ปัญหาการเลือกในโครงสร้างโอมินิมอล

นายศรณย์เศรษฐ์ โสกันธิกา

วิทยานิพนธ์นี้เป็นส่วนหนึ่งของการศึกษาตามหลักสูตรปริญญาวิทยาศาสตรดุษฎีบัณฑิต สาขาวิชาคณิตศาสตร์ ภาควิชาคณิตศาสตร์และวิทยาการคอมพิวเตอร์ คณะวิทยาศาสตร์ จุฬาลงกรณ์มหาวิทยาลัย ปีการศึกษา 2560 ลิขสิทธิ์ของจุฬาลงกรณ์มหาวิทยาลัย

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## SELECTION PROBLEMS IN O-MINIMAL STRUCTURES

Mr. Saronsad Sokantika

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ในวิทยานิพนธ์ฉบับนี้เราได้ปรับปรุงทฤษฎีบทการเลือกที่นิยามได้ของไมเคิลในโครงสร้างขยาย ของเรียลโคลสฟิลด์ที่โอมินิมอล จากนั้นเราแสดงการประยุกต์ใช้ทฤษฎีบทนี้ เช่น เราพิสูจน์ ข้อความต่อไปนี้ "กำหนดให้  $\mathfrak{R}$  เป็นโครงสร้างขยายของ  $\mathbb{R}$  ที่โอมินิมอล และ  $T: \mathbb{R}^n \Rightarrow \mathbb{R}^m$ เป็นการส่งค่าเซตที่นิยามได้โดยที่ n = 1 หรือ m = 1 ถ้า T มีการเลือกแบบต่อเนื่องแล้ว T มีการเลือกแบบต่อเนื่องที่นิยามได้" ยิ่งไปกว่านั้นเรายังพิสูจน์ข้อความต่อไปนี้ "กำหนดให้  $\mathfrak{R}$  เป็นโครงสร้างขยายของเรียลโคลสฟิลด์ R ที่โอมินิมอล และ E เป็นสับเซตปิดของ  $R^n$  ถ้า  $T: E \Rightarrow R^m$  เป็นการส่งค่าเซตแบบต่อเนื่องที่นิยามได้และสำหรับทุกสมาชิก x ในขอบของเซต E T(x) มีขอบเขตแล้ว T มีการส่งภาคขยายแบบต่อเนื่องที่นิยามได้

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In this dissertation, we improve the Definable Michael's Selection Theorem in o-minimal expansions of real closed fields. Then applications of this theorem are established; for instance, we prove the following statement: Let  $\mathfrak{R}$  be an o-minimal expansion of  $\mathbb{R}$  and  $T : \mathbb{R}^n \rightrightarrows \mathbb{R}^m$  be a definable set-valued map where n = 1or m = 1. If T has a continuous selection, then T has a definable continuous selection. Moreover, we prove the statement: Let  $\mathfrak{R}$  be an o-minimal expansion of a real closed field R and E be a closed subset of  $\mathbb{R}^n$ . If  $T : E \rightrightarrows \mathbb{R}^m$  is a definable continuous set-valued map and T(x) is bounded for each x in the boundary of E, then T has a definable continuous extension.

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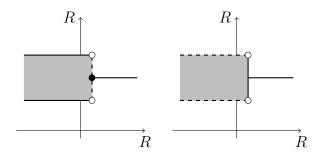
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# CHAPTER I INTRODUCTION

### 1.1 Set-valued maps

In this section, we let X and Y be sets. A **set-valued map** is a map T from X to the power set of Y and we denote such a map by  $T: X \rightrightarrows Y$ . The concept of setvalued maps is widely used in optimal control theory and mathematical economics (see [1]).

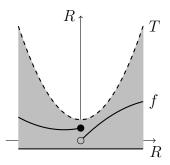
For the rest of this section, let R be an ordered field,  $X \subseteq R^n, Y \subseteq R^m$ , and  $T: X \Rightarrow Y$  be a set-valued map. The maximum R-norm ||x|| on  $R^n$  is defined by  $||x|| := \max_{i=1,\dots,n} \{|x_i|\}$  where | | is the absolute value function on R. We equip X and Y with maximum R-norms. Let  $x \in R^n$ ,  $S \subseteq R^n$ , and  $\epsilon > 0$  ( $\epsilon \in R$ ). We let  $B_n(x, \epsilon) := \{y \in R^n : ||x - y|| < \epsilon\}$  and  $B_n(S, \epsilon) := \bigcup_{s \in S} B_n(s, \epsilon)$ . We say that T is **lower semi-continuous** if for each  $x_0 \in X$ ,  $y_0 \in T(x_0)$  and  $\epsilon > 0$ , there is  $\delta > 0$  such that for every  $x \in B_n(x_0, \delta) \cap X$ ,  $T(x) \cap B_m(y_0, \epsilon) \neq \emptyset$ ; **upper semi-continuous** if for each  $x_0 \in X$  and  $\epsilon > 0$ , there is  $\delta > 0$  such that for all  $x \in B_n(x_0, \delta) \cap X$ ,  $T(x) \subseteq B_m(T(x_0), \epsilon)$ ; and **continuous** if it is both lower semi-continuous and upper semi-continuous. Note that if f is a continuous map, then f is continuous as a set-valued map.



Examples of a lower semi-continuous set-valued map (left) and an upper semi-continuous set-valued map (right).

A selection of T is a map  $f: X \to Y$  such that  $f(x) \in T(x)$  for every  $x \in X$ . In [19], E. Michael studied the existence of continuous selections of set-valued maps and proved the following statement:  $if T : \mathbb{R}^n \to \mathbb{R}^m$  is lower semi-continuous and each T(x) is nonempty closed and convex, then T has a continuous selection. This statement, which is known as Michael's Selection Theorem, has applications in various fields of mathematics (see [23], [25], and [17]).

In this dissertation, we make no distinction between set-valued maps and their graphs.



An example of a selection f of a set-valued map T.

### **1.2** O-minimal structures

The beginning of the study of o-minimal structures arose from Tarski's question on the decidability of the theory of the real field with the exponential function, called "the real exponential field." While the quantifier eliminability of the real field is obtained by Tarski's Theorem, L. van den Dries showed that the theory of the real exponential field does not admit quantifier elimination (see [5]). However, he argued that the theory of the real field and the theory of the real exponential field share many nice finiteness properties. Then he proved that these finiteness properties can be deduced from a certain axiom, which he called "finite type". Later, this axiom is known as "o-minimality". This term was introduced by A. Pillay and C. Steinhorn in [22].

A. Grothendieck has an influence in this subject. One of his aims is to study topological objects that satisfy finiteness properties and have tame behaviors (excluding objects like the topologist's sine curve, space-filling curves, fractals, etc.). This field is known as tame topology (or topologie modérée in French). See [14] for more details. It turns out that the o-minimality is the right framework for tame topology.

## **1.2.1** Definitions

First, we introduce the concept of structures (cf. [7]). Let R be a set. Let  $\mathfrak{R} := (\mathfrak{R}_n)_{n \in \mathbb{N}}$  and  $\mathfrak{R}' := (\mathfrak{R}'_n)_{n \in \mathbb{N}}$  be sequences such that  $\mathfrak{R}_n, \mathfrak{R}'_n$  are subsets of the power set of  $R^n$ . We say that  $\mathfrak{R} \subseteq \mathfrak{R}'$  if  $\mathfrak{R}_n \subseteq \mathfrak{R}'_n$  for each  $n \in \mathbb{N}$ . Let  $\{f_i\}_{i \in I}$  be a collection of functions  $f_i : R^{n_i} \to R$  and  $\{r_j\}_{j \in J}$  be a collection of relations  $r_j \subseteq R^{m_j}$ . A structure on R generated by  $\{f_i\}_{i \in I}, \{r_j\}_{j \in J}$  is the smallest sequence  $\mathfrak{R} := (\mathfrak{R}_n)_{n \in \mathbb{N}}$  with respect to  $\subseteq$  such that for each natural number n:

- 1.  $\mathfrak{R}_n$  is a boolean algebra of subsets of  $\mathbb{R}^n$ , that is,  $\mathfrak{R}_n$  is closed under finite intersection and relative complement.
- 2. The diagonal sets  $\Delta_{ij} := \{x \in \mathbb{R}^n : x_i = x_j\} \in \mathfrak{R}_n$  for  $1 \le i < j \le n$ ;
- 3. If  $A \in \mathfrak{R}_{n+1}$ , then  $\pi A \in \mathfrak{R}_n$  where  $\pi : \mathbb{R}^{n+1} \to \mathbb{R}^n$  is the projection map onto the first *n* coordinates;
- 4. If  $A \in \mathfrak{R}_n$ , then  $A \times R \in \mathfrak{R}_{n+1}$  and  $R \times A \in \mathfrak{R}_{n+1}$ ;
- 5. The singleton  $\{r\} \in \mathfrak{R}_1$  for each  $r \in R$ ;
- 6. For each  $i \in I, j \in J$ , there exist  $m, k \in \mathbb{N}$  such that  $f_i \in \mathfrak{R}_m, r_j \in \mathfrak{R}_k$ .

We denote such a structure by  $(R; \{f_i\}_{i \in I}, \{r_j\}_{j \in J})$  and let  $\mathfrak{L}_{\mathfrak{R}} := \{f_i\}_{i \in I} \cup \{r_j\}_{j \in J}$  be the "language" of this structure. We say that  $\mathfrak{R}$  is a structure on R if there exist a collection of functions and a collection of relations such that  $\mathfrak{R}$  is a structure on R generated by these collections. Let  $\mathfrak{R} := (R; \{f_i\}_{i \in I}, \{r_j\}_{j \in J})$  be a structure and  $\{f_{\alpha}\}_{\alpha \in \Lambda}$  be a collection of functions  $f_{\alpha} : R^{k_{\alpha}} \to R$ . Then a structure  $(R; \{f_i\}_{i \in I} \cup \{f_{\alpha}\}_{\alpha \in \Lambda}, \{r_j\}_{j \in J})$  is denoted by  $\mathfrak{R} \cup \{f_{\alpha}\}_{\alpha \in \Lambda}$ .

Next, let A be a subset of  $\mathbb{R}^n$ . We say that A is **definable in**  $\mathfrak{R}$  or  $\mathfrak{R}$  **defines** Aif  $A \in \mathfrak{R}_n$ . We simply say A is **definable** if the structure is clear from the context. A map  $f: A \to \mathbb{R}^m$  is **definable in**  $\mathfrak{R}$  if  $f \in \mathfrak{R}_{n+m}$ . Similarly, a set-valued map  $T: A \rightrightarrows \mathbb{R}^m$  is **definable in**  $\mathfrak{R}$  if  $T \in \mathfrak{R}_{n+m}$ .

Moreover, let  $\mathfrak{R}$  and  $\mathfrak{R}'$  be structures on R such that  $\mathfrak{R} \subseteq \mathfrak{R}'$ . We call  $\mathfrak{R}'$  an **expansion** of  $\mathfrak{R}$  and call  $\mathfrak{R}$  a **reduct** of  $\mathfrak{R}'$ . Note that the notion of structures is, in fact, a geometric point of view of the collection of all sets which is "definable in  $\mathfrak{R}$  with parameters" in first order logic. In other words, a definable set is a set that can be described by a first-order  $\mathfrak{L}_{\mathfrak{R}}$ -formula with parameters. We can prove that if A is definable in  $\mathfrak{R}$ , then int A the interior, cl A the closure, and fr  $A := \operatorname{cl} A \setminus A$  the frontier of A are also definable.

Now, we are ready to give the definition of o-minimal structures. Let  $\mathfrak{R}$  be an expansion of (R; <) where < is a linear order on R. Then  $\mathfrak{R}$  is **o-minimal** if every definable subset of R is a finite union of points and open intervals. Hence, every definable subset of R is also definable in (R; <). In other words, every definable subset of R can be described by a quantifier free formula in language  $\{<\}$  with parameters from R. Intuitively, the letter "o" in "o-minimal" stands for "order".

## **1.2.2** Examples of o-minimal structures

First, we give examples of o-minimal structures over the real field  $\mathbb{R}$ .

**Example 1.1.** A subset of  $\mathbb{R}^n$  is **semialgebraic** if it is a finite union of sets of the form

$$\{x \in \mathbb{R}^n : f(x) = 0, g_1(x) > 0, \dots, g_k(x) > 0\}$$

where f and  $g_1 \ldots, g_k$  are real polynomials in n variables. Clearly, each semialgebraic set is definable in  $\mathbb{R}_{alg} := (\mathbb{R}; <, +, \cdot)$ . In addition, Tarski–Seidenberg Theorem implies that the projection of semialgebraic set is also semialgebraic. Hence, each definable set in  $\mathbb{R}_{alg}$  is semialgebraic. Moreover,  $\mathbb{R}_{alg}$  is o-minimal since each semialgebraic subset of  $\mathbb{R}$  is a finite union of points and intervals. For more details on the structure  $\mathbb{R}_{alg}$ , see [7, Chapter 2]. **Example 1.2.** A set  $E \subseteq \mathbb{R}^n$  is called **semianalytic** if for every  $x \in \mathbb{R}^n$ , there is an open neighborhood U of x such that  $E \cap U$  is a finite union of sets of the form

$$\{x \in U : f(x) = 0, g_1(x) > 0, \dots, g_k(x) > 0\}$$

where f and  $g_1 \ldots, g_k$  are analytic functions on U. Note that the projections of semianalytic sets need not be semianalytic. A set  $E \subseteq \mathbb{R}^n$  is called **subanalytic** in  $\mathbb{R}^n$  if for every  $x \in \mathbb{R}^n$ , there is an open neighborhood U of x and a bounded semianalytic set  $S \subseteq \mathbb{R}^{n+m}$  such that  $U \cap E = \pi S$ , where  $\pi : \mathbb{R}^{n+m} \to \mathbb{R}^n$  is the projection on the first n coordinates. In [6], L. van den Dries introduced a notion called finitely subanalytic sets. A set  $E \subseteq \mathbb{R}^n$  is called **finitely subanalytic** (also known as **globally subanalytic**) if its image under the analytic isomorphism map from  $\mathbb{R}^n$  to  $\mathbb{R}^n$ :

$$(x_1, \ldots, x_n) \mapsto (x_1/\sqrt{1+x_1^2}, \ldots, x_n/\sqrt{1+x_n^2})$$

is subanalytic in  $\mathbb{R}^n$ . Let  $\mathfrak{R}_n := \{E \subseteq \mathbb{R}^n : E \text{ is globally subanalytic}\}$  and  $\mathfrak{R} := (\mathfrak{R}_n)_{n \in \mathbb{N}}$ . Then L. van den Dries proved that  $\mathfrak{R}$  is an o-minimal structure.

