_n}^i(p) u^{j_1} \dots u^{j_n} + Y_{j_1 \dots j_{n-2} k_1}^i(p) u^{j_1} \dots u^{j_{n-2}} v^{k_1} + \dots$$

$$+ \left. \begin{array}{l} Y_{k_1 \dots k_{\frac{n}{2}}}^i(p) v^{k_1} \dots v^{k_{\frac{n}{2}}} \text{ if } n \text{ is even} \\ Y_{j_1 k_1 \dots k_{\frac{n-1}{2}}}^i(p) u^{j_1} v^{k_1} \dots v^{k_{\frac{n-1}{2}}} \text{ if } n \text{ is odd} \end{array} \right] \frac{t^n}{n!} + \dots$$

$$\begin{aligned}
\text{Thus, } \psi^i(p_0, \alpha_0 u_0, \alpha_0 v_0, t) &= p_0^i + \alpha_0 u_0^i t + \alpha_0^2 v_0^2 \frac{t^2}{2!} \\
&+ (G_{j_1 j_2 j_3}^i (p_0) \alpha_0^3 u_0^{j_1} u_0^{j_2} u_0^{j_3} + K_{j_1 k_1}^i (p_0) \alpha_0^3 u_0^{j_1} v_0^{k_1}) \frac{t^3}{3!} + \dots \\
&+ \left[Y_{j_1 \dots j_n}^i (p_0) \alpha_0^n u_0^{j_1} \dots u_0^{j_n} + Y_{j_1 \dots j_{n-2} k_1}^i (p_0) \alpha_0^n u_0^{j_1} \dots u_0^{j_{n-2}} v_0^{k_1} + \dots \right. \\
&\quad \left. + \begin{cases} Y_{k_1 \dots k_{\frac{n}{2}}}^i (p_0) \alpha_0^n v_0^{k_1} \dots v_0^{k_{\frac{n}{2}}} & \text{if } n \text{ is even} \\ Y_{j_1 k_1 \dots k_{\frac{n-1}{2}}}^i (p_0) \alpha_0^n u_0^{j_1} v_0^{k_1} \dots v_0^{k_{\frac{n-1}{2}}} & \text{if } n \text{ is odd} \end{cases} \right] \frac{t^n}{n!} + \dots \\
&= p_0^i + u_0^i (\alpha_0 t) + v_0^i \frac{(\alpha_0 t)^2}{2!} \\
&+ (G_{j_1 j_2 j_3}^i (p_0) u_0^{j_1} u_0^{j_2} u_0^{j_3} + K_{j_1 k_1}^i (p_0) u_0^{j_1} v_0^{k_1}) \frac{\alpha_0^3 t^3}{3!} + \dots \\
&+ [Y_{j_1 \dots j_n}^i (p_0) u_0^{j_1} \dots u_0^{j_n} + Y_{j_1 \dots j_{n-2} k_1}^i (p_0) u_0^{j_1} \dots u_0^{j_{n-2}} v_0^{k_1} + \dots \\
&\quad + \begin{cases} Y_{k_1 \dots k_{\frac{n}{2}}}^i (p_0) v_0^{k_1} \dots v_0^{k_{\frac{n}{2}}} & \text{if } n \text{ is even} \\ Y_{j_1 k_1 \dots k_{\frac{n-1}{2}}}^i (p_0) u_0^{j_1} v_0^{k_1} \dots v_0^{k_{\frac{n-1}{2}}} & \text{if } n \text{ is odd} \end{cases}] \frac{\alpha_0^n t^n}{n!} + \dots \\
&= \psi^i(p_0, u_0, v_0, \alpha_0 t) \quad (\text{Where the } Y^i \text{'s are defined on page 51})
\end{aligned}$$

That is, $\psi^i(p_0, \alpha_0 u_0, \alpha_0 v_0, t)$ exists if and only if $\psi^i(p_0, u_0, v_0, \alpha_0 t)$ exists and they are equal. Theorem 2.15 is proved.

Properties of $\psi(p,u,v,t)$

We have already proved that if $\vec{\psi}$ satisfies

$$\ddot{\psi}^i = G_{j_1 j_2 j_3}^i(\psi) \dot{\psi}^{j_1} \dot{\psi}^{j_2} \dot{\psi}^{j_3} + K_{j_1 k_1}^i(\psi) \dot{\psi}^{j_1} \ddot{\psi}^{k_1}$$

where $G_{j_1 j_2 j_3}^i$, $K_{j_1 k_1}^i$ are analytic on open subset D of R^n then $\psi(p, \alpha u, \alpha v, t)$ exists if and only if $\psi(p, u, v, \alpha t)$ exists and they are equal.

