#### CHAPTER VI

SOLUTIONS OF g(x-y) = g(x)g(y) + f(x)f(y) AND  $g(\frac{x}{y}) = g(x)g(y) + f(x)f(y)$ .

In this chapter we shall determine all continuous solution of

$$(A_*) \qquad g(x-y) = g(x)g(y) + f(x)f(y)$$

on  $\mathbb{R}^n$  to  $\mathbb{R}$  , and all continuous solutions of

$$(A^*) \qquad g(\frac{x}{y}) \qquad = \qquad g(x)g(y) + f(x)f(y)$$

on  $\mathbb{R}^*$  to  $\mathbb{C}$  . Furthermore we shall show that discontinuous solutions of  $(A_*)$  and  $(A^*)$  also exist.

### 6.1 Continuous Solution of g(x-y) = g(x)g(y) + f(x)f(y) on $\mathbb{R}^n$

Let  $f,g:\mathbb{R}^{\frac{n}{}}\to\mathbb{R}$  be continuous functions such that f,g satisfy

$$(A_*)$$
 =  $g(x)g(y) + f(x)f(y)$ ,

for all x,y in  $\mathbb{R}^n$ . We shall characterize all such functions f,g. To do this, we may consider f,g as functions on the topological group  $(\mathbb{R}^n,+)$  into the topological field  $(\mathbb{R},+,\cdot)$ . Since  $\mathbb{R}^n$  is also the topological vector space over  $\mathbb{R}$ , hence by Corollary 4.9, the continuous solutions of  $(A_*)$  must be those and only those (f,g) of the forms:

(6.1.1) 
$$f(x) = b$$
,  $g(x) = a$  for all  $x$  in  $\mathbb{R}^n$ , where  $a,b \in [0, 1)$  and  $b = \sqrt{a-a^2}$ ; or

(6.1.2) 
$$f(x) = \frac{h(x) - h(x^{-1})}{2i}$$
,  $g(x) = \frac{h(x) + h(x^{-1})}{2}$ 

where h is a continuous homomorphism from  $\mathbb{R}^n$  to  $\bigwedge$ . By Theorem 5.3.6, h(x) must be of the form h(x) =  $e^{i(k_1x_1+\cdots+k_nx_n)}$  where  $x=(x_1,\cdots,x_n)$  and  $k_i$ 's are real numbers. Hence f,g in (6.1.2) must be of the form

$$f(x) = \frac{i(k_1x_1 + \cdots + k_nx_n) - i(k_1x_1 + \cdots + k_nx_n)}{2i}$$

$$= \sin(k_1x_1 + \cdots + k_nx_n)$$

and

$$g(x) = \frac{e^{i(k_1x_1 + \cdots + k_nx_n + e^{-i(k_1x_1 + \cdots + k_nx_n)})}}{2}$$

$$= \cos(k_1x_1 + \cdots + k_nx_n)$$

where  $x = (x_1, \dots, x_n)$  and k!s are real numbers.

In particular, when n = 1, the continuous solutions of  $(A_*)$  are those and only those (f,g) of the forms :

(6.1.3) 
$$f(x) = b$$
,  $g(x) = a$  for all  $x$  in  $\mathbb{R}$ , where  $a,b \in [0,1)$  and  $b = \sqrt{a-a^2}$ ; or

$$(6.1.4)$$
  $f(x) = \sin(kx)$ ,  $g(x) = \cos(kx)$ 

where k is a real number.

# 6.2 Continuous Solution of $g(\frac{x}{y}) = g(x)g(y) + g(x)f(y)$ on $\mathbb{R}^*$

Let  $f,g:\mathbb{R}^* \to \mathbb{C}$  be continuous functions such that f,g satisfy

(A\*) 
$$g(\frac{x}{y}) = g(x)g(y) + f(x)f(y)$$
,

for all x,y in  $\mathbb{R}^*$ . We shall characterize all such functions f,g.To do this we may consider f,g as functions on the topological group ( $\mathbb{R}^*$ ,.) into the topological field ( $\mathbb{C}$ ,+,.). It can be shown that ( $\mathbb{R}^+$ ,.) is the only subgroup of index 2 in  $\mathbb{R}^*$ , and that ( $\mathbb{R}^*$ ,.) has no subgroup of index 4. Hence by Theorem 4.5, the continuous solutions of ( $\mathbb{A}^*$ ) must be those and only those (f,g) of the forms:

(6.2.1) f(x) = b, g(x) = a for all x in  $\mathbb{R}^*$  where a, b are elements of  $\mathbb{C}$  such that  $a \neq 1$ ,  $a - a^2 = b^2$ ; or

(6.2.2) 
$$f(x) = \begin{cases} b, x \in \mathbb{R}^+ \\ -b, x \in \mathbb{R}^- \end{cases}, g(x) = \begin{cases} a, x \in \mathbb{R}^+ \\ -a, x \in \mathbb{R}^- \end{cases}$$

where a,b are elements of e such that  $a \neq 1$ ,  $a - a^2 = b^2$ ; or

(6.2.3) 
$$f(x) = \begin{cases} 0, & x \in \mathbb{R}^+ \\ d, & x \in \mathbb{R}^- \end{cases}, g(x) = \begin{cases} 1, & x \in \mathbb{R}^+ \\ c, & x \in \mathbb{R}^- \end{cases}$$

where c,d are elements of C such that  $c \neq 1$ ,  $c^2 + d^2 = 1$ ; or

(6.2.4) 
$$f(x) = \frac{h(x) - h(x^{-1})}{2i}, g(x) = \frac{h(x) + h(x^{-1})}{2}$$

where h is a continuous homomorphism from  $\mathbb{R}^*$  to  $\mathbb{C}^*$  . By Theorem 5.4.2, we see that

$$h(x) = |x|^c$$
 for all x in  $\mathbb{R}^*$ 

or

$$h(x) = \begin{cases} |x|^{c} & \text{if } x \neq 0 \\ -|x|^{c} & \text{if } x \neq 0 \end{cases}$$

where c is a complex number. Hence f,g in (6.2.4) must be of the forms :

