



## CHAPTER IV

### THE APPLICATION OF HYPERCOMPLEX NUMBER SYSTEMS

Hypercomplex numbers may be used to prove the following identities for real numbers.

$$(4.1) \quad (a_0^2 + a_1^2)(b_0^2 + b_1^2) = (a_0b_0 - a_1b_1)^2 + (a_1b_0 + a_0b_1)^2 \quad (10, p. 224)$$

$$(4.2) \quad (a_0^2 + a_1^2 + a_2^2 + a_3^2)(b_0^2 + b_1^2 + b_2^2 + b_3^2) \\ = (a_0b_0 - a_1b_1 - a_2b_2 - a_3b_3)^2 \\ + (a_1b_0 + a_0b_1 - a_3b_2 + a_2b_3)^2 \\ + (a_2b_0 + a_3b_1 + a_0b_2 - a_1b_3)^2 \\ + (a_3b_0 - a_2b_1 + a_1b_2 + a_0b_3)^2 \quad (10, p.277)$$

$$(4.3) \quad (a_0^2 + a_1^2 + \dots + a_7^2)(b_0^2 + b_1^2 + \dots + b_7^2) \\ = (a_0b_0 - a_1b_1 - a_2b_2 - a_3b_3 - a_4b_4 - a_5b_5 - a_6b_6 - a_7b_7)^2 \\ + (a_1b_0 + a_0b_1 - a_3b_2 + a_2b_3 - a_5b_4 + a_4b_5 - a_7b_6 + a_6b_7)^2 \\ + (a_2b_0 + a_3b_1 + a_0b_2 - a_1b_3 + a_6b_4 - a_7b_5 - a_4b_6 + a_5b_7)^2 \\ + (a_3b_0 - a_2b_1 + a_1b_2 + a_0b_3 - a_7b_4 - a_6b_5 + a_5b_6 + a_4b_7)^2 \\ + (a_4b_0 + a_5b_1 - a_6b_2 + a_7b_3 + a_0b_4 - a_1b_5 + a_2b_6 - a_3b_7)^2 \\ + (a_5b_0 - a_4b_1 + a_2b_2 + a_6b_3 + a_1b_4 + a_0b_5 - a_3b_6 - a_2b_7)^2 \\ + (a_6b_0 + a_7b_1 + a_4b_2 - a_5b_3 - a_2b_4 + a_3b_5 + a_0b_6 - a_1b_7)^2 \\ + (a_7b_0 - a_6b_1 - a_5b_2 - a_4b_3 + a_3b_4 + a_2b_5 + a_1b_6 + a_0b_7)^2$$

1. Proof of 4.1 with the help of complex numbers. Let

Let  $x = a_0 + ia_1$  and  $y = b_0 + ib_1$  be two complex numbers, then their complex conjugates are  $\bar{x} = a_0 - ia_1$  and  $\bar{y} = b_0 - ib_1$ .

$$\begin{aligned}
\text{Since } (a_0^2 + a_1^2)(b_0^2 + b_1^2) &= |X|^2 |Y|^2 \\
&= (X \bar{X})(Y \bar{Y}) \dots\dots\dots(\text{ch. II}) \\
&= X (\bar{X} Y) \bar{Y} \\
&= X (Y \bar{X}) \bar{Y} \\
&= (X Y) \overline{(X Y)} \\
&= |XY|^2
\end{aligned}$$

$$\text{Therefore } (a_0^2 + a_1^2)(b_0^2 + b_1^2) = (a_0 b_0 - a_1 b_1)^2 + (a_1 b_0 + a_0 b_1)^2$$

Other equivalent formulae may also be obtained by changing the sign of one or more of the numbers,  $a_0, a_1, b_0, b_1$ .