Using this fact, we can now show that ψ also has the following properties :

Property 1 Given $t_0 \in R$, $p_0 \in D$ then there exists neighbourhood U of the zero vector at p_0 such that $\forall u, v \in U$, $\psi(p_0, u, v, t_0)$ is defined.

Proof. Let t_0 be any point in R . Let p_0 be any initial point in D . Since $(p_0, 0, 0, 0)$ is a point on the domain of definition of \vec{H} , hence the Fundamental Theorem for Third order Ordinary Differential Equations implies that there exists a neighbourhood W of the zero vector at p_0 , and there exists an interval $I = (-r, r)$ such that $\psi(p_0, u, v, t)$ exists for all $u, v \in W$ and for all $t \in I$.

For any $t_0 \in R$, choose a real number $\alpha \neq 0$ such that $|\alpha t_0| < r$. Then $\alpha t_0 \in I$ and $\psi(p_0, u, v, \alpha t_0)$ exists for all $u, v \in W$. Since for $1 \leq i \leq n$, ψ^i satisfies $\psi^i(p, \alpha u, \alpha v, t) = \psi^i(p, u, v, \alpha t)$ for all $p \in D$, $u, v \in R^n$, $t \in J$, $\alpha \in R$.

Therefore, $\psi(p_0, \alpha u, \alpha v, t)$ exists for all $u, v \in W$. That is, $\psi(p_0, z, w, t)$ exists for all $z, w \in \alpha W$, $z = \alpha u$, $w = \alpha v$, and αW is a neighbourhood of zero vector at p_0 since $\alpha \neq 0$, then we are done.

Property 2 Given any compact neighbourhood U of the zero vector at p_0 then there exists a neighbourhood W of zero in R such that $\forall t \in W, \forall u, v \in U, \psi(p_0, u, v, t)$ exists.

Proof Let $B(\vec{0}_{p_0}, r_1) \supseteq U$. By the Fundamental Theorem of Ordinary Differential Equations, we know that there exists a ball $B(\vec{0}_{p_0}, r_2)$ and a neighbourhood W of 0 in R such that $\psi(p_0, u, v, t)$ exists $\forall u, v \in B(\vec{0}_{p_0}, r_2) \forall t \in W$.

Assume that the $B(\vec{0}_{p_0}, r_2)$ is a proper subset of $B(\vec{0}_{p_0}, r_1)$. To see this, choose $\alpha_0 \in R - \{0\}$ such that $|\alpha_0| < \frac{r_2}{r_1}$. For any $w \in B(\vec{0}_{p_0}, r_1)$, $|\alpha_0 w| \leq |\alpha_0| |r_1| < r_2$ so $\alpha_0 w \in B(\vec{0}_{p_0}, r_2)$ $\forall w \in B(\vec{0}_{p_0}, r_1)$. Since $\psi(p_0, u, v, t)$ exists $\forall v \in B(\vec{0}_{p_0}, r_2)$, $\forall t \in W$, hence $\psi(p_0, \alpha_0 u, \alpha_0 v, t)$ exist for all $u, v \in B(\vec{0}_{p_0}, r_1)$ for all $t \in W$. Since ψ satisfies $\psi^i(p, \alpha u, \alpha v, t) = \psi^i(p, u, v, \alpha t)$ $\forall p \in D, u, v \in R^n, \alpha \in R, t \in J$. Hence $\psi(p_0, u, v, \alpha_0 t)$ exists and $\psi(p_0, \alpha_0 u, \alpha_0 v, t) = \psi(p_0, u, v, \alpha_0 t)$.

Thus $\psi(p_0, u, v, \alpha t)$ exists for all $u, v \in B(\vec{0}_{p_0}, r_1)$ for all $t \in W$. That is $\psi(p_0, u, v, t^*)$ exists for all $u, v \in B(\vec{0}_{p_0}, r_1)$ for all $t^* \in \alpha W$. Then property 2 is proved.

