CHAPTER IV

Examples

4.1 Initial value problem of heat equation with impulse

Consider the following initial value problem:

$$\begin{cases} \frac{\partial u}{\partial t} - \frac{\partial^2 u}{\partial x^2} = f(t, u), & 0 < x < 1, t > 0, t \neq t_i ; \\ \Delta u(t_i) = J_i(u(t_i)), & t = t_i, i \in \mathbb{N}; \\ u(t, 0) = u(t, 1) = 0, u_x(t, 0) = u_x(t, 1) \\ u(0, x) = u_0(x). \end{cases}$$
(4.1)

This problem represents the heat flow in a ring of length one with a temperature dependent source. In this section we will introduce some functions $f, J_i (i \in \mathbb{N})$ such that satisfies the condition (JF) for this problem and use the previous chapter implying the existence and uniqueness of PCAP classical solution such that asymptotically stable as $t \to +\infty$. Now, we assume that $\{t_i\}$ is a sequence such that $\{t_i\}$ is EAP and $\inf t_j^1 = \xi > 0$.

We start by introducing a convenient abstract frame. Let $X = L^2([0, 1]; \Re)$ denote the space of all L^2 -integrable functions on [0, 1]. Define the $|\cdot| = |\cdot|_2$ -norm on $X = L^2([0, 1]; \Re)$ by

$$|u|_X = \left\{ \int_0^1 |u(x)|^p \right\}^{\frac{1}{p}}.$$

Then $X = L^2([0,1]; \Re)$ is Banach space. Define the operator $u(t): [0,1] \to \Re$ by

$$u(t)(x) = u(t,x)$$

and define an $A: X \to X$ by

$$Au = -u'', (4.2)$$

i.e.,

$$Au(t)(x) = -\frac{\partial^2 u(t,x)}{\partial x^2}, \text{ for all } x \in (0,1) \text{ with } D(A) = \{u \in \Xi \subseteq X \mid u', u'' \in X\}$$

where
$$\Xi = \{u \in X \mid u(t,0) = u(t,1) = 0, u_x(t,0) = u_x(t,1)\}.$$

Then A is self-adjoint with compact resolvent and is the infinitesimal generator of an analytic semigroup S(t) (see [10]) and we have, (4.1) corresponding to the abstract nonlinear impulsive differential system:

$$\begin{cases} u'(t) + Au(t) = f(t, u(t)), & t \neq t_i ; \\ \Delta u(t_i) = J_i(u(t_i)), & t = t_i , i \in \mathbb{N}; \\ u(0) = u_0. \end{cases}$$
(4.3)

where

$$u'(t)(x) = \lim_{h \to 0^+} \frac{u(t+h)(x) - u(t)(x)}{h}.$$

We now take $\alpha = 1/2$ and let $X_{1/2} = D(A^{1/2})$ with norm $|.|_{1/2}$. Define the function $f: \Re \times X_{1/2} \to X$ and $J_i(i \in \mathbb{N}): X_{1/2} \to X$ by

$$f(t,u) = h(t)g(u')$$
 for each $t \in \Re - \{t_i\}$ and $J_i(u) = g_i(u')$ for each, $u \in X_{1/2}$

where $h: \Re \to \Re$ is PCAP with a sequence $\{t_i\}$ such that $\{t_i^j\}$ is EAP and there exist k > 0 and $0 < \theta < 1$ satisfying

$$|h(t) - h(s)| \le k|t - s|^{\theta}$$
 for all $t, s \in \Re - \{t_i\}$ (4.4)

 $g: X \to X$ and $g_i: X \to X$ are Lipschitz continuous on X. Concrete examples of functions g and g_i are

$$sin(u)$$
, ku , $arctan(u)$

First, we introduce some known result for the operator A and $A^{1/2}$ defined by (4.2). Let $u \in D(A)$ and $k \in \Re$ such that

$$Au = -u'' = ku$$
 that is $u'' + ku = 0$. (4.5)

We have

$$< Au, u> = < ku, u>; \ \ {\rm that\ is}$$

$$k|u|_X^2 = k < u, u> = < -u'', u> = < u', u'> = |u'|_X^2.$$

So $k \in \Re_+$, for convenient we let $k = \lambda^2$. Then the solution of equation (4.5) have the form

$$u(x) = B_1 cos(\lambda x) + B_2 sin(\lambda x).$$

We have u(0) = u(1) = 0 so $B_1 = 0$ and $\lambda = n\pi$, $n \in \mathbb{N}$. Put $\lambda_n = n\pi$. The solutions of equation (4.5) are

$$u_n(x) = B_2 sin(\lambda_n x)$$
 , $n \in \mathbb{N}$.