Let  $f : \mathbb{R}^n \to \mathbb{R}$ . Then f is **restricted analytic** if f vanishes outside  $[-1,1]^n$ and there exist an open neighborhood U of  $[-1,1]^n$  and an analytic function g:  $U \to \mathbb{R}$  such that f = g on  $[-1,1]^n$ . We denote the real field with restricted analytic functions by

 $\mathbb{R}_{\mathrm{an}} := \mathbb{R}_{\mathrm{alg}} \cup \{ f : \mathbb{R}^n \to \mathbb{R} : f \text{ is restricted analytic and } n \in \mathbb{N} \}.$ 

Note that  $\mathbb{R}_{an} = \mathfrak{R}$  and hence  $\mathbb{R}_{an}$  is o-minimal.

**Example 1.3.** An exponential set in  $\mathbb{R}^n$  is a set of the form:

$$\{(x_1,\ldots,x_n): P(x_1,\ldots,x_n,e^{x_1},\ldots,e^{x_n})=0\}$$

where P is a real polynomial in 2n variables; a **subexponential** set is the image

of an exponential set under a coordinate projection. In 1991, A. J. Wilkie showed in his preprint that the real exponential field is model complete (see [30]). Let

$$\mathbb{R}_{\exp} := \mathbb{R}_{\operatorname{alg}} \cup \{\exp\}$$

Hence, every definable set in  $\mathbb{R}_{exp}$  is a subexponential set. Since every exponential set has finitely many connected components (this fact is called Khovanskii's Theorem),  $\mathbb{R}_{exp}$  is an o-minimal structure.

**Example 1.4.** Next, we consider an expansion of  $\mathbb{R}_{an}$  and  $\mathbb{R}_{exp}$ , called the real exponential field with restricted analytic functions. Let

$$\mathbb{R}_{\mathrm{an,exp}} := \mathbb{R}_{\mathrm{an}} \cup \{\mathrm{exp}\}.$$

The o-minimality of this structure was first proved by L. van den Dries and C. Miller in 1994 (see [9]) and a simpler proof was given by L. van den Dries, A. Macintyre and D. Marker in [8].

**Example 1.5.** A pfaffian chain is a finite sequence of  $C^1$ -functions  $g_1(x), \ldots, g_k(x)$ on an open set  $U \subset \mathbb{R}^n$  such that for each  $i = 1, \ldots, k, j = 1, \ldots, n$ ,

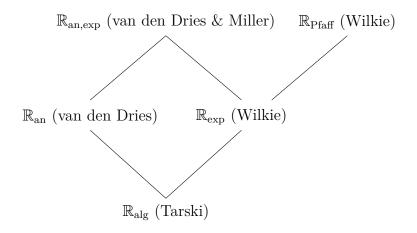
$$\frac{\partial g_i}{\partial x_j}(x) = P_{ij}(x, g_1(x), \dots, g_i(x))$$

where  $P_{ij}$  is a real polynomial in n + i variables. A **pfaffian function** is a function which belongs to a pfaffian chain. Note that polynomials and exponential functions are pfaffian while the sine function is not. Let  $g_1(x), \ldots, g_k(x)$  be a pfaffian chain on open set U containing  $[-1, 1]^n$  and let  $f_1(x), \ldots, f_k(x)$  be the corresponding truncations to  $[-1, 1]^n$ . In [29], A. Wilkie proved the model completeness of the structure  $(\mathbb{R}; <, +, \cdot, f_1, \ldots, f_k)$ . Combining with the result of A. Khovanskii in [16],  $(\mathbb{R}; <, +, \cdot, f_1, \ldots, f_k)$  is o-minimal. Moreover, A. Wilkie proved the o-minimality of

$$\mathbb{R}_{\text{pfaff}} := \mathbb{R}_{\text{alg}} \cup \{ f : \mathbb{R}^n \to \mathbb{R} : f \text{ is pfaffian and } n \in \mathbb{N} \}$$

in 1999 (see [30]). Since the exponential function is pfaffian,  $\mathbb{R}_{pfaff}$  is an expansion of  $\mathbb{R}_{exp}$ .

From the above examples, we get the following diagram:



Examples of o-minimal structures over the real field.

The reader may ask whether there is the largest o-minimal expansion  $\mathcal{M}$  of the real field. In 2003, J.-P. Rolin, P. Speissegger, and A. Wilkie introduced a new construction of o-minimal expansions of the real field and proved the following:

**Theorem 1.6** (J.-P. Rolin, P. Speissegger, and A. Wilkie [24, Theorem 2(1)]). Let  $f : U \to \mathbb{R}$  be a  $C^{\infty}$ -function where U is an open neighborhood of  $[-1, 1]^n$ . Then there exist o-minimal expansions of the real field  $\mathfrak{R}_1, \mathfrak{R}_2$  and functions  $f_1, f_2 : [-1, 1]^n \to \mathbb{R}$  such that for  $i = 1, 2, f_i$  is definable in  $\mathfrak{R}_i$  and  $f = f_1 + f_2$  on  $[-1, 1]^n$ .

Let  $f : \mathbb{R} \to \mathbb{R}$  be a function defined by

$$f(x) := \begin{cases} e^{-\frac{1}{x^2}} \sin(1/x), & \text{if } x \neq 0; \\ 0, & \text{if } x = 0. \end{cases}$$

Note that f is a  $C^{\infty}$ -function and  $\{x \in [-1, 1] : f(x) = 0 \text{ and } x \neq 0\}$  is an infinite discrete set. By Theorem 1.6, if there is the largest o-minimal expansion of the real field, then  $f \upharpoonright [-1, 1]$  and  $\{x \in [-1, 1] : f(x) = 0 \text{ and } x \neq 0\}$  are definable in this structure, which is absurd.

In [26], P. Speissegger introduced the pfaffian closure and proved that the pfaffian closure of an o-minimal expansion of the real field is also o-minimal.

**Example 1.7.** Let  $\mathfrak{R}$  be an o-minimal expansion of  $(\mathbb{N}; <)$  where < is a discrete linear order on  $\mathbb{N}$ . In [21], A. Pillay and C. Steinhorn proved that all definable one-variable functions in  $\mathfrak{R}$  are translations. Therefore, the theory of  $\mathfrak{R}$  is well-understood.

**Example 1.8.** Let R be a dense linearly ordered set without endpoints. The ominimality of (R; <) is obtained from the quantifier elimination property of the theory of dense linear orderings without endpoints. See [7] for more details.

Next, we introduce more definitions. Let R be a field. We say that R is formally real if -1 is not a sum of squares; and we say that R is a real closed field if R is formally real and each polynomial over R with single variable has an intermediate value property. Hence, by Intermediate Value Theorem,  $\mathbb{R}$  is a real closed field. Note that if R is a real closed field, then  $(R; +, \cdot)$  defines a linear order < that makes R an ordered field. Hence, R is a dense linearly ordered set without endpoints.

**Example 1.9.** Let R be a real close field. Since the theory of real closed fields admits quantifier elimination,  $(R; <, +, \cdot)$  is o-minimal.

**Theorem 1.10** (L. van den Dries [7, Chapter 1, Proposition 4.6]). If R is an ordered ring and there exists an o-minimal expansion of  $(R; <, +, \cdot)$ , then R is a real closed field.

We say that a structure  $\mathfrak{R}$  is an **expansion of a real closed field** R if  $\mathfrak{R}$  is an expansion of  $(R; <, +, \cdot)$ . In this thesis, we only focus on o-minimal expansions of a real closed field.

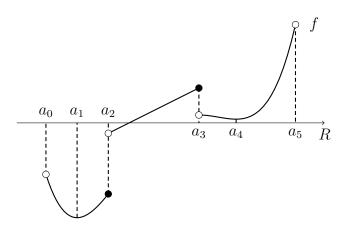
## **1.2.3** Geometry of definable sets

In this section, we recall important results in o-minimal structures, for example, Monotonicity Theorem, Cell Decomposition Theorem, and  $C^m$ -Cell Decomposition Theorem. These theorems tell us that definable sets in o-minimal structures can be partitioned into finitely many "well-behaved" sets. We also state Definable Choice, Triangulation Theorem, Definable Tietze's Extension, and Trivialization Theorem. For more details and proofs, see [7]. Throughtout, let  $\mathfrak{R}$  be an o-minimal expansion of a real closed field R and  $E \subseteq R^n$ .

#### Monotonicity Theorem

Consider a polynomial in one variable f(x) over the real field. Observe that, as a function, f is piecewise monotone and piecewise continuous. In fact, every onevariable function definable in  $\mathfrak{R}$  has this property.

**Theorem 1.11** (Monotonicity Theorem). Let  $a \in R \cup \{-\infty\}$  and  $b \in R \cup \{+\infty\}$ . Let  $f : (a,b) \to R$  be a definable function on the interval (a,b). Then there are points  $a = a_0 < \cdots < a_{k+1} = b$  such that for each 0 < i < k+1, the restriction of f to  $(a_i, a_{i+1})$  is either constant, or strictly monotone and continuous.



An example of a partition of (a, b) that satisfies the above conditions.

Let  $a \in R \cup \{-\infty\}$ ,  $b \in R \cup \{+\infty\}$ ,  $c \in (a, b)$ , and  $f : (a, b) \to R$  be a definable function. By Monotonicity Theorem,  $\lim_{x\to a^+} f(x)$ ,  $\lim_{x\to b^-} f(x)$ ,  $\lim_{x\to c^+} f(x)$ , and  $\lim_{x\to c^-} f(x)$  exist in  $R \cup \{-\infty, +\infty\}$ .

#### Cell Decomposition Theorem

In this part, we introduce the concept of "cells" and state that each definable set in o-minimal structures is a finite union of cells.

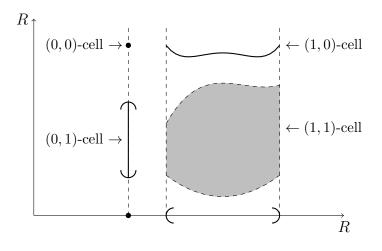
Let E be a definable subset of  $\mathbb{R}^n$ . We define C(E) to be the collection of all definable continuous functions  $f : E \to \mathbb{R}$ ; and  $C_{\infty}(E) := C(E) \cup \{-\infty, +\infty\}$ where  $-\infty$  and  $+\infty$  are considered as constant functions on E. Let  $(i_1, \ldots, i_n)$  be a sequence of zeroes and ones of length n. An  $(i_1, \ldots, i_n)$ -cell is a definable subset of  $\mathbb{R}^n$  defined inductively on n as follows:

- (i) a (0)-cell is a singleton set  $\{r\} \subseteq R$ , a (1)-cell is an open interval  $(a, b) \subseteq R$ ;
- (ii) suppose  $(i_1, \ldots, i_n)$  cells are already defined;
  - (a) an  $(i_1, \ldots, i_n, 0)$ -cell is a function in C(E) where E is an  $(i_1, \ldots, i_n)$ -cell;
  - (b) an  $(i_1, \ldots, i_n, 1)$ -cell is a set

$$(f,g)_E := \{(x,y) \in \mathbb{R}^n \times \mathbb{R} : x \in E, \ f(x) < y < g(x)\}$$

where E is an  $(i_1, \ldots, i_n)$ -cell and  $f, g \in C_{\infty}(E)$  such that f < g.

We call such f and g defining functions.



Examples of cells in  $\mathbb{R}^2$ .

A cell is an  $(i_1, \ldots, i_n)$ -cell, for some  $(i_1, \ldots, i_n) \in \{0, 1\}^n$ . Note that a cell in  $\mathbb{R}^n$  is open if and only if it is a  $(1, \ldots, 1)$ -cell. Moreover, the interior of non-open cells is empty.

We say that a definable set A is **definably connected** if A is not a disjoint union of two nonempty definable open subsets of A.

Proposition 1.12. Each cell is definably connected.

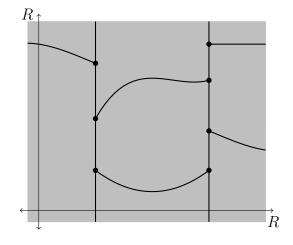
A cell decomposition of  $\mathbb{R}^n$  is a special kind of partitions of  $\mathbb{R}^n$  into finitely many cells. We define cell decompositions of  $\mathbb{R}^n$  inductively as follows:

(i) a cell decomposition of R is a collection

$$\{(-\infty, a_1), (a_1, a_2), \dots, (a_k, +\infty), \{a_1\}, \dots, \{a_k\}\}$$

where  $a_1 < \cdots < a_k$  are points in R;

(ii) a cell decomposition of  $\mathbb{R}^{n+1}$  is a finite partition  $\mathcal{C}$  of  $\mathbb{R}^{n+1}$  into cells such that  $\pi \mathcal{C} := \{\pi C : C \in \mathcal{C}\}$  is also a cell decomposition of  $\mathbb{R}^n$  where  $\pi : \mathbb{R}^{n+1} \to \mathbb{R}^n$ is the projection to the first n coordinates.



An example of a cell decomposition of  $R^2$ .