Property 3 (Exponential property) Given initial point $p_0 \in D$ and $t_0 \in \mathbb{R} - \{0\}$, and a neighbourhood W of $\vec{0} = (0, 0, \dots, 0)$ in \mathbb{R}^{2n} such that $\vec{\psi}(p_0, u, v, t_0)$ is defined $\forall (u, v) \in W$ (We proved already that such a W exists in property 1). Fix $v = 0$, then $(u, 0) \mapsto \vec{\psi}(p_0, u, 0, t_0)$ is a bidifferential map of some open set of the zero vector onto an open set.

Proof Let \vec{h} be a map defined on $\Pi_2(W)$, where Π_2 is defined on pages 29, by $\vec{h}(u, 0) = \vec{\psi}(p_0, u, 0, t_0)$. Then \vec{h} is a C^1 function on $\Pi_2(W)$. Since $\psi^i(p_0, \alpha u, \alpha v, t_0) = \psi^i(p_0, u, v, \alpha t_0)$ differentiate with respect to α , this gives

$$u^{j_1} \frac{\partial \psi^i}{\partial u^{j_1}}(p_0, \alpha u, \alpha v, t_0) + 2\alpha v^{j_2} \frac{\partial \psi^i}{\partial v^{j_2}} = \psi^i(p_0, u, v, \alpha t_0) t_0.$$

Let $\alpha = 0$, we get

$$u^{j_1} \frac{\partial \psi^i}{\partial u^{j_1}}(p_0, 0, 0, t_0) = t_0 u^i = t_0 \delta_{j_1}^i u^{j_1} \quad \text{where } \delta_{j_1}^i = \begin{cases} 0, & i \neq j \\ 1, & i = j \end{cases}.$$

Therefore, $\frac{\partial}{\partial u^{j_1}} \psi^i(p_0, 0, 0, t_0) = t_0 \delta_{j_1}^i$ and

$$\begin{aligned}
 J_{\vec{h}}(0) &= \det \begin{vmatrix} \frac{\partial \psi^1}{\partial u^1}(p_0, 0, 0, t_0) & \frac{\partial \psi^1}{\partial u^2}(p_0, 0, 0, t_0) & \dots & \frac{\partial \psi^1}{\partial u^n}(p_0, 0, 0, t_0) \\ \frac{\partial \psi^2}{\partial u^1}(p_0, 0, 0, t_0) & \frac{\partial \psi^2}{\partial u^2}(p_0, 0, 0, t_0) & \dots & \frac{\partial \psi^2}{\partial u^n}(p_0, 0, 0, t_0) \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial \psi^n}{\partial u^1}(p_0, 0, 0, t_0) & \frac{\partial \psi^n}{\partial u^2}(p_0, 0, 0, t_0) & \dots & \frac{\partial \psi^n}{\partial u^n}(p_0, 0, 0, t_0) \end{vmatrix} \\
 &= \det \begin{vmatrix} t_0 & & & 0 \\ & \ddots & & \\ & & & t_0 \end{vmatrix} = t_0^n \neq 0.
 \end{aligned}$$

By the Inverse Function Theorem, there exist two open sets $V \subseteq \Pi_a(W)$ of the zero vector and $W^1 \subseteq \mathbb{R}^n$ such that \vec{h} is 1-1, differentiable on V onto W^1 and \vec{h}^{-1} exists and is also differentiable. Thus \vec{h} is a bidifferential map of V onto W^1 .

Before we have the corollary to property 3), we need the following theorem.

Theorem 2.16 Let $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be continuously differentiable in an open set containing a , where $m \leq n$. If $f(a) = 0$ and the $n \times m$ matrix $(D_1 f^j(a))$ has rank m , then there is an open set $A \subset \mathbb{R}^n$ and a differentiable function $h : A \rightarrow \mathbb{R}^n$ with differentiable inverse such that

$$f \circ h(x^1, \dots, x^n) = (x^{n-m+1}, \dots, x^n).$$

For the proof, see reference [10] page 43.

Corollary The same hypothesis as in Property 3 except that we do not fix $v = 0$. Then the map $\vec{k}(u,v) = \vec{\psi}(p_0, u, v, t_0)$ is locally open map at $(0,0)$, that is there exist neighbourhoods W^1 of $(0,0)$ in W and U in R^n such that \vec{k} restrict on W^1 is onto U and is an open map.