(6.2.4.a) 
$$f(x) = \frac{|x|^c - |x|^{-c}}{2i}$$
,  $g(x) = \frac{|x|^c + |x|^{-c}}{2}$  for all x in R,

$$(6.2.4.b) f(x) = \begin{cases} \frac{|x|^c - |x|^{-c}}{2i} & \text{if } x = 0 \\ \frac{|x|^{-c} - |x|^c}{2i} & \text{if } x < 0 \end{cases}$$
 and

$$g(x) = \begin{cases} \frac{|x|^{c} + |x|^{-c}}{2} & \text{if } x > 0 \\ -\frac{|x|^{c} + |x|^{-c}}{2} & \text{if } x < 0 \end{cases}$$

where c is a complex number.

#### 6.3 Existence of Discontinuous Solution of g(x-y) = g(x)g(y)+f(x)f(y)

Let  $f,g: \mathbb{R}^{\frac{n}{2}} \to \mathbb{R}$  be functions such that f,g satisfy

$$(A_x) \qquad g(x-y) = g(x)g(y) + f(x)f(y)$$

for all x,y in  $\mathbb{R}^n$ . Since  $\mathbb{R}^n$  has no subgroup of index 2, hence, by Remark 3.31, any solution (f,g) of  $(A_*)$  on  $\mathbb{R}^n$  to  $\mathbb{R}$  must be of the forms:

(6.3.1) 
$$f(x) = b, g(x) = a \text{ for all } x \text{ in } \mathbb{R}^n, \text{ where}$$
 
$$a,b \in [0,1) \text{ and } b = \sqrt{a-a^2}; \text{ or}$$

(6.3.2) 
$$f(x) = \frac{h(x) - h(x^{-1})}{2i}, g(x) = \frac{h(x) + h(x^{-1})}{2}$$

where h is a homomorphism from  $\mathbb{R}^n$  to  $\triangle$ . Observe that each solution of the form (6.3.1) is continuous. Hence any discontinuous solution of  $(A_*)$ , if exists, must be of the form (6.3.2). By Theorem 4.4, the solution of the form (6.3.2) is continuous if and only if h is continuous. Hence any discontinuous h:  $\mathbb{R}^n \longrightarrow \triangle$  will provide a discontinuous solution (f,g) by (6.3.2). We have seen from Section 5.5 that such discontinuous homomorphism exists. Hence a discontinuous solution (f,g) of  $(A_*)$  on  $\mathbb{R}^n$  to  $\mathbb{R}$  exists.

## 6.4 Existence of Discontinuous Solution of $g(\frac{x}{y}) = g(x)g(y) + f(x)f(y)$

Let  $f,g: \mathbb{R} \xrightarrow{*} \mathbb{C}$  be functions such that f,g satisfy  $g(\frac{x}{y}) = g(x)g(y) + f(x)f(y)$ 

for all x,y in  $\mathbb{R}^*$ . Since  $\mathbb{R}^+$  is the only subgroup of index 2 of  $\mathbb{R}^*$ , and  $\mathbb{R}^*$  has no subgroup of index 4, hence by Theorem 3.30 any solution of  $(A^*)$  on  $\mathbb{R}^*$  to  $\mathbb{C}$  must be of the forms:

(6.4.1) f(x) = b, g(x) = a for all x in  $\mathbb{R}^*$ , where a,b are elements of C such that  $a \neq 1$ ,  $a-a^2 = b^2$ ; or

(6.4.2) 
$$f(x) = \begin{cases} b, & x \in \mathbb{R}^+ \\ -b, & x \in \mathbb{R}^- \end{cases}, g(x) = \begin{cases} a, & x \in \mathbb{R}^+ \\ -a, & x \in \mathbb{R}^- \end{cases}$$

where a,b are elements of C such that  $a \neq 1$ ,  $a-a^2 = b^2$ ; or

(6.4.3) 
$$f(x) = \begin{cases} 0, & x \in \mathbb{R}^+ \\ d, & x \in \mathbb{R}^- \end{cases}, g(x) = \begin{cases} 1, & x \in \mathbb{R}^+ \\ c, & x \in \mathbb{R}^- \end{cases}$$

where c,d are elements of C such that  $c \neq 1$ ,  $c^2 + d^2 = 1$ ; or (6.4.4)  $f(x) = \frac{h(x) - h(x^{-1})}{2i}$ ,  $g(x) = \frac{h(x) + h(x^{-1})}{2}$ 

where h is a homomorphism from !R into C .

Observe that each solution of the form (6.4.1) is continuous. Since  $\mathbb{R}^+$  is an open subgroup of  $\mathbb{R}^*$ , hence by Corollary 4.3 each solution of the forms (6.4.2) and (6.4.3) is continuous. Hence any discontinuous solution of  $(A^*)$ , if exist, must be of the form (6.4.4). By Theorem 4.4, the solution of the form (6.4.4) is continuous if and only if h is continuous. Hence any discontinuous h:  $\mathbb{R}^* \to \mathbb{C}^*$  will provide a discontinuous solution  $(\mathbf{f},\mathbf{g})$  by (6.4.4). The existence of discontinuous of such h is already discussed in Theorem 5.6.4. Hence a discontinuous solution  $(\mathbf{f},\mathbf{g})$  of  $(\mathbb{A}^*)$  on  $\mathbb{R}^*$  to  $\mathbb{C}$  exists.