Let  $A \subseteq \mathbb{R}^n$  and  $\mathcal{C}$  be a cell decomposition of  $\mathbb{R}^n$ . We say that  $\mathcal{C}$  partitions A if each cell  $C \in \mathcal{C}$  is either  $C \subseteq A$  or  $C \cap A = \emptyset$ . The next theorem tells us that cells are the building blocks of definable sets in o-minimal structures.

Theorem 1.13 (Cell Decomposition Theorem).

- (I) Given definable sets  $A_1, \ldots, A_k \subseteq \mathbb{R}^n$ , there is a cell decomposition  $\mathcal{C}$  of  $\mathbb{R}^n$ such that for each  $i = 1, \ldots, k$ ,  $\mathcal{C}$  partitions  $A_i$ .
- (II) For each definable function  $f : A \to R$  where  $A \subseteq R^n$ , there is a cell decomposition C of  $R^n$  such that C partitions A and for each cell  $C \in C$  with  $C \subseteq A$ , the restriction  $f \upharpoonright C : C \to R$  is continuous.

This theorem provides more information on the geometry of definable sets. As a consequence, each definable set has finitely many definably connected components (a definably connected component of a definable set E is a maximal definably connected subset of E) and each definable function is piecewise continuous. Moreover, we get this result:

**Theorem 1.14** (Uniform Finiteness Theorem). Let A be a definable subset of  $\mathbb{R}^{n+m}$ . If for each  $x \in \mathbb{R}^n$ ,  $\{y \in \mathbb{R}^m : (x, y) \in A\}$  is finite, then there is  $N \in \mathbb{N}$  such that  $|\{y \in \mathbb{R}^m : (x, y) \in A\}| \leq N$  for all  $x \in \mathbb{R}^n$ .

#### $C^m$ -Decomposition Theorem

The concept of differentiablility makes sense in o-minimal context. Let  $m \in \mathbb{N}$ and  $f: E \to R^k$  be definable. Then f is  $C^m$  if f is the restriction of a definable  $C^m$ -map  $g: U \to R^k$  where U is a definable open set containing E. For each  $m \in \mathbb{N}$ , let  $C^m(E)$  be the collection of all definable  $C^m$ -functions  $f: E \to R$  and  $C^m_{\infty}(E) := C^m(E) \cup \{-\infty, +\infty\}.$ 

Now we can define  $C^m$ -cells and  $C^m$ -cell decompositions in the same manner as the above, by replacing C(E) and  $C_{\infty}(E)$  by  $C^m(E)$  and  $C_{\infty}^m(E)$ , respectively. Then we get this modified version of the Cell Decomposition Theorem:

**Theorem 1.15** ( $C^m$ -Cell Decomposition Theorem). Let  $m \in \mathbb{N}$ . Then

(I) Given definable sets  $A_1, \ldots, A_k \subseteq \mathbb{R}^n$ , there is a  $\mathbb{C}^m$ -cell decomposition  $\mathcal{C}$  of  $\mathbb{R}^n$  such that for each  $i = 1, \ldots, k, \mathcal{C}$  partitions  $A_i$ .

(II) For each definable function  $f : A \to R$  where  $A \subseteq R^n$ , there is a  $C^m$ -cell decomposition C of  $R^n$  such that C partitions A and for each cell  $C \in C$  with  $C \subseteq A$  the restriction  $f \upharpoonright C : C \to R$  is  $C^m$ .

Since the above theorem holds for every natural number m, the smooth version of the Cell Decomposition Theorem (where smooth cells and smooth cell decomposition are defined in the same fashion) looks promising. However, in [15], O. Le Gal and J.-P. Rolin showed that there is an o-minimal expansion of a real closed field that does not admit smooth cell decomposition.

#### Invariant properties

We introduce concepts of "dimension" and "Euler characteristic" of definable sets and state that they are invariant under definable bijection. We define the **dimension** of a nonempty definable set  $A \subseteq \mathbb{R}^n$  by

$$\dim(A) := \max\{i_1 + \dots + i_n : A \text{ contains an } (i_1, \dots, i_n) \text{-cells}\}$$

(equvalently,

 $\dim(A) := \max\{k \in \mathbb{N} : \text{there is a coordinate projection } \pi : R^n \to R^k \text{ such that}$  $\inf \pi A \neq \emptyset\})$ 

and assign the dimension of the empty set to be  $-\infty$ . Then we have the following theorem:

**Theorem 1.16.** Let  $A \subseteq \mathbb{R}^n$  be nonempty and definable. Then  $\dim(\operatorname{cl} A \setminus A) < \dim A$ . In particular,  $\dim \operatorname{cl} A = \dim A$ .

This theorem implies that the topologist's sine curve and space-filling curves are not definable in o-minimal structures.

For each cell C of dimension d, we define the **Euler characteristic** of C to be

 $E(C) := (-1)^d$ . Let  $A \subseteq \mathbb{R}^n$ . We define the **Euler characteristic** of A to be

$$E(A) := \sum_{C \in \mathcal{P}} E(C)$$

where  $\mathcal{P}$  is a finite partition of A into cells. Note that the Euler characteristic of A does not depend on  $\mathcal{P}$ . Moreover, we get this result:

**Proposition 1.17.** Let  $A \subseteq \mathbb{R}^n$  and  $B \subseteq \mathbb{R}^m$  be definable sets. Then there exists a definable bijection from A to B if and only if dim  $A = \dim B$  and E(A) = E(B).

For more details on properties of dimension and Euler characteristic, we refer to [7, Chapter 3].

### **Definable Choice**

Next is a definable analog of the Axiom of Choice in o-minimal context.

**Theorem 1.18** (Definable Choice). If  $A \subseteq \mathbb{R}^{n+m}$  is definable and  $\pi : A \to \mathbb{R}^n$  is the projection to the first *n* coordinates, then there is a definable map  $f : \pi A \to \mathbb{R}^m$ such that  $f \subseteq A$ . Moreover, if  $x, x' \in \pi A$  such that  $\{y \in \mathbb{R}^m : (x, y) \in A\} = \{y \in \mathbb{R}^m : (x', y) \in A\}$ , then f(x) = f(x').

The following are consequences of the Definable Choice.

**Corollary 1.19** (Curve Selection). Let X be a definable set and  $a \in cl X \setminus X$ . Then there exist  $\epsilon > 0$  and a definable continuous injective map  $\gamma : (0, \epsilon) \to X$  such that  $\lim_{t\to 0} \gamma(t) = a$ .

By the Definable Choice, we can show that closed bounded definable sets in o-minimal structures have many properties resemble compact sets.

**Proposition 1.20.** Let  $f : E \to R^m$  be a definable continuous map on a nonempty closed bounded set E. Then

- 1. f(E) is closed and bounded in  $\mathbb{R}^m$ .
- 2. f has a maximum and a minimum values.
- 3. f is uniformly continuous.

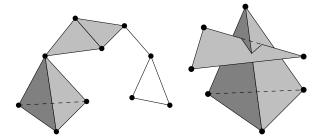
#### **Triangulation Theorem**

In this part, we introduce the concept of "simplices" and "complexes". We also state that each definable set can be triangulated. Hence, the topology of definable sets can be completely described via finite unions of simplices. For more details, see [7, Chapter 6].

Let  $a_0, \ldots, a_k \in \mathbb{R}^n$  be affinely independent, that is,  $a_1 - a_0, \ldots, a_k - a_0$  are linearly independent. Then a k-simplex in  $\mathbb{R}^n$  spanned by  $\{a_0, \ldots, a_k\}$  is the set

$$(a_0, \dots, a_k) := \{\sum_{i=0}^n t_i a_i : t_i > 0, \sum_{i=0}^k t_i = 1\}.$$

We say that a set  $S \subseteq \mathbb{R}^n$  is a **simplex** if there exist  $k \in \{0, \ldots, n\}$  and affinely independent elements  $a_0, \ldots, a_k$  in  $\mathbb{R}^n$  such that  $S = (a_0, \ldots, a_k)$ . A **face** of  $(a_0, \ldots, a_k)$  is a simplex spanned by a nonempty subset of  $\{a_0, \ldots, a_k\}$ . A **complex** in  $\mathbb{R}^n$  is a finite collection K of simplices in  $\mathbb{R}^n$  such that for all  $\sigma_1, \sigma_2 \in K$ , either  $\operatorname{cl} \sigma_1 \cap \operatorname{cl} \sigma_2 = \emptyset$ , or there is a face  $\sigma$  of  $\sigma_1$  and  $\sigma_2$  such that  $\operatorname{cl} \sigma_1 \cap \operatorname{cl} \sigma_2 = \operatorname{cl} \sigma$ . Let K be a finite collection of simplices in  $\mathbb{R}^n$ . Then we denote the union of the simplices of K by |K|.



An example of |K| where K is a complex in  $\mathbb{R}^3$  (left) and an example of |K| where K is not a complex in  $\mathbb{R}^3$  (right).

**Theorem 1.21** (Triangulation Theorem). Let A be a definable subset of  $\mathbb{R}^n$ . Then there is a complex K in  $\mathbb{R}^n$  and a definable homeomorphism  $h : A \to |K|$ .

There are many useful consequences of this theorem. For example,

**Lemma 1.22.** Let  $E_0, E_1$  be disjoint definable closed subsets of a definable set E. Then there exist disjoint definable open subsets  $U_0, U_1$  of E with  $E_i \subseteq U_i, i = 0, 1$ .

**Lemma 1.23.** Let  $E_0, E_1$  be disjoint definable closed subsets of a definable set E. Then there is a definable continuous function  $f: E \to [0, 1]$  such that  $f^{-1}(0) = E_0$ and  $f^{-1}(1) = E_1$ .

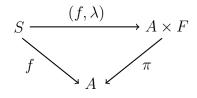
Let  $A \subseteq E \subseteq \mathbb{R}^n$ . We say that a map  $r : E \to A$  is a **retraction** if r is continuous and the restriction  $r \upharpoonright A$  is an identity map on A.

**Corollary 1.24.** Let A be a definable closed subset of a definable set E. Then there are a definable open subset U of E containing A and a definable retraction  $r : \operatorname{cl} U \cap E \to A$ .

**Theorem 1.25** (Definable Tietze's Extension). Let A be a closed subset of a definable set E and  $f: A \to R^m$  be a definable continuous map. Then there is a definable continuous map  $g: E \to R^m$  such that g = f on A.

#### **Trivialization Theorem**

Throughout the rest of this section, let  $A \subseteq R^m$ ,  $S \subseteq R^n$  be definable sets and  $f: S \to A$  be a definable continuous map. A **definable trivialization of** f is a pair  $(F, \lambda)$  consisting of a definable set  $F \subseteq R^N$  and a definable map  $\lambda: S \to F$  such that  $(f, \lambda): S \to A \times F$  is a homeomorphism. If f has a definable trivialization  $(F, \lambda)$ , then f behaves like a projection map  $A \times F \to A$ ; more precisely, let  $\pi$  be the projection on the first m coordinates, then the following diagram commutes:



Note that for each  $a \in A$ ,  $f^{-1}(a)$  are homeomorphic to F. We call f definably trivial if f has a definable trivialization. Given a definable subset  $A' \subseteq A$ , we say that f is definably trivial over A' if the restriction  $f \upharpoonright f^{-1}(A') : f^{-1}(A') \to A'$  is definably trivial. Note that if  $(F, \lambda)$  is a definable trivialization of f and  $A' \subseteq A$ , then  $(F, \lambda \upharpoonright f^{-1}(A'))$  is a definable trivialization of  $f \upharpoonright f^{-1}(A') : f^{-1}(A') \to A'$ .

Now we can state this theorem:

**Theorem 1.26** (Trivialization Theorem [7, Chapter 9, Theorem 1.2]). We can partition A into definable subsets  $A_1, \ldots, A_k$ , such that for each  $i = 1, \ldots, k$ , f is definably trivial over  $A_i$ .

## 1.3 Outline

In this dissertation, we mainly work on the selection problems in o-minimal expansion of a real closed field R. Fixed point problems and extension problems in o-minimal context are also discussed.

In Chapter 2, we focus on the Definable Michael's Selection Theorem. Let  $E \subseteq \mathbb{R}^n$  and  $T: E \rightrightarrows \mathbb{R}^m$ . In [19,20], E. Michael gave a sufficient condition for the existence of continuous selections of T when  $R = \mathbb{R}$ . In [2], A. Thamrongthanyalak and M. Aschenbrenner proved a definable version of Michael's Selection Theorem: if E is a closed subset of  $\mathbb{R}^n$  and  $T: E \rightrightarrows \mathbb{R}^m$  is a definable lower semi-continuous set-valued map such that T(x) is nonempty, closed, and convex for each  $x \in E$ , then T has a definable continuous selection. In addition, E. Michael showed that the closedness of E and the closedness of T(x) are not necessary for the existence of continuous selections. Hence, we want to improve the Definable Michael's Selection Theorem, we first prove a special case and will use it to prove an improved version of the Definable Michael's Selection Theorem.

In Chapter 3, we introduce the concept of the Glaeser refinement. Roughly speaking, the Glaeser refinement is a tool that we use to shave off "bad points" in set-valued maps (in the sense that set-valued maps are not lower semi-continous because of these points). We also prepare some results for Chapter 4. For instance, we prove that if each value of a definable set-valued map is convex, then each value of its Glaeser refinement is also convex. Moreover, we prove that definable setvalued maps will be stable after we apply Glaeser refinement finitely many times. We finish this chapter by showing that the argument in the proof of stability is sharp. More precisely, for each  $n \in \mathbb{N}$ , we provide an example of a definable setvalued map  $T_n$  such that the  $m^{\text{th}}$ -refinement of  $T_n$  is stable if and only if  $m \geq n$ .