Proof The Jacobian matrix of \vec{k} at $(0,0)$ is the $n \times (2n)$ matrix

$$\begin{bmatrix} \frac{\partial \psi^1}{\partial u^1}(p_0, 0, 0, t_0) \dots \frac{\partial \psi^1}{\partial u^n}(p_0, 0, 0, t_0) & \frac{\partial \psi^1}{\partial v^1}(p_0, 0, 0, t_0) \dots \frac{\partial \psi^1}{\partial v^n}(p_0, 0, 0, t_0) \\ \vdots \\ \frac{\partial \psi^n}{\partial u^1}(p_0, 0, 0, t_0) \dots \frac{\partial \psi^n}{\partial u^n}(p_0, 0, 0, t_0) & \frac{\partial \psi^n}{\partial v^1}(p_0, 0, 0, t_0) \dots \frac{\partial \psi^n}{\partial v^n}(p_0, 0, 0, t_0) \end{bmatrix}$$

and the $n \times n$ matrix $\frac{\partial \psi^j}{\partial u^j}(p_0, 0, 0, t_0)$ has non-zero determinant as we already showed. Therefore the Jacobian matrix has maximal rank n . Thus \vec{k} is locally open map by Theorem 2.16.

Property 4. Given $p_0 \in D$, v_0, u_0 at p_0 and any real number $\alpha_0 \neq 0$, then the solution curve $\psi(p_0, u_0, v_0, t)$ with initial values p_0, u_0, v_0 and the solution curve $\psi(p_0, \alpha_0 u_0, \alpha_0 v_0, t)$ having initial values $p_0, \alpha_0 v_0, \alpha_0 u_0$ agree as point sets, that is the images of the two functions coincide.

Proof By the Fundamental Theorem of Ordinary Differential Equations, $\psi(p_0, \alpha_0 u_0, \alpha_0 v_0, t)$ is defined on some open interval I_1 of zero in R and $\psi(p_0, u_0, v_0, t)$ is defined on some open interval I_2 of zero in R .

Let $C_1 = \{\psi(p_0, \alpha_0 u_0, \alpha_0 v_0, t) \mid \psi(p_0, \alpha_0 u_0, \alpha_0 v_0, t) \text{ is defined}\}$.

Let $C_2 = \{\psi(p_0, u_0, v_0, t) \mid \psi(p_0, u_0, v_0, t) \text{ is defined}\}$.

To show $C_1 \subseteq C_2$, let Q_1 be any point in C_1 . Then there exists $t_1 \in R$ such that $Q_1 = \psi(p_0, \alpha_0 u_0, \alpha_0 v_0, t_1)$

$$\text{Now } \psi(p_0, \alpha_0 u_0, \alpha_0 v_0, t_1) = \psi(p_0, u_0, v_0, \alpha_0 t_1) \quad \forall p_0 \in D$$

So let $t_2 = \alpha_0 t_1$. Thus we see that there exists $t_2 \in R$ such that $\psi(p_0, u_0, v_0, t_2)$ is defined, that is, there exists $t_2 \in R$ such that $Q_1 = \psi(p_0, u_0, v_0, t_2)$ so $Q_1 \in C_2$.

Let Q_2 be any point in C_2 . Then there exists $t_1 \in R$ such that $Q_2 = \psi(p_0, u_0, v_0, t_1)$. Then $\psi(p_0, u_0, v_0, \alpha_0 \frac{t_1}{\alpha_0})$ is defined.

Hence $\psi(p_0, \alpha_0 u_0, \alpha_0 v_0, \frac{t_1}{\alpha_0})$ is defined and

$$\psi(p_0, \alpha_0 u_0, \alpha_0 v_0, \frac{t_1}{\alpha_0}) = \psi(p_0, u_0, v_0, t_1)$$

Therefore let $t_2 = \frac{t_1}{\alpha_0}$. So we get that $\psi(p_0, \alpha_0 u_0, \alpha_0 v_0, t_2)$

is defined and $\psi(p_0, \alpha_0 u_0, \alpha_0 v_0, t_2) = Q_2$

i.e. $Q_2 \in C_1$. Thus $C_1 = C_2$. The proof is complete.

We conjecture that for any $n > 3$, there exists unique form of a differential equation which satisfies an analogous functional equation and whose solution curves have the above properties. The same type of proofs used above should give this result. In fact, the differential equation should be the one which in order n has exactly n dots on the RHS. Also, we should get the exact same four properties that we proved for the case $n = 3$.