For example, if  $b_1$  is replaced by  $(-b_1)$  we obtain

$$(a_0^2 + a_1^2)(b_0^2 + b_1^2) = (a_0 b_0 + a_1 b_1)^2 + (a_1 b_0 - a_0 b_1)^2.$$

2. Proof of (4.2) with the help of quaternions.

Let  $x = a_0 + ia_1 + ja_2 + ka_3$  and  $y = b_0 + ib_1 + jb_2 + kb_3$  be two quaternions, then their quaternion conjugates are

$$\bar{x} = a_0 - ia_1 - ja_2 - ka_3 \quad \text{and} \quad \bar{y} = b_0 - ib_1 - jb_2 - kb_3.$$

$$\begin{aligned}
\text{Since } (a_0^2 + a_1^2 + a_2^2 + a_3^2)(b_0^2 + b_1^2 + b_2^2 + b_3^2) &= |X|^2 |Y|^2 \\
&= (X \bar{X})(Y \bar{Y}) \dots\dots\dots(\text{ch. II}) \\
&= \{Y (X \bar{X})\} \bar{Y} \dots\dots\dots(\text{commute with real numbers}) \\
&= \{(Y X) (\bar{X} \bar{Y})\} \dots\dots\dots(\text{associative}) \\
&= (Y X) \overline{(Y X)} \dots\dots\dots(\text{ch. II}) \\
&= |Y X|^2
\end{aligned}$$

$$\begin{aligned}
\text{Therefore } (a_0^2 + \dots\dots\dots a_3^2)(b_0^2 + \dots\dots\dots b_3^2) \\
&= (a_0 b_0 - a_1 b_1 - a_2 b_2 - a_3 b_3)^2 \\
&\quad + (a_1 b_0 + a_0 b_1 - a_3 b_2 + a_2 b_3)^2 \\
&\quad + (a_2 b_0 + a_3 b_1 + a_0 b_2 - a_1 b_3)^2 \\
&\quad + (a_3 b_0 - a_2 b_1 + a_1 b_2 + a_0 b_3)^2
\end{aligned}$$

Other equivalent formulae may also be obtained by changing the sign of one or more of the numbers.

For example, if  $b_1, b_2, b_3$  are replaced by  $-b_1, -b_2, -b_3$ , we get

$$\begin{aligned} |X|^2 |Y|^2 &= (a_0 b_0 + a_1 b_1 + a_2 b_2 + a_3 b_3)^2 \\ &+ (a_1 b_0 - a_0 b_1 + a_3 b_2 - a_2 b_3)^2 \\ &+ (a_2 b_0 - a_3 b_1 - a_0 b_2 + a_1 b_3)^2 \\ &+ (a_3 b_0 + a_2 b_1 - a_1 b_2 - a_0 b_3)^2 \end{aligned}$$

3. Proof of (4.3) with the help of Cayley numbers.

Let  $x = \sum_0^7 e_i a_i$  and  $y = \sum_0^7 e_i b_i$  be two Cayley numbers, then their conjugates are  $\bar{x} = e_0 a_0 - \sum_1^7 e_i a_i$  and  $\bar{y} = e_0 b_0 - \sum_1^7 e_i b_i$ .

$$\begin{aligned} \text{First we have, } \sum_0^7 a_i^2 \sum_0^7 b_i^2 &= |X|^2 |Y|^2 \\ &= (X \bar{X})(Y \bar{Y}) = \left\{ (X \bar{X}) Y \right\} \bar{Y} \\ &= \left\{ Y (X \bar{X}) \right\} \bar{Y}; \end{aligned}$$

Note:

The last two steps depend on the fact that  $X\bar{X}$  is real and that the associative and commutative laws hold for the multiplication of  $X\bar{X}$  <sup>with</sup> Cayley numbers.

$$\begin{aligned} Y (X \bar{X})^* &= \sum_0^7 e_i b_i \left[ \sum_0^7 e_i a_i (e_0 a_0 - \sum_1^7 e_i a_i) \right] \\ &= \sum_0^7 e_i b_i \left[ \sum_0^7 e_i a_i e_0 a_0 - \sum_0^7 e_i a_i \sum_1^7 e_i a_i \right] \\ &= \left[ \sum_0^7 e_i b_i \left( \sum_0^7 e_i a_i e_0 a_0 \right) \right] - \left[ \sum_0^7 e_i b_i \left( \sum_0^7 e_i a_i \sum_1^7 e_i a_i \right) \right] \\ &= \left[ \left( \sum_0^7 e_i b_i \sum_0^7 e_i a_i \right) e_0 a_0 \right] - \left[ \left( \sum_0^7 e_i b_i \sum_0^7 e_i a_i \right) \sum_1^7 e_i a_i \right]^* \\ &= \left( \sum_0^7 e_i b_i \sum_0^7 e_i a_i \right) (e_0 a_0 - \sum_1^7 e_i a_i) \\ &= (Y X) \bar{X} \end{aligned}$$



$$I. \text{ Lemma 1: } \sum_{o \ i \ i}^7 e \ b \ (\sum_{o \ i \ i}^7 e \ a \ \sum_{o \ i \ i}^7 e \ a) = (\sum_{o \ i \ i}^7 e \ b \ \sum_{o \ i \ i}^7 e \ a) \sum_{o \ i \ i}^7 e \ a$$