Chapter 4 contains applications of the main theorem in Chapter 2. In Section 4.1, we ask this question: Let T be a definable set-valued map. Is the existence of continuous selections a sufficient condition for the existence of definable continuous selection of T? By using results in Chapter 3, we give a partial answer to this question. Section 4.2 and 4.3 are consequences of Section 4.1. In section 4.2, we want to characterize definable almost lower semicontinuous set-valued maps by using the concept of definable  $\epsilon$ -approximatic selections. In section 4.3, we study the lower semi-continuous version of the Definable Kakutani's Fixed Point Theorem. In the last section, we give an example of a definable upper semicontinuous set-valued map that does not have a continuous selection. Then we prove the following statement: for each  $\epsilon > 0$ , if  $T : E \Rightarrow R^m$  is a definable upper semi-continuous set-valued map such that T(x) is nonempty and convex for each  $x \in E$ , then there is a definable continuous map  $f : E \to R^m$  such that  $f \subseteq B_{n+m}(T, \epsilon)$ .

The content of Chapter 5 is independent from the rest of this dissertation. By the Definable Tieze's Extension, we know that each definable continuous map on a closed subset of  $\mathbb{R}^n$  can be extended to the whole space. Hence, if  $T: E \rightrightarrows \mathbb{R}^m$  is a definable continuous set-valued map and E is a closed subset of  $\mathbb{R}^n$ , it is natural to ask whether T has a definable continuous extension. We give a partial answer to this question.

#### **1.4** Conventions and notations

Throughout this dissertation, m, n and k will range over  $\mathbb{N} = \{0, 1, 2, 3, ...\}$ . We let R be a real closed field and we equip  $R^n$  with the Euclidean R-norm  $\| \|$  defined by  $\|(x_1, \ldots, x_n)\| :=$  the positive square root of  $\sum_{i=1,\ldots,n} x_i^2$ . We also equip  $R^n$  with the corresponding topology.

Let  $\epsilon > 0$ ,  $x \in \mathbb{R}^n$  and  $S, K \subseteq \mathbb{R}^n$ . Let  $d(x, S) := \inf\{\|x - y\| : y \in S\}$ ,  $B_n(x, \epsilon) := \{y \in \mathbb{R}^n : \|x - y\| < \epsilon\}$  and  $B_n(S, \epsilon) := \bigcup_{s \in S} B_n(s, \epsilon)$ . Also, we just use  $B(x, \epsilon)$  and  $B(S, \epsilon)$  if its ambient space is clear from the context. Note that  $\{B_n(x, \epsilon) : x \in \mathbb{R}^n \text{ and } \epsilon > 0\}$  is a topological basis of  $\mathbb{R}^n$ .

Let Aff  $S := \{\sum_{i=0}^{n} \alpha_i x_i : x_i \in S, \alpha_i \in R, \sum_{i=0}^{n} \alpha_i = 1\}$  be the affine hull of S, int<sub>K</sub> S be the relative interior of S in K,  $cl_K S$  be the relative closure of S in K, and bd S be the boundary of S.

## CHAPTER II

# GENERRALIZATION OF DEFINABLE MICHAEL SELECTION THEOREM

Throughout this chapter, let  $\mathfrak{R}$  be an o-minimal expansion of a real closed field Rand let  $E \subseteq \mathbb{R}^n$  and  $T : E \rightrightarrows \mathbb{R}^m$  be definable. In 1956, E. Michael proved that: ([19, Theorem 3.1''']) if T is lower semi-continuous and each T(x) is nonempty convex, then T has a continuous selection. However, the given construction may produce a continuous selection that is far more complicated than how T arose (see [28] for a discussion on this problem). Hence, we study this statement in the o-minimal context. The main goal of this chapter is to prove the following theorem:

**Theorem 2.1.** Assume T is lower semi-continuous and T(x) is nonempty and convex for every  $x \in E$ . Then T has a definable continuous selection.

## 2.1 Preliminaries

Now we begin working towards the proof of Theorem 2.1. First we prove the following facts:

**Lemma 2.2.** Suppose that T is lower semi-continuous. Then the set-valued map  $F: E \rightrightarrows \mathbb{R}^m$  defined by  $F(x) := \operatorname{cl} T(x)$  is definable and lower semi-continuous.

Proof. Obviously, F is definable. Let  $x_0 \in E$  and  $y_0 \in F(x_0)$ . Let  $\epsilon > 0$ . Then there is  $y \in B_m(y_0, \epsilon) \cap T(x_0)$ . Since T is lower semi-continuous, there is  $\delta > 0$ such that for each  $x \in B_n(x_0, \delta) \cap E$ ,  $\emptyset \neq B_m(y, \epsilon - ||y - y_0||) \cap T(x) \subseteq B_m(y_0, \epsilon) \cap$ F(x).

**Lemma 2.3.** Let A be a definable closed subset of E and  $f : A \to R^m$  be a definable selection of  $T \upharpoonright A$ . Suppose that T is lower semi-continuous set-valued map and f

is continuous. Then the set-valued map  $F: E \rightrightarrows R^m$  defined by

$$F(x) := \begin{cases} T(x), & \text{if } x \in E \smallsetminus A; \\ \{f(x)\}, & \text{if } x \in A \end{cases}$$

is definable and lower semi-continuous.

Proof. It is clear that F is definable. Let  $x_0 \in E$ ,  $y \in F(x_0)$  and  $\varepsilon > 0$ . Since T is lower semi-continuous, there is  $\delta_1 > 0$  such that for each  $x \in B(x_0, \delta_1) \cap E$ ,  $T(x) \cap B(y, \varepsilon) \neq \emptyset$ . Suppose that  $x_0 \in E \smallsetminus A$ . Since  $E \smallsetminus A$  is open, there exists  $\delta_2 > 0$  such that for each  $B(x_0, \delta_2) \subseteq E \smallsetminus A$ . Choose  $\delta = \min\{\delta_1, \delta_2\}$ . Then, for each  $x \in B(x_0, \delta) \cap E$ ,  $F(x) \cap B(y, \varepsilon) \neq \emptyset$ . Next, we assume  $x_0 \in A$ . Then  $y = f(x_0)$ . Since f is continuous, there is  $\delta_2 > 0$  such that for each  $x \in B(x_0, \delta_2) \cap A$ ,  $f(x) \in B(f(x_0), \varepsilon)$ . Choose  $\delta = \min\{\delta_1, \delta_2\}$ . Hence, for each  $x \in B(x_0, \delta) \cap E$ ,  $F(x) \cap B(f(x_0), \varepsilon) \neq \emptyset$ .

**Theorem 2.4** (Definable Michael Selection Theorem, M. Aschenbrenner and A. Thamrongthanyalak [2, Theorem 2.2.1]). Let E be closed and  $T : E \rightrightarrows R^m$ be lower semi-continuous. Assume T(x) is nonempty, closed, and convex for each  $x \in E$ . Then T has a definable continuous selection.

We can prove that the closedness of E in the above theorem can be omitted.

**Theorem 2.5.** Suppose T is lower semi-continuous and T(x) is nonempty, closed and convex for every  $x \in E$ . Then T has a definable continuous selection.

To prove this theorem, we recall these lemmas:

**Lemma 2.6** (M. Aschenbrenner and A. Thamrongthanyalak [2, Theorem 2.1.4]). There is a cell decomposition C of  $\mathbb{R}^n$  such that C partitions E and for each  $C \in C$ ,  $T \upharpoonright C$  is lower semi-continuous and closed in  $C \times \mathbb{R}^m$ .

**Lemma 2.7** (M. Aschenbrenner and A. Thamrongthanyalak [2, Lemma 2.2.2]). Let  $T : (0,1) \Rightarrow R^m$  be a definable set-valued map. Let  $(0,y) \in cl T$ . Then there are  $\epsilon \in (0,1)$  and a definable continuous map  $f : (0,\epsilon) \rightarrow R^m$  such that  $f(t) \in T(t)$ for all  $t \in (0,\epsilon)$  and  $\lim_{t\to 0^+} f(t) = y$ . To prove Theorem 2.5, we follows the proof of the Definable Michael's Selection Theorem in [2].

Proof of Theorem 2.5. We proceed by induction on dim E. If dim E = 0, then Eis finite and the above statement is trivial. Suppose dim E > 0 and the result holds for every set with dimension less than dim E. By Lemma 2.6, there is a cell decomposition C partitions E such that for each  $C \in C$ ,  $T \upharpoonright C$  is lower semicontinuous and closed in  $C \times R^m$ . By the Cell Decomposition Theorem, there is a definable open subset  $S \subseteq E$  such that dim  $E \smallsetminus S <$  dim E and  $T \upharpoonright S$  is lower semi-continuous and closed in  $S \times R^m$ . By the induction hypothesis, there is a definable continuous selection  $f : E \smallsetminus S \to R^m$ . Since  $E \smallsetminus S$  is closed in E, by the Definable Tietze's Extension Theorem, there is a definable continuous function  $g : E \to R^m$  such that g = f on  $E \backsim S$ . Since T(x) is closed and convex for all  $x \in E$ , we can define  $h : E \to R^m$  by

$$h(x) :=$$
 the unique  $y \in T(x)$  such that  $||x - y|| = d(x, T(x))$ .

Since T is definable, so is h. To show that h is continuous, let  $x_0 \in E$  and  $\gamma: (0,1) \to E$  such that  $\lim_{t\to 0^+} \gamma(t) = x_0$ ; we need to show that  $\lim_{t\to 0^+} h(\gamma(t)) = h(x_0)$ . First, we prove the following claim: Claim. Let  $\epsilon > 0$ . Then

$$||g(x_0) - h(\gamma(t))|| \le ||g(x_0) - h(x_0)|| + \epsilon$$
 as  $t \to 0^+$ 

Proof of Claim. Since T is lower semi-continuous, by Lemma 2.7, there exist  $0 < \epsilon < 1$  and a definable continuous function  $\phi : (0, \epsilon) \to R^m$  such that  $\phi(t) \in T(\gamma(t))$  for each  $0 < t < \epsilon$  and  $\lim_{t\to 0^+} \phi(t) = h(x_0)$ . By continuity of g at  $x_0$ , there is  $\delta > 0$  such that for all  $x \in B_n(x_0, \delta) \cap E$ ,  $||g(x) - g(x_0)|| < \frac{1}{3}\epsilon$ . Let  $t_0 > 0$  be such that for each  $0 < t \le t_0$ ,  $\gamma(t) \in B_n(x_0, \delta)$  and  $||\phi(t) - h(x_0)|| < \frac{1}{3}\epsilon$ . By the

definition of h,

$$\|h(\gamma(t)) - g(\gamma(t))\| \le \|\phi(t) - g(\gamma(t))\| \quad \text{ for all } t \in (0,1)$$

Moreover, for  $0 < t \le t_0$  we have

$$\begin{aligned} \|\phi(t) - g(\gamma(t))\| &\leq \|\phi(t) - h(\gamma(t))\| + \|h(\gamma(t)) - g(x_0)\| + \|g(x_0) - g(\gamma(t))\| \\ &\leq \|g(x_0) - h(\gamma(t))\| + \frac{2}{3}\epsilon \end{aligned}$$

and therefore

$$||g(x_0) - h(\gamma(t))|| \le ||g(x_0) - g(\gamma(t))|| + ||g(\gamma(t)) - h(\gamma(t))||$$
  
$$\le \frac{1}{3}\epsilon + ||g(\gamma(t)) - \phi(t)||$$
  
$$\le ||g(x_0) - h(\gamma(t))|| + \epsilon$$

as required.

By the Monotonicity Theorem and this claim,  $y_0 := \lim_{t\to 0^+} h(\gamma(x))$  exists in  $R^m$  and  $||g(x_0) - y_0|| \le ||g(x_0) - h(x_0)|| + \epsilon$  for every  $\epsilon > 0$ . Hence,  $||g(x_0) - y_0|| \le ||g(x_0) - h(x_0)||$ . If  $x_0 \in E \smallsetminus S$ , then  $g(x_0) = h(x_0)$  and hence  $y_0 = g(x_0) = h(x_0)$ . Suppose  $x_0 \in S$ . Since  $T \upharpoonright S$  is closed in  $S \times R^m$ , we have  $y_0 \in T(x_0)$ . By the definition of  $h, y_0 = h(x_0)$ . Therefore, h is continuous at  $x_0$ .

## 2.2 Proof of Theorem 2.1

First, we will prove the following special case of Theorem 2.1.

**Lemma 2.8.** Suppose T is lower semi-continuous, and T(x) is a nonempty and convex subset of  $B_m(0,1)$  for every  $x \in E$ , then T has a definable continuous selection.

*Proof.* We proceed by induction on the dimension of E. If dim E = 0, then E is finite and the result holds trivially. Suppose dim E > 0 and the result holds

for every set with dimension less than dim E. Define  $T_0: E \rightrightarrows \mathbb{R}^m$  by  $T_0(x) := \operatorname{int}_{\operatorname{Aff} T(x)} T(x)$ . Obviously,  $T_0$  is definable and  $T_0(x) \subseteq T(x)$  for every  $x \in E$ . By the Definable Choice and the Cell Decomposition Theorem, there exist  $S \subseteq E$ open in E and a definable map  $f: E \to \mathbb{R}^m$  such that dim  $E \smallsetminus S < \dim E$ ,  $f \upharpoonright S$  is continuous and  $f(x) \in T_0(x)$  for every  $x \in T_0(x)$ . Inductively, let  $g_0: E \smallsetminus S \to \mathbb{R}^m$ be a definable continuous selection of  $T \upharpoonright E \backsim S$ . Define  $T_1: E \rightrightarrows \mathbb{R}^m$  by

$$T_1(x) := \begin{cases} \operatorname{cl} T(x), & \text{if } x \in S; \\ \{g_0(x)\}, & \text{if } x \in E \smallsetminus S. \end{cases}$$

By Lemma 2.2 and 2.3, we have  $T_1$  is lower semi-continuous and definable, and  $T_1(x)$  is closed and convex for every  $x \in E$ . By Theorem 2.5, let  $g_1$  be a definable continuous selection of  $T_1$ .