We have $\langle u_n, u_m \rangle = 0$ for $n \neq m$ if $\langle u_n, u_n \rangle = 1$, then $B_2 = \sqrt{2}$ and

$$u_n(x) = \sqrt{2}sin(\lambda_n x) , n \in \mathbb{N}.$$

Then $\{u_n(x) = \sqrt{2}\sin(\lambda_n x)\}_{n\in\mathbb{N}}$ is orthonormal basis. Thus for $u \in D(A)$, there exists a sequence of real $\{\alpha_n\}$ such

$$u(x) = \sum_{n \in \mathbb{N}} \alpha_n u_n(x),$$

and

$$-u''(x) = \sum_{n \in \mathbb{N}} (\lambda_n)^2 \alpha_n u_n(x).$$

By using Bessel 's inequality,

$$\sum_{n\in\mathbb{N}} (\alpha_n)^2 < +\infty , \quad \sum_{n\in\mathbb{N}} (\lambda_n)^4 (\alpha_n)^2 < +\infty.$$

By Theorem 2.17, we have

$$A^{1/2}u(x) = \sum_{n \in \mathbb{N}} \lambda_n \alpha_n u_n(x)$$

with $u \in D(A^{1/2})$.

Next, we show now that f and $J_i(i \in \mathbb{N})$ are satisfying condition (JF). Let $t_1, t_2 \in \mathbb{R}$

and $u_1, u_2 \in X_{1/2}$, we obtain

$$f(t_1, u_1) - f(t_2, u_2) = h(t_1)g(u_1') - h(t_2)g(u_2')$$

= $[h(t_1) - h(t_2)]g(u_1') + h(t_2)[g(u_1') - g(u_2')]$ (4.6)

SO

$$|f(t_1, u_1) - f(t_2, u_2)|_X \le |h(t_1) - h(t_2)||g(u_1')| + |h(t_2)||g(u_1') - g(u_2')|$$

$$\le |g|_{\infty}|h(t_1) - h(t_2)| + |g|_{Lip}|h(t_2)||u_1' - u_2'|_X$$
(4.7)

since h is PCAP, there exist $k_2 > 0$ such that

$$|h(t_2)| < k_2.$$

We using the fact that g(u') is Lipchitz on $X_{1/2}$ (see more detail [5], page 75), we have

$$|f(t_1, u_1) - f(t_2, u_2)|_X \le k_1 |g|_{\infty} |t_1 - t_2|^{\theta} + k_2 |g|_{Lip} |u_1 - u|_{1/2}$$

$$\le L(|t_1 - t_2|^{\theta} + |u_1 - u|_{1/2})$$
(4.8)

where $0 < \theta < 1$.

Similarly, for $i \in \mathbb{N}$, we have

$$|J_{i}(u_{1}(t)) - J_{i}(u_{2}(t))|_{X} = |g_{i}(u'_{1}(t) - g_{i}(u'_{2}(t)))|_{X}$$

$$\leq |g_{i}|_{Lip}|u'_{1} - u'_{2}|_{X}$$

$$\leq L|u_{1} - u_{2}|_{1/2}.$$
(4.9)

Therefore f and $J_i(i \in \mathbb{N})$ satisfy the condition (JF) with

 $L = max\{k_1|g|_{\infty}, k_2|g|_{Lip}, sup_{i\in\mathbb{N}}|g_i|_{Lip}\}$. Moreover, we are following in the proof of Theorem 3.15., if $L < \frac{N}{K(\frac{\alpha}{2})} < \frac{N\sqrt{\pi}}{M_{1/2}}$ with $K(\alpha) = M_{\alpha}\left(\frac{\beta\pi}{\Gamma(\alpha)sin\pi\alpha} + \frac{\xi^{-\alpha}}{1-e^{-\beta\xi}}\right)$, then this theorem implies the existence and uniqueness of a classical PCAP solution for this system (4.3).

4.2 An impulsive logistic equation

Consider nonautomous logistic system:

$$\begin{cases} x'(t) = r(t)x(t) \left[1 - \frac{x(t)}{K(t)}\right], & t \neq t_k, t > 0\\ \Delta x(t) = B_k(x(t)), & t = t_k, k \in \mathbb{N} \end{cases}$$

$$(4.10)$$

in which r(t) is nonnegative and K(t) is a strictly positive continuous function and B_k are bounded operators.

By changing variable $x = \frac{1}{z}$ from (4.10) become to the nonautomous impulsive logistic system:

$$\begin{cases} z'(t) + Az(t) = f(t), & t \neq t_k, t > 0 \\ \Delta z(t) = J_k(z(t)), & t = t_k, k \in \mathbb{N} \end{cases}$$

$$(4.11)$$

where Az(t) = -r(t)z(t) and $f(t) = \frac{r(t)}{K(t)}$. We can see that the behavior or properties of solution for this problem depend on f and J_k which we put in our systems and one example of them is same as before.