Proof

$$\begin{aligned} \text{Left hand side} &= \sum_{o \ i \ i}^7 e \ b \ (\sum_{o \ i \ i}^7 e \ a \ \sum_{o \ i \ i}^7 e \ a) \\ &= \sum_{o \ i \ i}^7 e \ b \ (-\sum_{o \ i \ i}^7 a^2 + a \sum_{o \ i \ i}^7 e \ a) \\ &= -\sum_{o \ i \ i}^7 a^2 (\sum_{o \ i \ i}^7 e \ b) + a (\sum_{o \ i \ i}^7 e \ b \ \sum_{o \ i \ i}^7 e \ a) \\ &= -\sum_{o \ i \ i}^7 a^2 (\sum_{o \ i \ i}^7 e \ b) + a \left[ -\sum_{o \ i \ i}^7 b \ a + b \sum_{o \ i \ i}^7 e \ a + \sum_{o \ i \ i}^7 e \ a \right] \end{aligned}$$

$$\text{where } A_1 = (-b_{32}a + b_{23}a - b_{76}a + b_{67}a - b_{54}a + b_{45}a)$$

$$A_2 = (b_{31}a - b_{13}a - b_{75}a + b_{57}a + b_{64}a - b_{46}a)$$

$$A_3 = (-b_{21}a + b_{12}a - b_{74}a + b_{47}a - b_{65}a + b_{56}a)$$

$$A_4 = (b_{51}a - b_{15}a - b_{62}a + b_{26}a + b_{73}a - b_{37}a)$$

$$A_5 = (-b_{41}a + b_{14}a + b_{63}a - b_{36}a + b_{72}a - b_{27}a)$$

$$A_6 = (b_{42}a - b_{24}a - b_{53}a + b_{35}a + b_{71}a - b_{17}a)$$

$$A_7 = (-b_{43}a + b_{34}a - b_{52}a + b_{25}a - b_{61}a + b_{16}a)$$

$$= -\sum_{o \ i \ i}^7 a^2 (\sum_{o \ i \ i}^7 e \ b) - a \sum_{o \ i \ i}^7 b \ a + a \ b \ (\sum_{o \ i \ i}^7 e \ a) + a \ (\sum_{o \ i \ i}^7 e \ A_i)$$

$$\text{Right hand side} = (\sum_{o \ i \ i}^7 e \ b \ \sum_{o \ i \ i}^7 e \ a) \sum_{o \ i \ i}^7 e \ a$$

$$= \left[ a \ b - \sum_{o \ i \ i}^7 b \ a + b \ \sum_{o \ i \ i}^7 e \ a + \sum_{o \ i \ i}^7 e \ A_i + a \ \sum_{o \ i \ i}^7 e \ b \right] \sum_{o \ i \ i}^7 e \ a$$

$$= a \ b \ (\sum_{o \ i \ i}^7 e \ a) - \sum_{o \ i \ i}^7 b \ a \ (\sum_{o \ i \ i}^7 e \ a) - b \ \sum_{o \ i \ i}^7 a^2 + \sum_{o \ i \ i}^7 e \ A_i \ \sum_{o \ i \ i}^7 e \ a$$

$$- a \ \sum_{o \ i \ i}^7 b \ a + a \ \sum_{o \ i \ i}^7 e \ A_i$$

$$= a \ b \ (\sum_{o \ i \ i}^7 e \ a) - a \ \sum_{o \ i \ i}^7 b \ a + \left[ (\sum_{o \ i \ i}^7 e \ A_i \ \sum_{o \ i \ i}^7 e \ a + a \ \sum_{o \ i \ i}^7 e \ A_i \right.$$

$$\left. - \sum_{o \ i \ i}^7 b \ a \ (\sum_{o \ i \ i}^7 e \ a) - b \ \sum_{o \ i \ i}^7 a^2 \right]$$