By Lemma 1.22 and 1.23, there exist  $U \subseteq E$  definable open and  $t: E \to [0, 1]$ definable continuous such that  $E \smallsetminus S \subseteq U \subsetneq E$ ,  $t^{-1}(0) = E \smallsetminus S$ , and  $t^{-1}(1) = E \smallsetminus U$ . Next, we define  $h: E \to \mathbb{R}^m$  by

$$h(x) := (1 - t(x))g_1(x) + t(x)f(x).$$

Obviously, h is definable. To prove that h is a selection of T, it suffices to prove the following claim:

Claim. If  $C \subseteq \mathbb{R}^m$  is convex,  $a \in \operatorname{int}_{\operatorname{Aff} C} C$ ,  $b \in \operatorname{cl} C$ , and 0 < t < 1, then  $(1-t)a + tb \in \operatorname{int}_{\operatorname{Aff} C} C$ .

Proof of Claim. Let c = (1 - t)a + tb. First, assume  $b \in \operatorname{int}_{\operatorname{Aff} C} C$ . Since  $a, b \in \operatorname{int}_{\operatorname{Aff} C} C$ , there is  $\epsilon > 0$  such that  $B_m(a, \epsilon) \cap \operatorname{Aff} C \subseteq C$  and  $B_m(b, \epsilon) \cap \operatorname{Aff} C \subseteq C$ . We will show that  $B_m(c, \epsilon) \cap \operatorname{Aff} C \subseteq C$ . Let  $d \in B_m(c, \epsilon) \cap \operatorname{Aff} C$ . Then  $a + d - c \in B_m(a, \epsilon) \cap \operatorname{Aff} C$  and  $b + d - c \in B_m(b, \epsilon) \cap \operatorname{Aff} C$ . Therefore,  $a + d - c, b + d - c \in C$ . Since C is convex and  $d = (1 - t)(a + d - c) + t(b + d - c), d \in C$ .

Now let  $b \in cl C$ . Then there is  $u \in B_m(b, (1-t)\epsilon/t) \cap \operatorname{int}_{\operatorname{Aff} C} C$ . Since  $a \in \operatorname{int}_{\operatorname{Aff} C} C$ , there is  $\epsilon > 0$  such that  $B_m(a, \epsilon) \cap \operatorname{Aff} C \subseteq C$ . Let  $v := t(b-u)/(1-t) + a \in \operatorname{Aff} C$ . Then  $||v-a|| < \epsilon$ . Hence,  $v \in \operatorname{int}_{\operatorname{Aff} C} C$ . Since  $u, v \in \operatorname{int}_{\operatorname{Aff} C} C$ 

and tu + (1-t)v = ta + (1-t)b = c, by the above case,  $c \in \operatorname{int}_{\operatorname{Aff} C} C$ .

Therefore, it remains to prove that h is continuous. Since  $E \setminus S$  is closed in E, it suffices to show that h is continuous at  $x_0 \in E \setminus S$ . Let  $x_0 \in E \setminus S$  and  $\epsilon > 0$ . Since  $g_1$  is continuous at  $x_0$ , there is  $\delta > 0$  such that for all  $x \in B_n(x_0, \delta)$ ,  $\|g_1(x_0) - g_1(x)\| < \epsilon/2$  and  $\|t(x)\| = \|t(x_0) - t(x)\| < \epsilon/4$ . Let  $x \in B_n(x_0, \delta)$ . Hence,

$$\|h(x_0) - h(x)\| \le \|g_1(x_0) - g_1(x)\| + \|t(x)\| \cdot \|g_1(x)\| + \|t(x)\| \cdot \|f(x)\|$$
  
$$< \frac{\epsilon}{2} + \frac{2\epsilon}{4}$$
  
$$= \epsilon.$$

Therefore, h is continuous at  $x_0$ .

Now that we have the above result, one of the most intuitive ideas to finish the proof of Theorem 2.1 is to apply semialgebraic homeomorphisms from  $B_m(0,1)$ to  $R^m$  to reduce to the bounded case. However, such homeomorphisms do not preserve the convexity. Therefore, we propose the following:

Proof of Theorem 2.1. We proceed by induction on dim E. The case dim E = 0is trivial. Suppose that dim E > 0 and the result holds for sets with dimension less than dim E. Suppose T is lower semi-continuous such that T(x) is nonempty and convex for every  $x \in E$ . Similar to the proof of Lemma 2.8, there exists a definable selection f of T and  $S \subseteq E$  definable such that  $E \smallsetminus S$  is closed in E, dim  $E \backsim S < \dim E$ , and  $f \upharpoonright S$  is continuous. By the inductive hypothesis and Lemma 1.25, let  $g: E \to R^m$  be definable and continuous such that  $g(x) \in T(x)$ for every  $x \in E \backsim S$ . Define  $T - g: E \rightrightarrows \mathbb{R}^m$  by

$$T - g(x) := \{y - g(x) : y \in T(x)\}.$$

Observe that T-g is definable and lower semi-continuous, and T-g(x) is nonempty and convex for every  $x \in E$ . Note that if h is a definable continuous selection of

T - g, then h + g is a definable continuous selection of T. Hence, it suffices to assume that g = 0.

Let  $W = \{x \in E : B_m(0,1) \cap T(x) \neq \emptyset\}$ . Then W is open in E and  $E \smallsetminus S \subseteq W$ . By Lemma 1.22, there are definable  $U, V \subseteq E$  such that U, V are open in E and  $E \smallsetminus S \subseteq V \subseteq \operatorname{cl}_E V \subseteq U \subseteq \operatorname{cl}_E U \subseteq W$ .

Define  $T_0: \operatorname{cl}_E U \rightrightarrows R^m$  by  $T_0(x) = B_m(0,1) \cap T(x)$ . It is routine to check that  $T_0$  is definable and lower semi-continuous. By Lemma 2.8 and Lemma 1.25, let  $s: E \to R^m$  be a definable and continuous such that  $s(x) \in T_0(x)$  for every  $x \in \operatorname{cl}_E U$ . Since  $\operatorname{cl}_E V \subseteq U$ , there is a definable continuous function  $t: E \to [0,1]$ such that  $t^{-1}(0) = \operatorname{cl}_E V$  and  $t^{-1}(1) = E \smallsetminus U$ . Define  $h: E \to R^n$  by

$$h(x) := (1 - t(x))s(x) + t(x)f(x).$$

Note that h is definable,  $h \upharpoonright V = s \upharpoonright V$  and  $h \upharpoonright E \smallsetminus U = f \upharpoonright E \backsim U$ . Since  $s(x), f(x) \in T(x)$  for every  $x \in U \smallsetminus V$ , h is a selection of T. It remains to show that h is continuous. Since s, f and t are continuous on S,  $h \upharpoonright S$  is continuous. The restriction  $h \upharpoonright V$  is continuous because  $h \upharpoonright V = s \upharpoonright V$ . Since  $V, E \smallsetminus A$  are open and  $V \cap (E \smallsetminus A) \neq \emptyset$ , h is continuous.

In Chapter 4, we will show some applications of Theorem 2.1.

# CHAPTER III GLAESER REFINEMENT

In this chapter, we study the concept of the Glaeser refinement which is introduced in [13] (this concept is also called derived mapping in [3]). This concept plays an important role in Chapter 4. Throughout this chapter, assume that  $\mathfrak{R}$  is an o-minimal expansion of a real closed field R and let  $E \subseteq \mathbb{R}^n$  and  $T: E \rightrightarrows \mathbb{R}^m$  be definable.

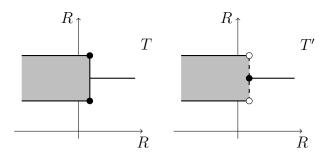
The **Glaeser refinement** of T is a set-valued map  $T': E \rightrightarrows R^m$  given by for each  $x_0 \in E$ ,

$$T'(x_0) := \{ y \in T(x_0) : \forall \epsilon > 0 \ \exists \delta > 0 \ \forall x \in B_n(x_0, \delta) \cap E, B_m(y, \epsilon) \cap T(x) \neq \emptyset \}$$

(equivalently,

$$T'(x_0) := \{ y \in T(x_0) : d(y, T(x)) \to 0 \text{ as } x \to x_0 \text{ where } x \in E \} \}.$$

Readers may think that the Glaeser refinement is a tool that we use to shave off "bad points" in T. Obviously, if T is definable, then so is T'. Since  $T' \subseteq T$ , selections of T' are also selections of T.



An example of the Glaeser refinement T' of a set-valued map T.

The following lemmas follow immediately from the definitions of lower semi-

continuity and the Glaeser refinement.

## **Lemma 3.1.** If T is lower semi-continuous, then T' = T.

*Proof.* Let  $(x_0, y_0) \in T$  and  $\epsilon > 0$ . Since T is lower semi-continuous, there is  $\delta > 0$ such that for each  $x \in B_n(x_0, \delta)$ ,  $B_m(y_0, \epsilon) \cap T(x) \neq \emptyset$ . Hence,  $(x_0, y_0) \in T'$ .  $\Box$ 

**Lemma 3.2.** If  $U \subseteq E$  is open in E, then  $T' \upharpoonright U = (T \upharpoonright U)'$ .

Proof. Let  $(x_0, y_0) \in T' \upharpoonright U$  and  $\epsilon > 0$ . Then there is  $\delta > 0$  such that for all  $x \in B_n(x_0, \delta), B_m(y_0, \epsilon) \cap T(x) \neq \emptyset$ . Hence,  $(x_0, y_0) \in (T \upharpoonright U)'$ . Next, let  $(x_0, y_0) \in (T \upharpoonright U)'$  and  $\epsilon > 0$ . Then there is  $\delta > 0$  such that  $B_n(x_0, \delta) \subseteq U$  and for all  $x \in B_n(x_0, \delta), B_m(y_0, \epsilon) \cap T(x) = B_m(y_0, \epsilon) \cap T \upharpoonright U(x) \neq \emptyset$ . Hence,  $(x_0, y_0) \in T' \upharpoonright U$ .  $\Box$ 

Moreover,

**Lemma 3.3.** Suppose  $T(x_0)$  is convex for every  $x_0 \in E$ . Then  $T'(x_0)$  is convex for every  $x_0 \in E$ .

Proof. Let  $x_0 \in E$ . If  $T'(x_0) = \emptyset$ , then we are done. Suppose  $T'(x_0) \neq \emptyset$ . Let  $a, b \in T'(x_0)$ , and  $t \in [0, 1]$ . We will show that  $c = (1 - t)a + tb \in T'(x_0)$ . Let  $\epsilon > 0$ . Then there is  $\delta > 0$  such that for each  $x \in B_n(x_0, \delta)$  there exist  $a_x \in B_m(a, \epsilon/2) \cap T(x)$  and  $b_x \in B_m(b, \epsilon/2) \cap T(x)$ . Hence, for each  $x \in B_n(x_0, \delta)$ ,

$$\|((1-t)a+tb) - ((1-t)a_x + tb_x)\| = \|(1-t)(a-a_x) + t(b-b_x)\|$$
  
$$\leq (1-t)\|(a-a_x)\| + t\|(b-b_x)\|$$
  
$$< \frac{(1-t)\epsilon}{2} + \frac{t\epsilon}{2}$$
  
$$= \epsilon.$$

Hence,  $ta + (1 - t)b \in T'(x_0)$ .

We inductively define a sequence  $(T^{(l)})_{l \in \mathbb{N}}$  of set-valued maps by  $T^{(0)} := T$  and  $T^{(l+1)} = (T^{(l)})'$  for every  $l \in \mathbb{N}$ . We say that T is **stable (under the Glaeser refinement)** if T' = T. It is natural to ask whether there exists a natural number l such that  $T^{(l)}$  is stable.

**Lemma 3.4.** For all  $l \ge \dim E$ ,  $T^{(l)} = T^{(\dim E)}$ .

Proof of Lemma 3.4. It is enough to prove that for each  $d \leq \dim E$ , there exists a definable open subset U of E such that  $\dim(E \smallsetminus U) < \dim E - d$  and  $T^{(d)} \upharpoonright U$ is lower semi-continuous. We proceed by induction on d. The case d = 0 is immediate from Lemma 2.6. Suppose the result holds for d. Let  $V \subseteq E$  be definable and open in E such that  $\dim(E\smallsetminus V)<\dim E-d$  and  $T^{(d)}{\upharpoonright}V$  is lower semi-continuous. Then  $T^{(d)}(x) = T^{(d+1)}(x)$  for every  $x \in V$ . By Lemma 2.6 and the Cell Decomposition Theorem, let  $\mathcal{C}$  be a cell decomposition of  $E \smallsetminus V$  such that for each  $C \in \mathcal{C}$ ,  $T^{(d+1)} \upharpoonright C$  is lower semi-continuous and fr C is a finite union of cells in  $\mathcal{C}$ . Let  $U = V \cup \bigcup \{C \in \mathcal{C} : \dim C = \dim(E \setminus V)\}$ . It is routine to check that U is definable and open in E, and  $\dim(E \setminus U) < \dim E - d - 1$ . It remains to prove that  $T^{(d+1)} \upharpoonright U$  is lower semi-continuous. Note that  $T^{(d)} \upharpoonright V$  is lower semi-continuous. Let  $x_0 \in U \setminus V$  and  $y_0 \in T^{(d+1)}(x)$ . Let  $\epsilon > 0$ . Then there exists  $\delta_1 > 0$  such that for every  $x \in B_n(x_0, \delta_1) \cap U$ ,  $B_m(y_0, \epsilon) \cap T^{(d)}(x) \neq \emptyset$ . Since  $T^{(d)}(x) = T^{(d+1)}(x)$  for every  $x \in B_n(x_0, \delta_1) \cap V$ , we have  $B_m(y_0, \epsilon) \cap T^{(d+1)}(x) \neq \emptyset$ for every  $x \in B_n(x_0, \delta_1) \cap V$ . Observe that  $T^{(d+1)} \upharpoonright U \smallsetminus V$  is lower semi-conitnuous. Hence, there exists a box  $0 < \delta_2 < \delta_1$  such that  $B_m(y_0, \epsilon) \cap T^{(d+1)}(x) \neq \emptyset$  for every  $x \in B_n(x_0, \delta_2) \cap (U \setminus V)$ . Thus,  $T^{(d+1)} \upharpoonright U$  is lower semi-continuous. 

As a consequence of Lemma 3.4, we have  $T^{(\dim E)}$  is stable. For convenience, we write  $T^{(*)} = T^{(\dim E)}$ . Note that, by the definition of the Glaeser refinement,  $T^{(*)}$  is lower semi-continuous.

Next, we will show that the stabilization method in Lemma 3.4 is sharp. Let  $n \in \mathbb{N} \setminus \{0\}$  and  $x = (x_1, \ldots, x_n) \in \mathbb{R}^n$ . For  $i \in \{1, \ldots, n-1\}$ , let

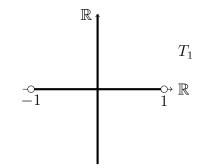
$$y_{ij}(x) := \begin{cases} 1, & \text{if } j = i; \\ x_i x_{i+1} / |x_{i+1}|, & \text{if } j = i+1 \text{ and } x_{i+1} \neq 0; \\ 0, & \text{otherwise.} \end{cases}$$

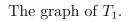
and let  $v_i^n(x) = (y_{i1}(x), \dots, y_{in}(x)).$ 

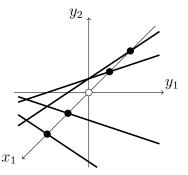
Let  $U := (-1, 0) \cup (0, 1)$ . A sequence  $(E_n)_{n \in \mathbb{N}}$  is recursively defined by  $E_0 := \mathbb{R}^0$ and  $E_{n+1} := U^{n+1} \cup (E_n \times \{0\}) \subseteq \mathbb{R}^{n+1}$ .

**Example 3.5.** For each  $n \in \mathbb{N} \setminus \{0\}$ , define  $T_n \colon E_n \rightrightarrows \mathbb{R}^n$  by

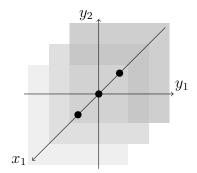
$$T_n(x) := \begin{cases} \operatorname{span}\{v_1^n(x), \dots, v_{n-1}^n(x)\}, & \text{if } x \in U^n; \\ \mathbb{R}^n, & \text{otherwise.} \end{cases}$$



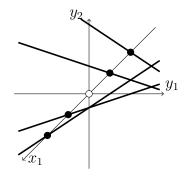




Examples of  $T_2(x_1, x_2)$  when  $(x_1, x_2) \in E_2$  and  $x_2 < 0$ .



Examples of  $T_2(x_1, 0)$  when  $(x_1, 0) \in E_2$ .



Examples of  $T_2(x_1, x_2)$  when  $(x_1, x_2) \in E_2$  and  $x_2 > 0$ .

Let  $n \in \mathbb{N} \setminus \{0\}$  and  $k \in \mathbb{N}$ . Then for every  $x \in E_n$ ,  $T_n^{(k)}(x) = T_n^{(k+1)}(x)$  if and only if  $k \ge n$ .

*Proof.* We proceed by induction on  $n \ge 1$ . It is easy to see that  $T'_1(0) = \{0\} \ne \mathbb{R} = T_1(0)$ . Assume for every  $x \in E_n$ ,  $T_n^{(k)}(x) = T_n^{(k+1)}(x)$  if and only if  $k \ge n$ . It suffices to show that for every  $x \in E_{n+1}$ ,

$$T'_{n+1}(x) = \begin{cases} T_{n+1}(x), & \text{if } x \in U^{n+1};\\ \text{span}\{v_1^{n+1}(x), \dots, v_{n-1}^{n+1}(x)\}, & \text{if } x \in U^n \times \{0\};\\ \mathbb{R}^n \times \{0\}, & \text{otherwise.} \end{cases}$$

Note that for each  $i, v_i^{n+1}$  is continuous on  $U^{n+1}$ ; therefore,  $T_{n+1}$  is lower semicontinuous on  $U^{n+1}$ . If  $x \in U^{n+1}$ , then  $T'_{n+1}(x) = T_{n+1}(x)$ . Suppose x =  $(x_1, \dots, x_n, 0) \in U^n \times \{0\}$ . We will prove that  $T'_{n+1}(x) = \operatorname{span}\{v_1^{n+1}(x), \dots, v_{n-1}^{n+1}(x)\}$ . Since  $\lim_{U^{n+1} \ni z \to x} v_i^{n+1}(z) = v_i^{n+1}(x)$  for each  $i \in \{1, \dots, n-1\}$ ,

$$\operatorname{span}\{v_1^{n+1}(x),\ldots,v_{n-1}^{n+1}(x)\}\subseteq T'_{n+1}(x).$$

Let  $y \in T'_{n+1}(x)$ . Let  $v_1 = v_n^{n+1}(x_1, \dots, x_n, 1/2)$  and  $v_2 = v_n^{n+1}(x_1, \dots, x_n, -1/2)$ . Note that for every  $t \in (0, 1)$  and  $i \in \{1, \dots, n-1\}$ , we have

$$v_i^{n+1}(x_1, \dots, x_n, t) = v_i^{n+1}(x) = v_i^{n+1}(x_1, \dots, x_n, -t),$$
$$v_n^{n+1}(x_1, \dots, x_n, t) = v_1,$$
$$v_n^{n+1}(x_1, \dots, x_n, -t) = v_2.$$

Then for every  $\epsilon > 0$ ,

$$d(y, \operatorname{span}\{v_1^{n+1}(x), \dots, v_{n-1}^{n+1}(x), v_1\}) < \epsilon,$$
  
$$d(y, \operatorname{span}\{v_1^{n+1}(x), \dots, v_{n-1}^{n+1}(x), v_2\}) < \epsilon.$$

Therefore,

$$y \in \operatorname{span}\{v_1^{n+1}(x), \dots, v_{n-1}^{n+1}(x), v_1\} \cap \operatorname{span}\{v_1^{n+1}(x), \dots, v_{n-1}^{n+1}(x), v_2\}$$
$$= \operatorname{span}\{v_1^{n+1}(x), \dots, v_{n-1}^{n+1}(x)\}.$$

Let  $x \in E_{n-1} \times \{0\}^2$ . Then there is an integer  $k \leq n-1$  such that  $x \in U^k \times \{0\}^{n+1-k}$ . Since dim  $T'_{n+1}(x) \leq \liminf_{z \to x} \dim T_{n+1}(z)$ , it suffices to prove that  $v_i^{n+1}(x) \in T'_{n+1}(x)$  for every  $i \in \{1, \ldots, n\}$ . Observe that

$$\lim_{U^{n+1} \ni z \to x} v_i^{n+1}(z) = v_i^{n+1}(x)$$

for every  $i \in \{1, \ldots, n\} \setminus \{k\}$ . For each  $z = (z_1, \ldots, z_{n+1}) \in U^{n+1}$ , let  $C_z :=$ 

 $z_k z_{k+1} / |z_{k+1}|$ . Therefore,

$$\lim_{U^{n+1}\ni z\to x} (v_k^{n+1}(z) - C_z v_{k+1}^{n+1}(z)) = v_k^{n+1}(x).$$

Hence,  $T'_{n+1}(x) = \mathbb{R}^n \times \{0\}.$ 

Note that, for each  $n \in \mathbb{N}$ ,  $T_n$  is definable in the real field  $(\mathbb{R}; <, +, \cdot)$ . Hence, the stabilization method in Lemma 3.4 is sharp. Moreover, as far as we are concerned,  $T_3$  is the first example of a set-valued map which is not stable after applying the Glaeser refinement twice.

# CHAPTER IV APPLICATIONS

Unless indicated otherwise, let  $\mathfrak{R}$  be an o-minimal expansion of a real closed field R. Let  $E \subseteq \mathbb{R}^n$  and  $T : E \rightrightarrows \mathbb{R}^m$  be a set-valued map. In this chapter, we study applications of Theorem 2.1 in various problems.

### 4.1 Existence of selections and definable selections

In this section, we study the correspondence between the existence of selections and definable selections in  $\Re$ . Obviously, the existence of definable continuous selections implies the existence of continuous selections. Hence, this question arises:

If T has a continuous selection, is there a continuous selection of T definable in  $(R; <, +, \cdot, T)$ ?

Roughly speaking, if T has a continuous selection, is there a continuous selection of T that can be defined by  $only + \cdot$  and T?

However, the answer is "no".

**Example 4.1.** Let R be the set of real algebraic numbers and  $\mathfrak{M} := (R; <, +, \cdot)$ . Let  $T: R \rightrightarrows R$  be defined by

$$T(x) := \begin{cases} \{0\}, & \text{if } x < 0; \\ \{0, 1\}, & \text{if } 0 \le x \le 4; \\ \{1\}, & \text{if } x > 4. \end{cases}$$

The structure  $\mathfrak{M}$  is o-minimal and T is definable in  $\mathfrak{M}$ . Observe that  $f: \mathbb{R} \to \mathbb{R}$ 

defined by

$$f(x) := \begin{cases} 0, & \text{if } x < \pi; \\ 1, & \text{if } x > \pi, \end{cases}$$

is a continuous selection of T. However, by o-minimality, T has no continuous selection definable in  $\mathfrak{M}$ .

The problem is that definably connected sets need not be connected. Therefore, it is natural to ask this question in structures that definably connected sets are connected. Note that definably connected sets in o-minimal expansion of the real field are connected. Moreover, let us consider the following examples:

- If (ℝ; <, +, ·, T) defines Z, then every Borel set is definable in (ℝ; <, +, ·, T) (see [18, Exercise 37.6]). Therefore, if E is Borel and (ℝ; <, +, ·, T) defines Z, then every continuous selection of T is definable.</li>
- 2. Let M be the double helix defined in [12] and define  $T : \mathbb{R} \Rightarrow \mathbb{R}^2$  by  $T(z) = \{(x, y) \in \mathbb{R}^2 : (x, y, z) \in M\}$ . Then  $(\mathbb{R}; <, +, \cdot, T)$  is not o-minimal and a continuous selection of T must be interdefinable with a connected component of M, which is not definable in  $(\mathbb{R}; <, +, \cdot, T)$ .

These give rise to the following question:

If T has a continuous selection and  $(\mathbb{R}; <, +, \cdot, T)$  is o-minimal, is there a continuous selection of T definable in  $(\mathbb{R}; <, +, \cdot, T)$ ?

Throughout this section, let  $\mathfrak{R}$  be an o-minimal expansion of the real field,  $E \subseteq \mathbb{R}^n$  and  $T \colon E \rightrightarrows \mathbb{R}^m$  be definable in  $\mathfrak{R}$ . Here, we will give a partial answer to the above question:

**Theorem 4.2.** Suppose that n = 1 or m = 1. Then T has a continuous selection if and only if T has a definable continuous selection.

Now, we work towards the proof of Theorem 4.2. First, we prove this useful theorem:

**Theorem 4.3.** Suppose for each  $x \in E$ , each connected component of T(x) is convex, and T has a continuous selection. Then T has a definable continuous selection.

Proof. Let  $T: E \rightrightarrows \mathbb{R}^n$  be definable such that for each  $x \in E$ , connected components of T(x) are convex, and  $f: E \to \mathbb{R}^n$  be a continuous selection of T. By the Trivialization Theorem and the Cell Decomposition Theorem, there exists a cell decomposition C of E,  $(A_C)_{C \in C}$  and  $(h_C)_{C \in C}$  such that for each  $C \in C$ ,  $A_C \subseteq \mathbb{R}^n$ is definable and  $h_C: T \upharpoonright C \to C \times A_C$  is a definable homeomorphism, and for each  $x \in C$ ,  $h_C(\{x\} \times T(x)\} = \{x\} \times A_C$ . Let  $C \in C$ . Note that  $f \upharpoonright C$  is connected. Therefore,  $h_C(f \upharpoonright C)$  is contained in a unique connected component of  $C \times A_C$ . Observe that every connected component of  $C \times A_C$  is the set  $C \times X$  where X is a connected component of  $A_C$ . For each  $C \in C$ , let  $X_C$  be a connected component of  $A_C$  such that  $h_C(f \upharpoonright C) \subseteq C \times X_C$ .

Let  $T_0 = \bigcup \{h_C^{-1}(C \times X_C) : C \in \mathcal{C}\}$ . Then  $T_0 \subseteq T$  is a definable set-valued map  $E \rightrightarrows \mathbb{R}^n$  such that  $T_0(x)$  is convex for every  $x \in E$ .

Note that f is a continuous selection of  $T_0$ . Hence,  $T_0^{(*)}(x)$  is nonempty for every  $x \in E$ . Moreover, by Lemma 3.3, each  $T_0^{(*)}(x)$  is convex. Since  $T_0^{(*)}$  is stable,  $T_0^{(*)}$  is lower semi-continuous. Hence, by Theorem 2.1,  $T_0^{(*)}$  has a definable continuous selection, which is also a selection of  $T_0$ . Therefore, T has a definable continuous selection.

Note that the last part of this proof is also valid in an o-minimal expansion of a real closed field. Therefore, we have:

**Corollary 4.4.** Let  $\mathfrak{R}$  be an o-minimal expansion of a real closed field R and  $E \subseteq R^n$ . Let  $T : E \rightrightarrows R^m$  be definable. Suppose for each  $x \in E$ , T(x) is convex. If T has a continuous selection, then T has a definable continuous selection.

Let  $T: E \rightrightarrows \mathbb{R}$  be definable. Since every connected subset of  $\mathbb{R}$  is convex, T has a continuous selection if and only if T has a definable continuous selection. To finish the proof of Theorem 4.2, it suffices to consider the case n = 1.