$$\begin{aligned}
&= a_{oo} b_{oo} \left( \sum_{l, i, i}^7 e_{i, i} a_i \right) - a_{oo} \sum_{l, i, i}^7 b_{i, i} a_i + \left( \sum_{l, i, i}^7 e_{i, i} A_i \sum_{o, i, i}^7 e_{i, i} a_i \right. \\
&\quad \left. - \sum_{l, i, i}^7 b_{i, i} a_i \sum_{l, i, i}^7 e_{i, i} a_i - b_{oo} \sum_{l, i, i}^7 a_i^2 \right) \\
&= a_{oo} b_{oo} \left( \sum_{l, i, i}^7 e_{i, i} a_i \right) - a_{oo} \sum_{l, i, i}^7 b_{i, i} a_i + \left( a_{oo} \sum_{l, i, i}^7 e_{i, i} A_i - \sum_{l, i, i}^7 a_i^2 \sum_{o, i, i}^7 e_{i, i} b_i \right) \\
&= - \sum_{l, i, i}^7 a_i^2 \left( \sum_{o, i, i}^7 e_{i, i} b_i \right) - a_{oo} \sum_{l, i, i}^7 b_{i, i} a_i + a_{oo} b_{oo} \left( \sum_{l, i, i}^7 e_{i, i} a_i \right) + a_{oo} \left( \sum_{l, i, i}^7 e_{i, i} A_i \right)
\end{aligned}$$

Therefore  $\sum_{o, i, i}^7 e_{i, i} b_i \left( \sum_{o, i, i}^7 e_{i, i} a_i \sum_{l, i, i}^7 e_{i, i} a_i \right) = \left( \sum_{o, i, i}^7 e_{i, i} b_i \sum_{o, i, i}^7 e_{i, i} a_i \right) \sum_{l, i, i}^7 e_{i, i} a_i$

Lemma 2:  $\left( \left( \sum_{o, i, i}^7 e_{i, i} b_i \sum_{o, i, i}^7 e_{i, i} a_i \right) \sum_{l, i, i}^7 e_{i, i} a_i \right) \sum_{l, i, i}^7 e_{i, i} b_i$

$$= \left( \sum_{o, i, i}^7 e_{i, i} b_i \sum_{o, i, i}^7 e_{i, i} a_i \right) \left( \sum_{l, i, i}^7 e_{i, i} a_i \sum_{l, i, i}^7 e_{i, i} b_i \right)$$

Proof

Left handside =  $\left[ - \sum_{l, i, i}^7 a_i^2 \left( \sum_{o, i, i}^7 e_{i, i} b_i \right) - a_{oo} \sum_{l, i, i}^7 b_{i, i} a_i + a_{oo} b_{oo} \left( \sum_{l, i, i}^7 e_{i, i} a_i \right) + a_{oo} \left( \sum_{l, i, i}^7 e_{i, i} A_i \right) \right] \sum_{l, i, i}^7 e_{i, i} b_i$

$$= - a_{oo} \sum_{l, i, i}^7 b_{i, i} a_i \left( \sum_{l, i, i}^7 e_{i, i} b_i \right) - \sum_{l, i, i}^7 a_i^2 \left( \sum_{o, i, i}^7 e_{i, i} b_i \sum_{l, i, i}^7 e_{i, i} b_i \right) +$$

$$a_{oo} b_{oo} \left( \sum_{l, i, i}^7 e_{i, i} a_i \sum_{l, i, i}^7 e_{i, i} b_i \right) + a_{oo} \left( \sum_{l, i, i}^7 e_{i, i} A_i \sum_{l, i, i}^7 e_{i, i} b_i \right)$$

$$= - a_{oo} \sum_{l, i, i}^7 b_{i, i} a_i \left( \sum_{l, i, i}^7 e_{i, i} b_i \right) - \sum_{l, i, i}^7 a_i^2 \left( b_{oo} \sum_{l, i, i}^7 e_{i, i} b_i - \sum_{l, i, i}^7 b_i^2 \right) +$$

$$a_{oo} b_{oo} \left( - \sum_{l, i, i}^7 a_i b_i - \sum_{l, i, i}^7 e_{i, i} A_i \right) + a_{oo} \left( \sum_{l, i, i}^7 e_{i, i} A_i \sum_{l, i, i}^7 e_{i, i} b_i \right)$$