In [4], M. Czapla and W. Pawłucki proved the following theorem:

**Theorem 4.5** (M. Czapla and W. Pawłucki [4]). Let  $T : E \rightrightarrows \mathbb{R}^m$  be a definable and lower semi-continuous set-valued map with nonempty connected values and dim E = 1. Then T has a definable continuous selection.

We are now ready to prove a slight modification of the case n = 1.

**Theorem 4.6.** Suppose dim E = 1. If T has a continuous selection, then T has a definable continuous selection.

Proof. Let  $f: E \to \mathbb{R}^m$  be a continuous selection of T. By the same argument as in the Proof of Theorem 4.3, there exists a definable set-valued map  $T_0: E \rightrightarrows \mathbb{R}^m$ such that  $f \subseteq T_0$  and for every  $x \in E$ ,  $T_0(x)$  is connected. By Lemma 2.6, let  $\mathcal{C}$  be a cell decomposition of E such that  $T_0 \upharpoonright C$  is lower semi-continuous for every  $C \in \mathcal{C}$ . Let  $E_0 = \bigcup \{C \in \mathcal{C} : \dim C = 0\}$ . Then  $E_0$  is finite. Define  $T_1: E \rightrightarrows \mathbb{R}^m$ by

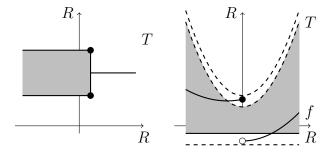
$$T_1(x) := \begin{cases} \{f(x)\}, & \text{if } x \in E_0; \\ T_0(x), & \text{if } x \notin E_0. \end{cases}$$

By Lemma 2.3,  $T_1$  is lower semi-continuous. By Theorem 4.5, this completes the proof.

#### 4.2 Existence of definable $\epsilon$ -approximate selections

In this section, we assume that  $\mathfrak{R}$  is an o-minimal expansion of a real closed field R.

We say that T is almost lower semi-continuous if for every  $x_0 \in E$  and  $\epsilon > 0$  there is  $\delta > 0$  such that  $\bigcap_{x \in B_n(x_0,\delta) \cap E} B_m(T(x),\epsilon) \neq \emptyset$ ; for each  $\epsilon > 0$ , a map  $f : E \to \mathbb{R}^m$  is an  $\epsilon$ -approximate selection of T if  $f(x) \in B_m(T(x),\epsilon)$ , for each  $x \in E$ . In [10], F. Deutsch and P. Kenderov studied the concepts of almost lower semi-continuous and  $\epsilon$ -approximate selections, and showed a relation between these two concepts.



Examples of an almost lower semi-continuous set-valued map (left) and an  $\epsilon$ -approximate selection f of a set-valued map T (right).

**Theorem 4.7** (F. Deutsch and P. Kenderov [10, Theorem 2.4]). Suppose that T(x) is nonempty and convex for each  $x \in E$ . Then T is almost lower semi-continuous iff T admits a continuous  $\epsilon$ -approximate selection for each  $\epsilon > 0$ .

If each T(x) is nonempty and convex, then this theorem provides an alternative definition of almost lower semi-continuity of T. Hence, this question arises:

Let T be definable such that each T(x) is nonempty and convex. Is the almost lower semi-continuity of T equivalent to the existence of definable  $\epsilon$ -approximate selections?

The answer is yes. Next, we prove a definable version of Theorem 4.7 in ominimal context.

**Theorem 4.8.** Suppose that T is definable and T(x) is nonempty and convex for each  $x \in E$ . Then the following are equivalent:

- (a) T is almost lower semi-continuous;
- (b) T admits a continuous  $\epsilon$ -approximate selection for each  $\epsilon > 0$ ;
- (c) T admits a definable continuous  $\epsilon$ -approximate selection for each  $\epsilon > 0$ .

*Proof.* By Theorem 4.7, (a) and (b) are equivalent. To show that (b) and (c) are equivalent, by Corollary 4.4, it suffices to show that if C is a convex subset of  $\mathbb{R}^m$ , then  $B(C, \epsilon)$  is convex. Let  $a, b \in B(C, \epsilon)$  and  $t \in [0, 1]$ . Let c := ta + (1-t)b. Then

there exist  $a', b' \in C$  such that  $||a - a'||, ||b - b'|| < \epsilon$ . Define c' := ta' + (1 - t)b', then

$$||c - c'|| \le t ||a - a'|| + (1 - t)||b - b'|| < \epsilon.$$

Hence,  $c \in B(C, \epsilon)$ .

#### 4.3 Existence of fixed points of definable set-valued maps

In this section, we assume that  $\mathfrak{R}$  is an o-minimal expansion of a real closed field R.

Let  $X \subseteq \mathbb{R}^n$ . We say that a function  $f: X \to X$  has a **fixed point**  $x_0 \in X$  if  $x_0 = f(x_0)$ . Moreover, a set-valued map  $T: X \rightrightarrows X$  has a **fixed point**  $x_0 \in X$  if  $x_0 \in T(x_0)$ . The main result of this section is a lower semi-continuous version of the Definable Kakutani's Fixed Point Theorem:

**Theorem 4.9.** Let  $X \subseteq \mathbb{R}^n$  be closed bounded convex and definable. Let  $T : X \rightrightarrows X$  be a definable lower semi-continuous set-valued map such that T(x) is nonempty and convex for each  $x \in X$ . Then T has a fixed point.

We will prove the above theorem by using the following results:

**Theorem 4.10** (M. J. Edmundo [11, Corollary 3.6]). Let  $X \subseteq \mathbb{R}^n$  be definable closed and bounded and  $f : X \to X$  be definable and continuous. If the Euler characteristic  $E(X) \neq 0$  and there exists a definable continuous function  $h : X \times$  $[0,1] \to X$  such that h(x,0) = f(x) and h(x,1) = x for each  $x \in X$ , then f has a fixed point.

**Lemma 4.11.** Let S be a simplex. Then  $E(\operatorname{cl} S) = 1$ .

*Proof.* Let S be a k-simplex and S be the collection of faces of S. By the definition of the Euler characteristic of simplices, we have

$$E(\operatorname{cl} S) = \sum_{\sigma \in \mathcal{S}} E(\sigma) = \sum_{i=1}^{k+1} (-1)^{i+1} \binom{k+1}{i}.$$

By the Binomial Theorem,  $\sum_{i=0}^{k+1} (-1)^i \binom{k+1}{i} = 0$ . Therefore,

$$E(\operatorname{cl} S) = \sum_{i=1}^{k+1} (-1)^{i+1} \binom{k+1}{i} = 1 + \sum_{i=0}^{k+1} (-1)^{i+1} \binom{k+1}{i} = 1.$$

This completes the proof.

We are ready to prove Theorem 4.9.

Proof of Theorem 4.9. Define  $F: X \times [0,1] \rightrightarrows X$  by

$$F(x,t) := \begin{cases} T(x), & \text{if } t = 0; \\ \{x\}, & \text{if } t = 1; \\ X, & \text{otherwise} \end{cases}$$

Clearly, F is definable. Since X and T(x) are convex for each  $x \in X$ , F(x,t) is convex for each  $x \in X$  and  $t \in [0, 1]$ . Moreover, F is lower semi-continuous because T is lower semi-continuous. By Theorem 2.1, F has a definable continuous selection f. Define  $g: X \to X$  by g(x) := f(x, 0). If g has a fixed point, so is T. Hence, by Theorem 4.10, it suffices to show that E(X) = 1. By the Triangulation Theorem, there exists a complex K in  $\mathbb{R}^n$  such that X is definably homeomorphic to |K|. Since X is closed, bounded, and definably connected, |K| is closed and definably connected. Note that, by the Cell Decomposition Theorem, for all definable sets A and B,  $E(A \cup B) = E(A) + E(B) - E(A \cap B)$ . Hence, we reduce to the case where |K| is the closure of a simplex. By Lemma 4.11, E(|K|) = 1. Since the Euler characteristic is preserved under definable bijection, E(X) = 1.

The convex condition of X in this theorem is necessary. Consider this example, let  $S := \{x \in \mathbb{R}^n : ||x|| = 1\}$  and  $T : S \rightrightarrows S$  be defined by  $T(x) := \{-x\}$ . Then T has no fixed points and T is definable and continuous.

# 4.4 Approximation of upper semi-continuous set-valued maps by using C<sup>p</sup>-maps

Note that upper semi-continuous set-valued maps do not necessarily have continuous selections even their values are closed, bounded, and convex;

**Example 4.12.** Let  $T : \mathbb{R} \rightrightarrows \mathbb{R}$  be a set-valued map defined by

$$T(x) := \begin{cases} \{0\}, & \text{if } x < 0; \\ [0,1], & \text{if } x = 0; \\ \{1\}, & \text{if } x > 0. \end{cases}$$

Then T does not have continuous selections.

However, in [1, Chapter 9], we have this result: let  $\epsilon > 0$  and  $T : E \to R^m$ be an upper semi-continuous set-valued map such that for each  $x \in E$ , T(x) is nonempty and convex. Then there exists a continuous function  $f : E \to R^m$  such that  $f \subseteq B_{n+m}(T, \epsilon)$ .

Hence, this question arises:

Let  $\epsilon > 0$ . If  $T : E \Rightarrow R^m$  is a definable upper semi-continuous set-valued map and T(x) is nonempty convex for each  $x \in E$ , is there a definable continuous function  $f : E \to R^m$  such that  $f \subseteq B_{n+m}(T, \epsilon)$ ?

The answer is yes.

**Theorem 4.13.** Suppose T is upper semi-continuous and definable such that T(x) is nonempty and convex for each  $x \in E$ . Then for each  $\epsilon > 0$ , there is a definable continuous map  $f : E \to R^m$  such that  $f \subseteq B_{n+m}(T, \epsilon)$ .

Proof. Let  $\epsilon > 0$ . We proceed by induction on dim E. The case dim E = 0 is trivial. Suppose the theorem holds for all set-valued maps whose domain has dimension less than dim E. By Lemma 2.6, there is a definable set S open in E such that  $T \upharpoonright S$  is lower semi-continuous and dim  $E \smallsetminus S < \dim E$ . Then there is a definable continuous function  $g_0 : E \smallsetminus S \to R^m$  such that  $g_0 \subseteq B_{n+m}(T \upharpoonright E \backsim S, \epsilon/4)$ . By the Definable Tietze's Extension Theorem, there is a definable continuous function  $g: E \to R^m$  such that  $g \upharpoonright E \smallsetminus S = g_0$ . Next, by Theorem 2.1, there exists a definable continuous selection h of  $T \upharpoonright S$ . Define  $r: E \smallsetminus S \to R$  by

$$r(x) := \sup\{r' \in (0, \frac{\epsilon}{2}] : \forall x' \in B_n(x, r') \cap E, \ T(x') \subseteq B_m(T(x), \frac{\epsilon}{4}) \text{ and} \\ g(x') \in B_m(g(x), \frac{\epsilon}{4})\}.$$

Obviously, r is definable. Since T is upper semi-continuous and g is continuous, r(x) > 0 for every  $x \in E \smallsetminus S$ . Let  $U := \bigcup_{x \in E \smallsetminus S} B_n(x, r(x))$ . Then U is a definable open subset of E containing  $E \smallsetminus S$ . By Lemma 1.22, there exists a definable open subset V of E such that  $E \smallsetminus S \subseteq V \subseteq \operatorname{cl}_E V \subseteq U \subseteq E$ . By Lemma 1.23, there exists a definable continuous function  $t : E \to [0, 1]$  such that  $t^{-1}(0) = \operatorname{cl}_E V$  and  $t^{-1}(1) = E \smallsetminus U$ . Define  $f : E \to R^n$  by

$$f(x) := \begin{cases} (1 - t(x))g(x) + t(x)h(x), & \text{if } x \in S; \\ g(x), & \text{if } x \in E \smallsetminus S. \end{cases}$$

Clearly, f is definable. To show that f is continuous, let  $x_0 \in E$ . Since S is open in E and g(x), h(x), and t(x) are continuous on S, f is continuous on E. Therefore, we may assume  $x_0 \in E \setminus S$ . Since  $t^{-1}(0) = cl_E V$ , f(x) = g(x) for every  $x \in V$ . Since g is continuous on V and  $x_0 \in V$ , f is continuous at  $x_0$ .

Next, we will show that  $f \subseteq B_{n+m}(T,\epsilon)$ . Let  $x_0 \in E$ . If  $x_0 \in E \setminus U$ , then  $f(x_0) = h(x_0) \in T(x_0)$ . Suppose that  $x_0 \in U$ . Then there is  $x \in E \setminus S$  such that  $x_0 \in B_n(x, r(x))$ ,  $T(x_0) \subseteq B_m(T(x), \epsilon/4)$ , and  $g(x_0) \in B_m(g(x), \epsilon/4)$ . Since  $B_m(T(x), \epsilon/2)$  is a convex set containing  $g(x_0)$  and  $h(x_0)$ ,  $B_m(T(x), \epsilon/2)$  also contains  $f(x_0)$ . Hence, there is  $y \in T(x)$  such that  $||y - f(x_0)|| < \epsilon/2$ . Therefore,

$$||(x,y) - (x_0, f(x_0))|| \le ||x - x_0|| + ||y - f(x_0)|| < \epsilon/2 + \epsilon/2 = \epsilon.$$

This completes the proof.

In fact, if E is open, then for each  $\epsilon > 0$  and  $p \in \mathbb{N}$ , there exists a definable  $C^{p}$ -map  $f: E \to \mathbb{R}^{m}$  satisfies  $f \subseteq B_{n+m}(T, \epsilon)$ .

**Corollary 4.14.** Suppose T is upper semi-continuous and definable such that T(x) is nonempty and convex for each  $x \in E$ . If E is open, then for each  $\epsilon > 0$  and  $p \in \mathbb{N}$ , there is a definable  $C^p$ -map  $f : E \to R^m$  such that  $f \subseteq B_{n+m}(T, \epsilon)$ .