Right handside =  $\left( a_{oo} b_{oo} + b_{oo} \sum_{l, i, i}^7 e_{i, i} a_i + a_{oo} \sum_{l, i, i}^7 e_{i, i} b_i - \sum_{l, i, i}^7 b_{i, i} a_i + \sum_{l, i, i}^7 e_{i, i} A_i \right)$

$$\left( - \sum_{l, i, i}^7 a_i b_i - \sum_{l, i, i}^7 e_{i, i} A_i \right)$$

$$= a_{oo} b_{oo} \left( - \sum_{l, i, i}^7 a_i b_i - \sum_{l, i, i}^7 e_{i, i} A_i \right) - a_{oo} \sum_{l, i, i}^7 b_{i, i} a_i \left( \sum_{l, i, i}^7 e_{i, i} b_i \right)$$

$$- a_{oo} \sum_{l, i, i}^7 e_{i, i} b_i \sum_{l, i, i}^7 e_{i, i} A_i + \left( - b_{oo} \sum_{l, i, i}^7 b_{i, i} a_i \sum_{l, i, i}^7 e_{i, i} a_i - b_{oo} \sum_{l, i, i}^7 e_{i, i} a_i \sum_{l, i, i}^7 e_{i, i} A_i \right) + \left[ \left( \sum_{l, i, i}^7 b_{i, i} a_i \right)^2 - \left( \sum_{l, i, i}^7 e_{i, i} A_i \right)^2 \right]$$

$$\begin{aligned}
&= a_0 b_0 \left( -\sum_1^7 a_i b_i - \sum_1^7 e_i A_i \right) - a_0 \sum_1^7 b_i a_i \left( \sum_1^7 e_i b_i \right) \\
&\quad - a_0 \sum_1^7 e_i b_i \sum_1^7 e_i A_i + \left( b_0^2 \sum_1^7 a_i^2 - b_0 \sum_1^7 a_i^2 \sum_1^7 e_i b_i \right) \\
&\quad + \left\{ \left( \sum_1^7 b_i a_i \right)^2 - \sum_1^7 A_i^2 \right\} \\
&= a_0 b_0 \left( -\sum_1^7 a_i b_i - \sum_1^7 e_i A_i \right) - a_0 \sum_1^7 b_i a_i \left( \sum_1^7 e_i b_i \right) \\
&\quad - a_0 \sum_1^7 e_i b_i \sum_1^7 e_i A_i + \left( b_0 \sum_1^7 a_i^2 \sum_1^7 e_i b_i \right) + \left( \sum_1^7 a_i^2 \sum_1^7 b_i^2 \right) \\
&= -a_0 \sum_1^7 b_i a_i \left( \sum_1^7 e_i b_i \right) - \sum_1^7 a_i^2 \left( b_0 \sum_1^7 e_i b_i - \sum_1^7 b_i^2 \right) \\
&\quad + a_0 b_0 \left( -\sum_1^7 a_i b_i - \sum_1^7 e_i A_i \right) + a_0 \left( \sum_1^7 e_i A_i \sum_1^7 e_i b_i \right)
\end{aligned}$$

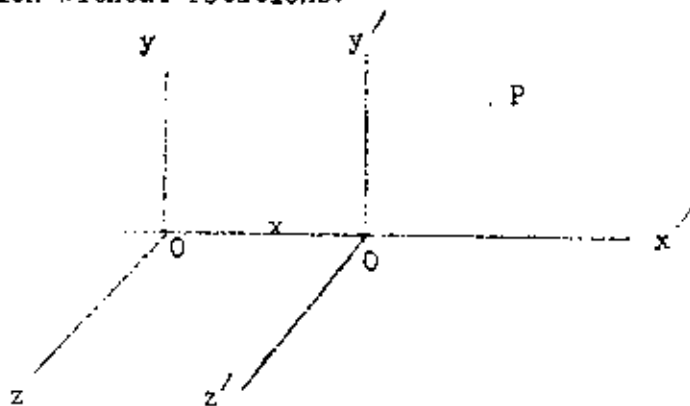
Left handside = Right handside

Note : An identity for  $(a_0^2 + a_1^2 + \dots + a_{n-1}^2)(b_0^2 + b_1^2 + \dots + b_{n-1}^2)$  similar to the identities (4.1), (4.2) and (4.3) cannot be found for every  $n$ , but only for  $n = 1, 2, 4, 8$ . (13, p. 100-125).

The Lorentz transformation of Special Relativity in Quaternion

Forms.

Let  $(x, y, z, t)$  be the cartesian coordinates and the time of an event P in the Galilean reference frame S, and let  $(x', y', z', t')$  be the coordinates in another reference frame S', where the x, y, and z axes of S coincide with the x', y', and z' axes of S' and  $t = t'$  where  $t = 0$ , and S' is moving with a velocity v relative to S in the x direction without rotations.



The Galilean transformation is the mapping which maps a point  $(x, y, z, t)$  in S onto the point  $(x', y', z', t')$  in S' where

~~the point  $(x, y, z, t)$  is the same as~~

$$x' = x - vt$$

$$y' = y$$

$$z' = z$$

$$t' = t$$

This transformation is used in Newtonian mechanics. According to the relativity principle, the transformation equations are

$$x' = \frac{x - vt}{\left(1 - \frac{v^2}{c^2}\right)^{\frac{1}{2}}} \quad \text{where } c \text{ is the speed of light} = 300,000 \text{ km/sec.}$$



$$\begin{aligned} y' &= y \\ z' &= z \\ t' &= \frac{t - \frac{vx}{c^2}}{\left(1 - \frac{v^2}{c^2}\right)^{\frac{1}{2}}} \end{aligned}$$

These transformation equations are called Lorentz equations.

Let  $\frac{1}{\left(1 - \frac{v^2}{c^2}\right)^{\frac{1}{2}}} = \gamma$

$$\begin{aligned} x' &= \gamma(x - vt) \\ y' &= y \\ z' &= z \\ t' &= \gamma\left(t - \frac{vx}{c^2}\right) \end{aligned}$$

Now let  $\tau = \gamma t$ , where  $\gamma$  is  $\sqrt{1 - \frac{v^2}{c^2}}$

Then  $x' = \gamma\left(x - \frac{v\tau}{\gamma}\right) = \gamma\left(x + \frac{iv\tau}{c}\right)$

$$\begin{aligned} y' &= y \\ z' &= z \\ \tau' &= \gamma\left(\frac{\tau}{\gamma} - \frac{vx}{c^2}\right) \gamma \\ &= \gamma\left(\tau - \frac{vxi}{c}\right) \end{aligned}$$

This can be written

$$\begin{pmatrix} x' \\ y' \\ z' \\ \tau' \end{pmatrix} = \begin{pmatrix} \gamma & 0 & 0 & \frac{\gamma vi}{c} \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -\frac{\gamma vi}{c} & 0 & 0 & \gamma \end{pmatrix} \begin{pmatrix} x \\ y \\ z \\ \tau \end{pmatrix} \dots (1)$$

The Lorentz transformation can be viewed as a rotation in four dimensional space from the point  $(x, y, z, \tau)$  to  $(x', y', z', \tau')$  (12, p.11,12) and rotations in four dimensional space can be represented by a transformation of quaternions of the form  $Q' = A Q B$ , (3, p. 68) where the point represented by the components of  $Q$  is transformed into the point represented by the components of  $Q'$ . Therefore we shall try to find the quaternions  $A$  and  $B$  that represent the Lorentz transformation (1).

Consider the transformation of quaternions

$$\begin{aligned}
 Q' &= A Q B \quad \text{where} \\
 A &= a + e_1 b + e_2 c + e_3 d \\
 B &= p + e_1 q + e_2 r + e_3 s \\
 Q &= x + e_1 y + e_2 z + e_3 \tau \\
 Q' &= x' + e_1 y' + e_2 z' + e_3 \tau'
 \end{aligned}$$

the transformation is

$$\begin{aligned}
 x' + e_1 y' + e_2 z' + e_3 \tau' &= (a + e_1 b + e_2 c + e_3 d)(x + e_1 y + e_2 z + e_3 \tau) \\
 (p + e_1 q + e_2 r + e_3 s) &\text{ or}
 \end{aligned}$$

$$\begin{pmatrix} x' \\ y' \\ z' \\ \tau' \end{pmatrix} = \begin{pmatrix} E_1 & E_2 & E_3 & E_4 \\ E_5 & E_6 & E_7 & E_8 \\ E_9 & E_{10} & E_{11} & E_{12} \\ E_{13} & E_{14} & E_{15} & E_{16} \end{pmatrix} \begin{pmatrix} x \\ y \\ z \\ \tau \end{pmatrix} \dots\dots \text{II}$$