To prove this result we recall:

**Theorem 4.15** (A. Thamrongthanyalak [27, Corollary 4.1]). Let E be open and  $f: E \to R^m$  be a definable continuous map. Let  $\epsilon > 0$  and  $p \in \mathbb{N}$ . Then there exists a definable  $C^p$ -map  $g: E \to R^m$  such that  $||g(x) - f(x)|| < \epsilon$  for each  $x \in E$ .

This theorem tells us that we can approximate definable continuous maps by definable  $C^p$ -maps.

Proof of Corollary 4.14. Suppose that E is open. Let  $\epsilon > 0$  and  $p \in \mathbb{N}$ . By Theorem 4.13, we obtain a definable continuous map  $f : E \to R^m$  such that  $f \subseteq B_{n+m}(T, \epsilon/2)$ . By Theorem 4.15, there is a  $C^p$ -map  $g : E \to R^m$  such that  $\|g(x) - f(x)\| < \epsilon/2$  for each  $x \in E$ . Hence,  $g \subseteq B_{n+m}(T, \epsilon)$ .

### CHAPTER V

# DEFINABLE EXTENSION OF CONTINUOUS SET-VALUED MAPS

Throughout this chapter, assume that  $\mathfrak{R}$  is an o-minimal expansion of a real closed field R and let  $E \subseteq R^n$  and  $T: E \rightrightarrows R^m$  be definable. We say a set-valued map  $F: R^n \rightrightarrows R^m$  is an **extension** of T if F(x) = T(x) for each  $x \in E$ . By the Definable Tietze's Extension Theorem, we know that definable continuous maps on closed sets have definable continuous extensions. Hence, we are interested in this question:

Does a definable continuous set-valued map on a closed domain have a definable continuous extension?

Recall that a set-valued map is continuous if it is lower semi-continuous and upper semi-continuous. In this chapter, we partially answer this question. First, we prove these lemmas.

**Lemma 5.1.** Let  $Y \subseteq \mathbb{R}^m$ . If  $f : E \to Y$  is definable and continuous and  $T : Y \rightrightarrows \mathbb{R}^k$  is definable and continuous, then  $T \circ f : E \rightrightarrows \mathbb{R}^k$  defined by  $T \circ f(x) := T(f(x))$  is definable and continuous.

Proof. Obviously,  $T \circ f$  is definable. To show that  $T \circ f$  is lower semi-continuous, let  $x_0 \in E$ ,  $z_0 \in T \circ f(x_0)$  and  $\epsilon > 0$ . Since T is lower semi-continuous, there is  $\delta_1 > 0$  such that for each  $y \in B_m(f(x_0), \delta_1) \cap Y$ ,  $T(y) \cap B_k(z_0, \epsilon) \neq \emptyset$ . Since f is continuous, there is  $\delta > 0$  such that for each  $x \in B_n(x_0, \delta) \cap E$ ,  $f(x) \in$  $B_m(f(x_0), \delta_1)$ . Hence, for each  $x \in B_n(x_0, \delta) \cap E$ ,  $T \circ f(x) \cap B_k(z_0, \epsilon) \neq \emptyset$ .

To prove that  $T \circ f$  is upper semi-continuous, let  $x_0 \in E$  and  $\epsilon > 0$ . Since T is upper semi-continuous, there is  $\delta_1 > 0$  such that  $T(y) \subseteq B_k(T \circ f(x_0), \epsilon)$ for all  $y \in B_m(f(x_0), \delta_1) \cap Y$ . Since f is continuous, there is  $\delta > 0$  such that for each  $x \in B_n(x_0, \delta) \cap E$ ,  $f(x) \in B_m(f(x_0), \delta_1)$ . Hence, for each  $x \in B_n(x_0, \delta)$ ,  $T \circ f(x) \subseteq B_k(T \circ f(x_0), \epsilon)$ .

Next, we show that the Cartesian product of two continuous set-valued maps is continuous:

**Lemma 5.2.** Let  $T : E \rightrightarrows R^m$  and  $T' : E' \rightrightarrows R^k$  be definable continuous set-valued maps where  $E, E' \subseteq R^n$ . Define  $T \times T' : E \times E' \rightrightarrows R^{m+k}$  by  $T \times T'(x, x') :=$  $T(x) \times T'(x')$ . Then  $T \times T'$  is definable and continuous.

Proof. Obviously,  $T \times T'$  is definable. We will show that  $T \times T'$  is lower semicontinuous. Let  $(x_0, x'_0) \in E \times E'$ ,  $(y_0, y'_0) \in T \times T'(x_0, x'_0)$  and V be an open neighborhood of  $(y_0, y'_0)$ . Then there is  $\epsilon > 0$  such that  $B_m(y_0, \epsilon) \times B_k(y'_0, \epsilon) \subseteq V$ . Since T and T' are lower semi-continuous, there exists  $\delta > 0$  such that for each  $x \in B_n(x_0, \delta)$  and  $x' \in B_n(x'_0, \delta)$ ,  $T(x) \cap B_m(y_0, \epsilon) \neq \emptyset$  and  $T'(x') \cap B_k(y'_0, \epsilon) \neq \emptyset$ . Hence, for each  $(x, x') \in B_{2n}((x_0, x'_0), \delta)$ ,  $T \times T'(x, x') \cap V \neq \emptyset$ .

To prove that  $T \times T'$  is upper semi-continuous, let  $(x_0, x'_0) \in E \times E'$  and  $\epsilon > 0$ . Then there is  $\epsilon' > 0$  such that  $B_m(T \times T'(x_0), \epsilon') \times B_k(T \times T'(x'_0), \epsilon') \subseteq$   $B_{m+k}(T \times T'(x_0, x'_0), \epsilon)$ . Since T and T' are upper semi-continuous, there exists  $\delta > 0$  such that for each  $x \in B_n(x_0, \delta)$  and  $x' \in B_n(x'_0, \delta)$ ,  $T(x) \subseteq B_m(T(x_0), \epsilon')$ and  $T'(x') \subseteq B_k(T(x'_0), \epsilon')$ . Therefore, for each  $(x, x') \in B_{2n}((x_0, x'_0), \delta)$ ,

$$T \times T'(x, x') \subseteq B_m(T \times T'(x_0), \epsilon') \times B_k(T \times T'(x'_0), \epsilon') \subseteq B_{m+k}(T \times T'(x_0, x'_0), \epsilon).$$

This completes the proof.

Next is a version of the Pasting Lemma for definable set-valued maps.

**Lemma 5.3.** Let E, E' be closed subsets of  $\mathbb{R}^n$ . Let  $T : E \rightrightarrows \mathbb{R}^m$  and  $T' : E' \rightrightarrows \mathbb{R}^m$ be definable continuous set-valued maps such that T = T' on  $E \cap E'$ . Define  $F : E \cup E' \rightrightarrows \mathbb{R}^m$  by

$$F(x) := \begin{cases} T(x), & \text{if } x \in E; \\ T'(x), & \text{if } x \in E'. \end{cases}$$

#### Then F is definable and continuous.

Proof. Obviously, F is definable. Next, we will prove that F is continuous. Let  $x_0 \in E \cup E'$ . Since  $E \cap E'$  is closed,  $(E \cup E') \smallsetminus (E \cap E')$  is open in  $E \cup E'$ . Since F = T on  $E \smallsetminus E'$  and F = T' on  $E' \smallsetminus E$ , F is continuous on  $(E \cup E') \smallsetminus (E \cap E')$ . We may assume  $x_0 \in E \cap E'$ . Let  $y_0 \in F(x_0)$  and  $\epsilon > 0$ . Since T and T' are continuous, there is  $\delta > 0$  such that for each  $x \in B_n(x_0, \delta) \cap (E \cup E')$ ,  $F(x) \cap B_m(y_0, \epsilon) \neq \emptyset$  and  $F(x) \subseteq B_m(F(x_0), \epsilon)$ . Therefore, F is continuous.

Now, we ready to prove the main theorem of this chapter:

**Theorem 5.4.** Let E be a closed subset of  $\mathbb{R}^n$ . If  $T : E \rightrightarrows \mathbb{R}^m$  is a definable continuous set-valued map such that for each  $x \in \operatorname{bd} E$ , T(x) is bounded, then T has a definable continuous extension.

*Proof.* Let  $T : E \Rightarrow \mathbb{R}^m$  be a definable continuous set-valued map where E is a closed subset of  $\mathbb{R}^n$ . By Corollary 1.24, there is a definable open set U containing bd E and a definable retraction  $r : \operatorname{cl} U \to \operatorname{bd} E$ . Define  $r' : \operatorname{cl} U \cup E \to E$  by

$$r'(x) := \begin{cases} x, & \text{if } x \in E; \\ r(x), & \text{otherwise.} \end{cases}$$

Clearly, r' is a definable continuous map such that for each  $x \in \operatorname{cl} U \setminus \operatorname{int} E$ ,  $r'(x) \in \operatorname{bd} E$ . Let  $V = U \cup E$ . Since  $U \cup E = U \cup \operatorname{int} E$ , V is an open neighborhood of E. By Lemma 1.22, there is a definable continuous function  $t : \mathbb{R}^n \to [0, 1]$  such that  $t^{-1}(1) = E$  and  $t^{-1}(0) = \mathbb{R}^n \setminus V$ . Note that every function can be considered as a set-valued map. Define  $\phi : \mathbb{R}^m \times [0, 1] \to \mathbb{R}^m$  by  $\phi(x_1, \ldots, x_m, s) := (sx_1, \ldots, sx_m)$  and define  $F : \mathbb{R}^n \rightrightarrows \mathbb{R}^m$  by

$$F(x) := \begin{cases} \phi(T \circ r' \times t(x)), & \text{if } x \in \operatorname{cl} V_{2} \\ \{0\}, & \text{otherwise.} \end{cases}$$

We claim that F is a definable continuous extension of T. Obviously, F is definable. Next, we will show that F is continuous. Clearly,  $F \upharpoonright R^n \smallsetminus V$  is continuous. By Lemma 5.3, it suffices to show that F is continuous on  $\operatorname{cl} V$ . Since r' and t are continuous and T is a continuous set-valued map, by Lemma 5.1 and 5.2,  $T \circ r' \times t$  is continuous on  $\operatorname{cl} V$ . To show that F is lower semi-continuous on  $\operatorname{cl} V$ , let  $x_0 \in \operatorname{cl} V$ ,  $z_0 \in F(x_0)$  and  $\epsilon > 0$ . Then there is  $y_0 \in T \circ r'(x_0)$  such that  $\phi(y_0, t(x_0)) = z_0$ . Since  $\phi$  is continuous, there exists  $\epsilon_1 > 0$  such that  $\phi(B_{m+1}((y_0, t(x_0)), \epsilon_1)) \subseteq$  $B_m(z_0, \epsilon)$ . Since  $T \circ r' \times t$  is lower semi-continuous on  $\operatorname{cl} V$ , there is  $\delta > 0$  such that for each  $x \in B_n(x_0, \delta) \cap \operatorname{cl} V$ ,

$$F(x) \cap B_m(z_0, \epsilon) \supseteq \phi(T \circ r' \times t(x)) \cap B_m(z_0, \epsilon)$$
$$\supseteq \phi(T \circ r' \times t(x)) \cap B_{m+1}((y_0, t(x_0)), \epsilon_1))$$
$$\neq \emptyset.$$

Hence, F is lower semi-continuous on cl V. To show that F is upper semi-continuous on cl V, let  $\epsilon > 0$  and  $x_0 \in \operatorname{cl} V$ . Since  $F(x) = T \circ r'(x)$  for each  $x \in \operatorname{int} E$ , Fis upper semi-continuous on int E. We may assume  $x_0 \in \operatorname{cl} V \setminus \operatorname{int} E$ . Since  $r'(x_0) \in E$ ,  $T \circ r'(x_0)$  is bounded. Then there is M > 1 such that  $T \circ r'(x_0) \subseteq$  $B_m(0, M)$ . We claim that  $\phi(B_{m+1}(T \circ r' \times t(x_0), \epsilon/2M)) \subseteq B_m(F(x_0), \epsilon)$ . Let  $(y, s) \in B_{m+1}(T \circ r' \times t(x_0), \epsilon/2M)$ . Then there is  $y' \in T \circ r'(x_0)$  such that  $||y - y'|| < \epsilon/2M$ . Since  $T \circ r'(x_0) \subseteq B_m(0, M)$ , we have

$$\begin{aligned} \|\phi(y,s) - \phi(y',t(x_0))\| &\leq \|\phi(y,s) - \phi(y',s)\| + \|\phi(y',s) - \phi(y',t(x_0))\| \\ &\leq \|s \cdot (y-y')\| + \|(s-t(x_0)) \cdot y'\| \\ &\leq \|y - y'\| + \frac{\epsilon}{2M} \cdot \|y'\| \\ &< \frac{\epsilon}{2} + \frac{\epsilon}{2} = \epsilon. \end{aligned}$$

Since  $T \circ r' \times t$  is upper semi-continuous on  $\operatorname{cl} V$ , there is  $\delta > 0$  such that for every  $x \in B_n(x_0, \delta) \cap \operatorname{cl} V$ ,  $T \circ r' \times t(x) \subseteq B_{m+1}(T \circ r' \times t(x_0), \epsilon/2M)$ . Hence,

$$F(x) \subseteq \phi(B_{m+1}(T \circ r' \times t(x_0), \epsilon/2M)) \subseteq B_m(F(x_0), \epsilon).$$

Therefore, F is upper semi continuous on cl V. To show that F is an extension of T, let  $x \in E$ . Then  $F(x) = \phi(T \circ r'(x) \times \{t(x)\}) = \phi(T(x) \times \{1\}) = T(x)$ . Therefore, F is a definable continuous extension of T as desired.  $\Box$ 

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