Where  $E_1, E_2, \dots, E_{16}$  are elements in matrix of transformation in (II) which is similar to (I). Then we have,

$$\begin{aligned}
 E_1 &= ap - bq - cr - ds &= \delta &, \\
 E_2 &= -bp - aq - dr + cs &= 0 &, \\
 E_3 &= -cp + dq - ar - bs &= 0 &, \\
 E_4 &= -dp - cq + br - as &= \frac{\delta v_i}{C} &, \\
 E_5 &= bp + aq - dr + cs &= 0 &, \\
 E_6 &= ap - bq + cr + ds &= 1 &, \\
 E_7 &= -dp - cq - br + as &= 0 &, \\
 E_8 &= cp - dq - ar - bs &= 0 &, \\
 E_9 &= cp + dq + ar - bs &= 0 &, \\
 E_{10} &= dp - cq - br - as &= 0 &,
 \end{aligned}$$

$$\begin{aligned}
 E_{11} &= ap + bq - cr + ds = 1, \\
 E_{12} &= -bp + aq - dr - cs = 0, \\
 E_{13} &= dp - cq + br + as = -\frac{\delta vi}{c}, \\
 E_{14} &= -cp - dq + ar - bs = 0, \\
 E_{15} &= bp - aq - dr - cs = 0, \\
 E_{16} &= ap + bq + cr - ds = \delta.
 \end{aligned}$$

From the above sixteen equations, we find  $b = c = r = q = 0$ ,

$$\text{and } \frac{a}{d} = \frac{p}{s} = -\frac{vi\delta}{c(1-\delta)} = -\frac{(1+\delta)c}{\delta vi}.$$

$$\text{Therefore } A = \left(\frac{a}{d} + e_3\right) d \dots\dots\dots \text{III}$$

$$B = \left(\frac{p}{s} + e_3\right) s \dots\dots\dots \text{IV}$$

The above transformation  $Q' = AQB$  becomes

$$\begin{aligned}
 Q' &= d \left(\frac{a}{d} + e_3\right) (x + e_1 y + e_2 z + e_3 \tau) \left(\frac{p}{s} + e_3\right) s \\
 \text{The right handside is } &sd \left\{ \left[ x \left(\frac{a}{d} \cdot \frac{p}{s} - 1\right) - \tau \left(\frac{a}{d} + \frac{p}{s}\right) \right] + \right. \\
 &e_1 \left\{ y \left(\frac{a}{d} \cdot \frac{p}{s} + 1\right) + z \left(\frac{a}{d} - \frac{p}{s}\right) \right\} + e_2 \left\{ z \left(\frac{a}{d} \cdot \frac{p}{s} + 1\right) + y \left(\frac{p}{s} - \frac{a}{d}\right) \right\} \\
 &\left. + e_3 \left\{ x \left(\frac{a}{d} + \frac{p}{s}\right) + \tau \left(\frac{a}{d} \cdot \frac{p}{s} - 1\right) \right\} \right\}.
 \end{aligned}$$

Comparing with (I) we have,

$$sd \left(\frac{a}{d} \cdot \frac{p}{s} - 1\right) = \delta = sd \left(\frac{2\delta}{1-\delta}\right),$$

$$sd \left(\frac{a}{d} + \frac{p}{s}\right) = -\frac{\delta vi}{c} = -2 sd \frac{\delta vi}{c(1-\delta)},$$

$$sd \left(\frac{a}{d} \cdot \frac{p}{s} + 1\right) = 1 = sd \left(\frac{2}{1-\delta}\right).$$

From the above three equations we get  $sd = \frac{1-\delta}{2}$ .

Therefore we can choose  $s$  and  $d$  arbitrarily subject to this condition.

If  $s$  is put equal to  $d$ , we have  $s = d = \sqrt{\frac{1-\delta}{2}}$  and the quaternion

$A$  is equal to the quaternion  $B$ .

We can therefore represent the Lorentz transformation (I) by the quaternion transformation

$$\begin{aligned} Q' &= A Q B \\ \text{Where } A &= B = \frac{-vix}{c\sqrt{2(1-\delta)}} + e_3 \sqrt{\frac{1-\delta}{2}} \end{aligned}$$

Note: The transformation  $Q' = A Q$  is not sufficient to represent the general Lorentz Transformation because there are not enough parameters in A to specify a general rotation in 4 - dimensional space.

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